

# ON THE CONVERGENCE OF A NEWTON-LIKE METHOD IN $\mathbb{R}^n$ AND THE USE OF BERINDE'S EXIT CRITERION

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Berinde has shown that Newton's method for a scalar equation  $f(x) = 0$  converges under some conditions involving only  $f$  and  $f'$  and not  $f''$  when a generalized stopping inequality is valid. Later Sen et al. have extended Berinde's theorem to the case where the condition that  $f'(x) \neq 0$  need not necessarily be true. In this paper we have extended Berinde's theorem to the class of  $n$ -dimensional equations,  $F(x) = 0$ , where  $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $\mathbb{R}^n$  denotes the  $n$ -dimensional Euclidean space. We have also assumed that  $F'(x)$  has an inverse not necessarily at every point in the domain of definition of  $F$ .

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## 1. Introduction

Let  $F$  be a nonlinear continuous operator mapping  $D_0 \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ .  $D_0$  is an open convex subset of  $\mathbb{R}^n$ , the  $n$ -dimensional Euclidean space. We introduce componentwise partial ordering in  $\mathbb{R}^n$ .

Componentwise partial ordering in  $\mathbb{R}^n$  is defined as follows. For  $x, y \in \mathbb{R}^n$ ,  $x \leq y$  if and only if  $x_i \leq y_i$ ,  $i = 1, 2, \dots, n$ . Let  $\langle a, b \rangle$  denote the order interval  $\{x \in \mathbb{R}^n \mid a \leq x \leq b\}$ .

We seek the solution of

$$F(x) = 0 \quad \text{in } \langle a, b \rangle \subset D_0. \quad (1.1)$$

In case the finite derivative  $F'(x)$  has an inverse at the iteration points, Newton's method is given by the iteration

$$x_{m+1} = x_m - [F'(x_m)]^{-1}F(x_m), \quad x_0 \in \langle a, b \rangle, \quad m \geq 0. \quad (1.2)$$

The importance of Newton's method lies in the fact that it offers a quadratic convergence. Nevertheless this quadratic convergence is achieved after making certain assumptions about  $F$ ,  $F'$ ,  $F''$  (Ortega and Rheinboldt [6]). In case  $F(x) = 0$  is a scalar equation, Berinde (Berinde [1–4]) without making any assumption about the existence of  $F''(x)$

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has achieved linear convergence under the condition that  $F'(x) \neq 0$  in the interval under consideration. In the case of a scalar equation we have not assumed the conditions that  $F'(x) \neq 0$  (Sen et al. [9]). It has been shown that the sequence  $\{x_m\}$  given by

$$x_{m+1} = x_m - \frac{2F(x_m)}{F'(x_m) + M'_m}, \quad x_0 \text{ prechosen, } m = 0, 1, 2, \dots, \quad (1.3)$$

is convergent. In the above expression,  $M = \sup_{x \in [a,b]} |F'(x)|$ ,  $M'_m = M \cdot \text{Sign} F'(x_m)$ .

In case  $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$  we proceed as follows. Let  $F$  be differentiable in  $D_0 \subseteq \mathbb{R}^n$  and let  $F'(x) = (a_{ij}(x))$ .

Let

$$A = (C_{ij}), \quad \text{where } 0 \geq C_{ij} = -\sup_x |a_{ij}(x)|, \quad i \neq j, \quad C_{ii} \geq \sup_x \sum_{j=1}^n |a_{ij}(x)|. \quad (1.4)$$

We can show that under certain conditions  $A + F'(x)$  has an inverse even if  $F'(x)$  may not have an inverse. The Newton-like iterative sequence  $\{x_m\}$  is given by

$$x_{m+1} = x_m - 2[A + F'(x_m)]^{-1}F(x_m), \quad x_0 \in (a, b), \quad m = 0, 1, 2, \dots \quad (1.5)$$

We show that under certain assumptions  $\{x_m\}$  given by (1.2) converges to a solution of  $F(x) = 0$ . The exit criterion has been established. Section 2 presents the mathematical preliminaries. Section 3 contains the convergence theorem, Section 4 an extension of Newton's method, Section 5 contains a numerical example, and Section 6 the discussion.

