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ON A WEIGHTED BOUNDARY VALUE PROBLEM FOR A SYSTEM OF SINGULAR FUNCTIONAL DIFFERENTIAL EQUATIONS

(Reported on February 7, 2000)

Let $-\infty < a < b < +\infty$, $0 \leq \alpha, \beta \leq 1$, $n \geq 1$, and f be a continuous operator acting from the space of continuously differentiable vector functions $u :]a, b[\rightarrow R^n$ satisfying the condition

$$\sup \left\{ (t-a)^{\alpha-1} (b-t)^{\beta-1} \|u(t)\| + (t-a)^\alpha (b-t)^\beta \|u'(t)\| : a < t < b \right\} < +\infty$$

to the space of n -dimensional, summable with the weight $(t-a)^\alpha (b-t)^\beta$, vector functions. Consider the system of functional differential equations

$$u''(t) = f(u)(t) \tag{1}$$

with the boundary conditions

$$\lim_{t \rightarrow a} u(t) = 0, \quad \lim_{t \rightarrow b} u(t) = 0, \tag{2}$$

$$\sup \left\{ (t-a)^{\alpha-1} (b-t)^{\beta-1} \|u(t)\| + (t-a)^\alpha (b-t)^\beta \|u'(t)\| : a < t < b \right\} < +\infty.$$

In case $n = 1$ or $f(u)(t) = f_0(t, u(t), u'(t))$, where $f_0 :]a, b[\times R^n \rightarrow R^n$ is a vector function satisfying the local Carathéodory conditions, boundary value problems of the type (1), (2) are investigated in full detail (see [1–9, 11–20] and the references therein). Below we give optimal sufficient conditions for the solvability and the unique solvability of the problem (1), (2) which generalize the results of [19].

Throughout the paper the following notation will be used.

$R =]-\infty, +\infty[$, $R_+ = [0, +\infty[$.

R^n is the space of n -dimensional vector columns $x = (x_i)_{i=1}^n$ with the components $x_i \in R$ ($i = 1, \dots, n$) and the norm

$$\|x\| = \sum_{i=1}^n |x_i|.$$

If $x = (x_i)_{i=1}^n$, then $|x| = (|x_i|)_{i=1}^n$.

$R_+^n = \{(x_i)_{i=1}^n \in R^n : x_i \in R_+ (i = 1, \dots, n)\}$.

The inequality between vectors is understood componentwise, i.e, if $x = (x_i)_{i=1}^n$ and $y = (y_i)_{i=1}^n \in R^n$, then

$$x \leq y \iff x_i \leq y_i \quad (i = 1, \dots, n).$$

2000 *Mathematics Subject Classification.* 34K10.

Key words and phrases. The system of singular functional differential equations, weighted boundary value problem, solvability, unique solvability.

$R^{n \times n}$ is the space of $n \times n$ -matrices $X = (x_{ik})_{i,k=1}^n$ with the components $x_{ik} \in R$ ($i, k = 1, \dots, n$) and the norm

$$\|X\| = \sum_{i,k=1}^n |x_{ik}|.$$

$R_+^{n \times n} = \{X = (x_{ik})_{i,k=1}^n : x_{ik} \in R_+ \text{ (} i, k = 1, \dots, n \text{)}\}$.

$r(X)$ is the spectral radius of a matrix $X \in R^{n \times n}$.

$C_{\alpha,\beta}^1([a, b[; R^n)$ is the space of continuously differentiable functions $u :]a, b[\rightarrow R^n$ such that the norm

$$\|u\|_{C_{\alpha,\beta}^1} = \sup \left\{ (t-a)^{\alpha-1}(b-t)^{\beta-1} \|u(t)\| + (t-a)^\alpha (b-t)^\beta \|u'(t)\| : a < t < b \right\}$$

is finite.

If $u = (u_i)_{i=1}^n \in C_{\alpha,\beta}^1([a, b[; R^n)$, then

$$\nu_{0,\alpha,\beta}(u_i) = \sup \left\{ (t-a)^{\alpha-1}(b-t)^{\beta-1} |u_i(t)| : a < t < b \right\},$$

$$\nu_{1,\alpha,\beta}(u_i) = \sup \left\{ \frac{(t-a)^\alpha (b-t)^\beta}{b-a} |u_i'(t)| : a < t < b \right\},$$

$$\nu_{\alpha,\beta}(u_i) = \max \left\{ \nu_{0,\alpha,\beta}(u_i), \nu_{1,\alpha,\beta}(u_i) \right\}, \quad \nu_{\alpha,\beta}(u) = \left(\nu_{\alpha,\beta}(u_i) \right)_{i=1}^n.$$

$L_{\alpha,\beta}([a, b[; R^n)$ is the space of vector functions $v :]a, b[\rightarrow R^n$ with summable with the weight $(t-a)^\alpha (b-t)^\beta$ components and the norm

$$\|v\|_{L_{\alpha,\beta}} = \int_a^b (t-a)^\alpha (b-t)^\beta \|v(t)\| dt.$$

$L_{\alpha,\beta}([a, b[; R_+^{n \times n})$ is the set of matrix functions $H :]a, b[\rightarrow R_+^{n \times n}$ with summable with the weight $(t-a)^\alpha (b-t)^\beta$ nonnegative components.

$M_{\alpha,\beta}([a, b[\times R_+; R_+^n)$ is the set of vector functions $h :]a, b[\times R_+ \rightarrow R_+^n$ summable in the first argument with the weight $(t-a)^\alpha (b-t)^\beta$ and nondecreasing in the second argument.

In what follows it will be assumed that the operator $f : C_{\alpha,\beta}^1([a, b[; R^n) \rightarrow L_{\alpha,\beta}([a, b[; R^n)$ is continuous and

$$\sup \left\{ \|f(u)(\cdot)\| : \|u\|_{C_{\alpha,\beta}^1} \leq \rho \right\} \in L_{\alpha,\beta}([a, b[; R) \text{ for } 0 < \rho < +\infty.$$

A vector function $u :]a, b[\rightarrow R^n$ is called a solution of the problem (1), (2) if:

- (i) u is continuously differentiable and u' is locally absolutely continuous in $]a, b[$;
- (ii) u satisfies the boundary conditions (2);
- (iii) u satisfies the system (1) almost everywhere on $]a, b[$.

Analogously to Theorem 1 of [10] it can be proved the following

Theorem 1. *Let there exist a positive number ρ_0 such that for any $\lambda \in]0, 1[$ an arbitrary solution of the differential system*

$$\frac{du(t)}{dt} = \lambda f(u)(t)$$

satisfying the boundary conditions (2) admits the estimation

$$\|u\|_{C_{\alpha,\beta}^1} \leq \rho_0.$$

Then the problem (1), (2) is solvable.

Corollary 1. *Let there exist $H \in L_{\alpha,\beta}(]a, b[; R_+^{n \times n})$ and $h \in M_{\alpha,\beta}(]a, b[\times R_+; R_+^n)$ such that*

$$\left| f(u)(t) \right| \leq H(t)\nu_{\alpha,\beta}(u) + h(t; \|u\|_{C_{\alpha,\beta}^1}) \quad \text{for } t \in]a, b[, \quad u \in C_{\alpha,\beta}^1(]a, b[; R^n). \quad (3)$$

Moreover, let

$$\lim_{\rho \rightarrow +\infty} \left(\frac{1}{\rho} \int_a^b \|h(t, \rho)\| dt \right) = 0 \quad (4)$$

and the system of differential inequalities

$$|u''(t)| \leq H(t)\nu_{\alpha,\beta}(u) \quad (5)$$

under the boundary conditions (2) have only the trivial solution. Then the problem (1), (2) is solvable.