### 2. Preliminaries

By componentwise partial ordering in  $\mathbb{R}^n$ , we mean for  $x, y \in \mathbb{R}^n$ ,

$$\begin{aligned} x < y &\iff x_i < y_i, \quad \forall i \\ x \leq y &\iff x_i \leq y_i, \quad \forall i, \text{ but } x \neq y, \\ x \leqslant y &\iff x_i \leq y_i. \end{aligned} \quad (2.1)$$

Let  $L(\mathbb{R}^n, \mathbb{R}^n)$  be the class of matrices which maps  $\mathbb{R}^n \rightarrow \mathbb{R}^n$ .

Let  $P \in L(\mathbb{R}^n, \mathbb{R}^n)$  and  $P = (\tilde{a}_{ij})$ .

$$\begin{aligned} P > 0 &\iff \tilde{a}_{ij} > 0, \quad \forall i, j, \\ P \geq 0 &\iff \tilde{a}_{ij} \geq 0, \quad \forall i, j, \\ P \geq 0 &\iff \tilde{a}_{ij} \geq 0, \quad \forall i, j, \text{ but } P \neq 0. \end{aligned} \quad (2.2)$$

*Definition 2.1* (*M-matrix, a Stieltjes matrix*). A matrix  $Q = (q_{ij}) \in L(\mathbb{R}^n, \mathbb{R}^n)$  is said to be an *M-matrix* if  $q_{ij} \leq 0$ , for all  $i, j, i \neq j$ .  $Q^{-1}$  exists and  $Q^{-1} \geq 0$  (Ortega and Rheinboldt [6]). A symmetric *M-matrix* is called a *Stieltjes matrix*.

*Definition 2.2* (*spectral radius*). A spectral radius of a matrix  $H$  is denoted by  $\rho(H)$  and  $\rho(H) = \sup_i |\lambda_i|$ , where  $\lambda_1, \dots, \lambda_n$  are eigenvalues of  $H$ .

**THEOREM 2.3** (Ortega and Rheinboldt [6]).  $A = (C_{ij})$  is an  $M$ -matrix if and only if (i) the diagonal elements of  $A$  are positive, and (ii) the matrix  $H = I - D^{-1}A$  where  $D = \text{diag}(a_{11}, \dots, a_{nn})$  satisfies  $\rho(H) < 1$ .

**LEMMA 2.4.** *The following results hold:*

- (i)  $A = (C_{ij})$  is an  $M$ -matrix,
- (ii)  $[A + F'(x)]$  is an  $M$ -matrix, provided the condition

$$\sup_x \left( \sum_{k=1}^n |a_{ik}(x)| \right) + a_{ii}(x) > \sum_{\substack{j=1 \\ j \neq i}}^n \left( \sup_x |a_{ij}(x)| - a_{ij}(x) \right) \quad (2.3)$$

holds.

*Proof.* (i) Let  $D$  denote the diagonal matrix  $(C_{ii})$ . Then  $D > 0$ . Moreover  $I - D^{-1}A$  is a matrix with zero diagonal elements and  $(i, j)$ th element  $= -C_{ij}/C_{ii}$ ,  $i \neq j$ .

Therefore  $\|I - D^{-1}A\|_{l_1} = \sup_i (\sum_{j, i \neq j} |C_{ij}|/C_{ii}) < 1$ , where  $\|\cdot\|_{l_1}$  denotes  $l_1$ -norm.

Thus  $\rho(I - D^{-1}A)$ , the spectral radius (Ortega and Rheinboldt [6]) of  $(I - D^{-1}A)$ , is less than 1. Hence  $A$  is an  $M$ -matrix.

(ii) We write  $F'(x) = D_1(x) - B_1(x)$  where the diagonal matrix  $D_1(x) = (a_{ii}(x))$  and the matrix  $B_1(x) = (b_{ij}(x))$ , where  $b_{ii}(x) = 0$  and  $b_{ij}(x) = -a_{ij}(x)$ , for  $i \neq j$ .

Let  $\tilde{A} = A + F'(x) = D_2(x) - B_2(x)$ , where the diagonal matrix is given by  $D_2(x) = (C_{ii} + a_{ii}(x))$ ,  $C_{ii} + a_{ii}(x) > 0$ , and the matrix  $B_2(x) = (b'_{ij}(x))$ , where  $b'_{ij}(x) = (-C_{ij} - a_{ij}(x))$ ,  $b'_{ii} = 0$ . Moreover,  $b'_{ij}(x) = \sup_x |a_{ij}(x)| - a_{ij}(x) \geq 0$ .

Let  $I - D_2(x)^{-1}\tilde{A} = (e_{ij}(x))$ , where  $e_{ii}(x) = 0$  and

$$e_{ij}(x) = \frac{-C_{ij} - a_{ij}(x)}{C_{ii} + a_{ii}(x)} \leq \frac{\sup_x |a_{ij}(x)| - a_{ij}(x)}{\sup_x \sum_{k=1}^n |a_{ik}(x)| + a_{ii}(x)}, \quad i \neq j. \quad (2.4)$$

Therefore,

$$\begin{aligned} \|I - D_2(x)^{-1}\tilde{A}\|_{l_1} &= \sup_i \sum_{\substack{j=1 \\ j \neq i}}^n |e_{ij}(x)| = \sup_i \frac{\sum_{j \neq i} |C_{ij} + a_{ij}(x)|}{|C_{ii} + a_{ii}(x)|} \\ &\leq \sup_i \frac{\sum_{j \neq i} (\sup_x |a_{ij}(x)| - a_{ij}(x))}{\sup_x \sum_{k=1}^n |a_{ik}(x)| + a_{ii}(x)} < 1 \end{aligned} \quad (2.5)$$

provided that

$$\sup_x \sum_{k=1}^n |a_{ik}(x)| + a_{ii}(x) > \sum_{\substack{j=1 \\ j \neq i}}^n (\sup_x |a_{ij}(x)| - a_{ij}(x)), \quad \forall i. \quad (2.6)$$

Thus  $\rho(I - D_2(x)^{-1}\tilde{A}) < 1$  provided the relation (2.6) holds for all  $i, j$ .  $\square$

### 3. Convergence

THEOREM 3.1. *Let the following conditions be fulfilled.*

- (i)  $F : D_0 \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ .
- (ii)  $D_0$  is an open convex subset  $\subseteq \mathbb{R}^n$ .
- (iii)  $F$  is continuously differentiable in  $D_0$ .
- (iv)  $F$  has a solution in the order-interval  $\langle a, b \rangle \subseteq D_0$ .
- (v)  $x_0 \in \langle a, b \rangle$  is an initial approximation to the solution.
- (vi)  $A = (C_{ij})$  is a matrix defined by (1.4).
- (vii)  $[A + F'(x)]$  is a Stieltjes matrix.
- (viii)  $F'(x)$  is symmetric for each  $x$  and  $F'(x) \geq 0$ .
- (ix) The eigenspaces of  $[A + F'(x)]^{-1}$  and of  $F'(x)$ , respectively, have nonempty intersection.
- (x)  $\rho(F'(x)) < \rho([A + F'(x)]^{-1})^{-1}$ , where  $\rho$  stands for the spectral radius.
- (xi)  $\rho(C(x)) < 1$  and  $\rho(C(x))(1 - \rho(C(x))) < 1/2$ , where

$$C(x) = [A + F'(x)]^{-1} F'(x + t(x^* - x)), \quad 0 < t < 1. \quad (3.1)$$

Then  $\{x_m\}$  given by

$$x_{m+1} = x_m - 2[A + F'(x_m)]^{-1} F(x_m) \quad (3.2)$$

will converge to a solution  $x^*$  of  $F(x) = 0$ , provided that  $\{x_m\} \subseteq \langle a, b \rangle$ .

*Proof.* It follows from (3.2) and the application of mean-value theorem in  $\mathbb{R}^n$  that

$$\begin{aligned} x_{m+1} - x^* &= x_m - x^* - 2[A + F'(x_m)]^{-1} (F(x_m) - F(x^*)) \\ &= \int_0^1 [I - 2[A + F'(x_m)]^{-1} F'(x_m + t(x^* - x_m))] \cdot (x_m - x^*) dt \end{aligned} \quad (3.3)$$

or

$$\|x_{m+1} - x^*\| \leq \sup_{0 < t < 1} \left\| [I - 2[A + F'(x_m)]^{-1} F'(x_m + t(x^* - x_m))] \right\| \|x_m - x^*\|. \quad (3.4)$$

Since  $F'(x) \geq 0$ ,  $F'(x_m + t(x^* - x_m)) \geq 0$ .