The problem (5), (2) has only the trivial solution if

$$r \left(\int_a^b (t-a)^\alpha (b-t)^\alpha H(t) dt \right) < b-a, \quad (6)$$

or

$$H(t) \leq (t-a)^{-\alpha} (b-t)^{-\beta} H_0, \quad H_0 \in R_+^{n \times n}$$

and

$$r(H_0) < \min\{2-\alpha, 2-\beta\}. \quad (7)$$

Therefore from Corollary 1 it follows

Corollary 2. *Let there exist $H \in L_{\alpha,\beta}(]a, b[; R_+^{n \times n})$ and $h \in M_{\alpha,\beta}(]a, b[\times R_+; R_+^n)$ such that the conditions (3), (4) and (6) are fulfilled. Then the problem (1), (2) is solvable.*

Corollary 3. *Let there exist $H_0 \in R_+^{n \times n}$ and $h \in M_{\alpha,\beta}(]a, b[\times R_+; R_+^n)$ such that*

$$\left| f(u)(t) \right| \leq (t-a)^{-\alpha} (b-t)^{-\beta} H_0 \nu_{\alpha,\beta}(u) + h(t; \|u\|_{C_{\alpha,\beta}^1})$$

$$\text{for } t \in]a, b[, \quad u \in C_{\alpha,\beta}^1(]a, b[; R^n)$$

and the conditions (4) and (7) are fulfilled. Then the problem (1), (2) is solvable.

Theorem 2. *Let there exist $H \in L_{\alpha,\beta}(]a, b[; R_+^{n \times n})$ such that*

$$\left| f(u)(t) - f(v)(t) \right| \leq H(t)\nu_{\alpha,\beta}(u-v) \quad \text{for } t \in]a, b[, \quad u, v \in C_{\alpha,\beta}^1(]a, b[; R^n) \quad (8)$$

and the problem (5), (2) has only the trivial solution. Then the problem (1), (2) has one and only one solution.

Corollary 4. *Let there exist $H \in L_{\alpha,\beta}(]a, b[; R_+^{n \times n})$ such that the conditions (6) and (8) are fulfilled. Then the problem (1), (2) has one and only one solution.*

Corollary 5. *Let there exist $H_0 \in R_+^{n \times n}$ such that*

$$\left| f(u)(t) - f(v)(t) \right| \leq (t-a)^{-\alpha} (b-t)^{-\beta} H_0 \nu_{\alpha,\beta}(u-v)$$

$$\text{for } t \in]a, b[, \quad u, v \in C_{\alpha,\beta}^1(]a, b[; R^n).$$

Then the problem (1), (2) has one and only one solution.

A particular case of (1) is the differential system with deviating arguments

$$u''(t) = f_0(t, u(\tau_1(t)), u'(\tau_2(t))). \quad (9)$$

This system will be considered under the following assumptions:

- (i) f_0 maps $I \times R^{2n}$ into R^n , where $I \subset [a, b]$ and $\text{mes} I = b - a$;
- (ii) $f_0(t, \cdot, \cdot) : R^{2n} \rightarrow R^n$ is continuous for every $t \in I$, and $f(\cdot, x, y) : I \rightarrow R^n$ is measurable for every x and $y \in R^n$;
- (iii) $\tau_i : I \rightarrow]a, b[$ ($i = 1, 2$) are measurable functions.

The propositions below on the solvability and the unique solvability of the problem (9), (2) follow from Corollaries 2–5.

Corollary 6. *Let there exist $H_i \in L_{\alpha, \beta}(]a, b[; R_+^{n \times n})$ ($i = 1, 2$) and $h \in M_{\alpha, \beta}(]a, b[\times R_+; R_+^n)$ such that*

$$\begin{aligned} & \left| f_0(t, (\tau_1(t) - a)^{1-\alpha} (b - \tau_1(t))^{1-\beta} x, (\tau_2(t) - a)^{-\alpha} (b - \tau_2(t))^{-\alpha} y) \right| \leq \\ & \leq H_1(t)|x| + |H_2(t)||y| + \\ & + h(t, (\tau_1(t) - a)^{1-\alpha} (b - \tau_1(t))^{1-\alpha} |x| + (\tau_2(t) - a)^{-\alpha} (b - \tau_2(t))^{-\beta} |y|) \\ & \text{for } t \in I, \quad x, y \in R^n \end{aligned}$$

and the condition (4) hold. Moreover, let either

$$r \left(\int_a^b (t - a)^\alpha (b - t)^\beta [H_1(t) + (b - a)H_2(t)] dt \right) < b - a \quad (10)$$

or

$$H_1(t) + (b - a)H_2(t) \leq (t - a)^{-\alpha} (b - t)^{-\alpha} H_0, \quad r(H_0) < 2. \quad (11)$$

Then the problem (9), (2) is solvable.