Also,  $[A + F'(x)]$  being a Stieltjes matrix is both symmetric and an  $M$ -matrix,  $[A + F'(x)]^{-1} \geq 0$ . Therefore,

$$C(x) = [A + F'(x)]^{-1} F'(x + t(x^* - x)) \geq 0. \quad (3.5)$$

Let  $B(x) = [I - 2[A + F'(x)]^{-1} F'(x + t(x^* - x))]$ .

Since  $C(x) \geq 0$ , by the Perron-Frobenius theorem (Varga [12]), for a given  $x$ ,  $C(x)$  has an eigenvalue  $\lambda(x) = \rho(C(x))$ , with  $\rho$  being the spectral radius. Therefore, for a given  $x$ ,

$B(x)$  has an eigenvalue  $\mu(x) = 1 - 2\lambda'(x)$ , where  $\lambda'(x)$  is an eigenvalue of  $C(x)$ . If we use Euclidean norm of a vector and then matrix norm induced by the vector norm,

$$\|B\| = [\rho(B^T B)]^{1/2}, \quad \rho(B^T B) = \sup |\mu^* \mu| = \sup_{\lambda'} |(1 - 2\lambda')^* (1 - 2\lambda')| < 1 \quad (3.6)$$

if  $|1 - 4\operatorname{Re}\lambda' + 4|\lambda'|^2| < 1$  for all  $\lambda'$ , or, if  $|\lambda'|^2 < \operatorname{Re}\lambda' < 1/2 + |\lambda'|^2$ .

Thus  $\|B\| < 1$  if

$$\rho(C(x))^2 < \rho(C(x)) < \frac{1}{2} + \rho(C(x))^2. \quad (3.7)$$

The left-hand inequality in (3.7) yields  $\rho(C(x)) < 1$ , and the right-hand inequality in (3.7) yields  $\rho(C(x))(1 - \rho(C(x))) < 1/2$  always true.

Thus by condition (xi)  $\|B\| < 1$ .

If

$$\|B\| = \alpha < 1, \quad \|x_{m+1} - x^*\| \leq \alpha \|x_m - x^*\|. \quad (3.8)$$

□

*Remark 3.2.* The sequence  $\{x_m\}$  given by (3.2) is convergent if conditions (ii)–(iv) of Theorem 3.1 are satisfied, if  $[A + F'(x)]$  is an  $M$ -matrix and  $\|I - 2[A + F'(x_m)]^{-1}F'(x)\| < 1$ .

The following theorem determines the stopping inequality.

**THEOREM 3.3.** *Let the conditions of Theorem 3.1 be true. Then the numerical computation of the sequence  $\{x_m\}$  given by (3.2) is stopped when the following inequality is valid:*

$$\|x_m - x^*\| \leq \|[I + A^{-1}F'(x_m)]\| \|A\| \cdot \left( \sup_{0 < t < 1} \|F'(x_m + t(x^* - x_m))\| \right)^{-1} \|x_{m+1} - x_m\|. \quad (3.9)$$

*Proof.* Equation (3.2) can be written as

$$\begin{aligned} \|x_{m+1} - x_m\| &= 2 \left\| [A + F'(x_m)]^{-1} [F(x_m) - F(x^*)] \right\| \\ &= \sup_{0 < t < 1} \left\| \int_0^1 [A + F'(x_m)]^{-1} F'(x_m + t(x^* - x_m)) \cdot (x^* - x_m) dt \right\| \\ &\leq \left\| [A + F'(x_m)]^{-1} \right\| \sup_{0 < t < 1} \|F'(x_m + t(x^* - x_m))\| \cdot \|x^* - x_m\|. \end{aligned} \quad (3.10)$$

Since  $A$  and  $A + F'(x_m)$  are both  $M$ -matrices,  $[I + A^{-1}F'(x_m)]^{-1}$  exists, and therefore  $\|([I + A^{-1}F'(x_m)]^{-1})^{-1}\| \leq \|I + A^{-1}F'(x_m)\|$ .

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Thus,

$$\begin{aligned} \|x^* - x_m\| &\leq \left\| \left( [A + F'(x_m)]^{-1} \right)^{-1} \left\| \left( \sup_{0 < t < 1} \|F'(x_m + t(x^* - x_m))\| \right) \right\|^{-1} \|x^* - x_m\| \right. \\ &\leq \|I + A^{-1}F'(x_m)\| \|A\| \left\| \left( \sup_{0 < t < 1} \|F'(x_m + t(x^* - x_m))\| \right) \right\|^{-1} \cdot \|x_{m+1} - x_m\|. \end{aligned} \quad (3.11)$$

□

*Note 3.4.* The inequality (3.11) may be termed as “the exit criterion” because if  $\|x_{m+1} - x_m\| < \varepsilon$ ,  $\varepsilon$  a small positive quantity, then  $\|x^* - x_m\| \leq C_m \varepsilon$ , where

$$C_m = \|[I + A^{-1}F'(x_m)]\| \|A\| \left\| \left( \sup_{0 < t < 1} \|F'(x_m + t(x^* - x_m))\| \right) \right\|^{-1}. \quad (3.12)$$

### 4. The extension of Newton’s method

However  $\langle a, b \rangle$  is generally not an invariant set with respect to iterations (3.2); that is, it is possible to obtain a certain  $p$  such that  $x_p \notin \langle a, b \rangle$ . In case  $x_p < a$  or  $x_p > b$ , the mapping  $F(x)$  is extended throughout  $\mathbb{R}^n$  in the light of Berinde’s extension, and the sequence  $\{x_m\}$  given by (3.2) is extended throughout  $\mathbb{R}^n$ .

**THEOREM 4.1.** *Let the following conditions be fulfilled:*

- (i)  $F(a) \leq 0$ ,
- (ii)  $F(x)$  is differentiable at  $a$  and  $A$  is an  $M$ -matrix (Ortega and Rheinboldt [6]),
- (iii)  $F(b) \geq 0$ ,
- (iv)  $F(x)$  is differentiable at  $b$ .

*Then if  $x_p$  goes out of  $\langle a, b \rangle$ ,  $x_{p+1}$  will lie in  $\langle a, b \rangle$ .*

*Extend  $F(x)$  throughout  $\mathbb{R}^n$  as follows:*

$$\tilde{F}(x) = \begin{cases} A(x - a) + F(a) & x \leq a, \\ F(x) & x \in \langle a, b \rangle, \\ A(x - b) + F(b) & x \geq b. \end{cases} \quad (4.1)$$

*Proof.* If some iteration  $x_p$  does not lie in  $\langle a, b \rangle$  we have either  $x_p < a$  or  $x_p > b$ . In the first case applying (3.2) after extension to  $\tilde{F}(x)$  we get

$$\begin{aligned} x_{p+1} &= x_p - 2[A + \tilde{F}'(x_p)]^{-1} \tilde{F}(x_p) = x_p - 2[2A]^{-1}[A(x_p - a) + F(a)] \\ &= x_p - (x_p - a) - A^{-1}F(a) = a - A^{-1}F(a) > a, \end{aligned} \quad (4.2)$$

since  $A$  is an  $M$ -matrix and  $F(a) \leq 0$ . Therefore,  $x_{p+1} \in \langle a, b \rangle$ .

If  $x_p > b$ , repeating the same steps as above we get

$$x_{p+1} = x_p - 2[2A]^{-1}[A(x_p - b) + F(b)] = x_p - (x_p - b) - A^{-1}F(b) = b - A^{-1}F(b). \quad (4.3)$$

Since  $A$  is an  $M$ -matrix and  $F(b) \geq 0$ ,  $A^{-1}F(b) \geq 0$ . Hence  $x_{p+1} \in \langle a, b \rangle$ .