Corollary 7. *Let there exist $H_i \in L_{\alpha, \beta}(]a, b[; R_+^{n \times n})$ ($i = 1, 2$) such that*

$$\begin{aligned} & \left| f_0(t, (\tau_1(t) - a)^{1-\alpha} (b - \tau_1(t))^{1-\beta} x, (\tau_2(t) - a)^{-\alpha} (b - \tau_2(t))^{-\beta} y) - \right. \\ & \left. - f_0(t, (\tau_1(t) - a)^{1-\alpha} (b - \tau_1(t))^{1-\beta} \bar{x}, (\tau_2(t) - a)^{-\alpha} (b - \tau_2(t))^{-\beta} \bar{y}) \right| \leq \\ & \leq H_1(t)|x - \bar{x}| + H_2(t)|y - \bar{y}| \quad \text{for } t \in]a, b[, \quad x, \bar{x}, y, \bar{y} \in R^n. \end{aligned}$$

Moreover, let either the condition (10) or the condition (11) hold. Then the problem (9), (2) has one and only one solution.

As an example, consider the differential system

$$\begin{aligned} u''(t) = & (\tau_1(t) - a)^{\alpha-1} (b - \tau_1(t))^{\beta-1} F_1(t)|u(\tau_1(t))| + \\ & + (\tau_2(t) - a)^\alpha (b - \tau_2(t))^\beta F_2(t)|u'(\tau_2(t))| + q(t), \end{aligned} \quad (12)$$

where $F_i : I \rightarrow R^{n \times n}$ ($i = 1, 2$) are matrix functions with measurable bounded components, $\tau_i : I \rightarrow]a, b[$ ($i = 1, 2$) are measurable functions, and $q \in L_{\alpha, \beta}(]a, b[; R^n)$.

From Corollary 7 it follows

Corollary 8. *Let there exist $H_0 \in R_+^{n \times n}$ satisfying the inequality (7) such that*

$$|F_1(t)| + (b - a)|F_2(t)| \leq H_0 \quad \text{for } t \in I.$$

Then the problem (12), (2) has one and only one solution.

Suppose now that

$$\alpha = \beta = 0, \quad F_1(t) \equiv H_0, \quad F_2(t) = \Theta, \quad q(t) = \ell,$$

where Θ is the zero matrix, $H_0 \in R_+^{n \times n}$, and $\ell \in R^n$ is a vector with positive components. Let us show that if

$$r(H_0) \geq 2,$$

then the problem (12), (2) has no solution. Indeed, let u be an arbitrary solution of that problem. Then

$$u''(t) \geq \ell.$$

Thus

$$u(t) \leq -\frac{(t-a)(b-t)}{2} \ell \quad \text{for } a < t < b.$$

Taking into account this inequality, we obtain

$$u''(t) \geq \frac{1}{2} H_0 + \ell$$

and

$$u(t) \leq -\left(\frac{1}{2} H_0 \ell + \ell\right) \ell(t-a)(b-t) \quad \text{for } a < t < b.$$

If we continue this process, then we will get

$$-u(t) \geq \sum_{k=0}^{+\infty} \left(\frac{1}{2} H_0\right)^k \ell(t-a)(b-t) \quad \text{for } a < t < b,$$

which is impossible since $r(\frac{1}{2} H_0) \geq 1$.

The above example shows that the condition (7) in Corollaries 3 and 5–8 cannot be replaced by the condition

$$r(H_0) \leq \min\{2 - \alpha, 2 - \beta\}.$$

ACKNOWLEDGEMENT

This work was supported by Grant No. 201/99/0295 the Grant Agency of the Czech Republic.

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