Thus beginning from a step  $p_0 \geq 0$ , we necessarily have  $x_m \in [a, b]$ . If Theorems 3.1 and 4.1 are valid,  $x_m \in \langle a, b \rangle$  for  $m \geq p_0$ , and the convergence of  $\{x_m\}$  to a solution  $x^*$  in  $\langle a, b \rangle$  is guaranteed. Furthermore, the error estimate (3.8) and the exit criterion or the stopping inequality (3.9) are both valid.  $\square$

## 5. Numerical example

Let  $z = [x, y]^T$ ,  $D_0 = \langle -(\pi/2), \pi \rangle \times \langle 0, 1 \rangle$ .

$$F(z) = \begin{cases} f_1(x, y) \\ f_2(x, y) \end{cases} = \begin{cases} \left(x - \frac{\pi}{2}\right)^3 + \left(\left(x - \frac{\pi}{2}\right) \sin\left(x - \frac{\pi}{2}\right)\right)y - 0.752 \\ \pi^2 y + \pi^2 y^3 - \left(x - \frac{\pi}{2}\right) \cos\left(x - \frac{\pi}{2}\right) + \sin\left(x - \frac{\pi}{2}\right) - \frac{5\pi^2}{8} - 0.152. \end{cases} \quad (5.1)$$

We are interested in solving  $F(z) = 0$  for  $z \in D_0$ .

Initial approximation  $z_0 = (x_0, y_0)^T$ .

$$\begin{aligned} \frac{\partial f_1}{\partial x} &= 3\left(x - \frac{\pi}{2}\right)^2 + \left(\sin\left(x - \frac{\pi}{2}\right)\right)y + \left(\left(x - \frac{\pi}{2}\right) \cos\left(x - \frac{\pi}{2}\right)\right)y, \\ \frac{\partial f_1}{\partial y} &= \left(x - \frac{\pi}{2}\right) \sin\left(x - \frac{\pi}{2}\right), \\ \frac{\partial f_2}{\partial x} &= \left(x - \frac{\pi}{2}\right) \sin\left(x - \frac{\pi}{2}\right), \\ \frac{\partial f_2}{\partial y} &= \pi^2 + 3\pi^2 y^2. \end{aligned} \quad (5.2)$$

$F'(z)$  is symmetric.

$F'(z) \geq 0$  for all  $x \in \langle -\pi, \pi \rangle$  and  $y \in \langle 0, 1 \rangle$  except at  $x = -\pi$ ,  $y = \pi$ .

$$\begin{aligned} F(a) = F(x)|_{\substack{x=-\pi/2 \\ y=0}} &= \begin{cases} -\pi^3 - 0.752 \\ -\frac{5\pi^2}{8} - \pi - 0.152 \end{cases} \leq 0, \\ F(b) = F(x)|_{\substack{x=\pi \\ y=1}} &= \begin{cases} \frac{\pi^3}{8} + \frac{\pi}{2} - 0.752 \\ \frac{3\pi^2}{8} + 1 - 0.152 \end{cases} \geq 0. \end{aligned} \quad (5.3)$$

$F'(z)|_{\substack{x=\pi/2 \\ y=0}}$  does not have an inverse.

We choose  $A$  as

$$A = \begin{pmatrix} 2 & -1.5708 \\ -1.5708 & 22 \end{pmatrix} \quad (5.4)$$

and  $\epsilon = 10^{-11}$ , the desired accuracy is achieved in 17 iterations.

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Starting from  $x_0 = 1.5708$  and  $y_0 = 0$ , we obtain  $x_1 = 2.67715530056448$  and  $y_1 = 0.45117812654687$ ; and  $x_{17} = 2.35205300236830$  and  $y_{17} = 0.50014720328245$ .

### 6. Discussion

(i) Convergence of Newton's method as proposed by Kantorovich (see [11]) is based on majorization principle which ensures that all the members of the sequence  $\{x_m\}$  will lie in a small neighborhood of the initial approximation  $x_0$ . Hence majorization principle has not been used. But in order to ensure that  $\{x_m\}$  does not go beyond  $\langle a, b \rangle$ , barring a finite number of members, an extended formula of the mapping  $F$  is taken.

(ii) Here the condition that  $F'(x) \neq 0$  has been relaxed and the extended method is called Newton-like method.

(iii) The convergence is linear.

(iv) The numerical equation under consideration being nonlinear has more than one solution, the  $x$ -component of one solution being  $x^* = 1.087961617$ . In our case, the initial point taken is close to a point where the Jacobian becomes singular and the purpose is to show that the sequence of iterations (1.5) with the initial point mentioned above still converges to a solution of the given equation.

(v) For other modifications of Newton's method please see (Ortega and Rheinboldt [6], Keller [5], Sen [7, 8], Sen and Guhathakurta [10]).

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