

Research Article

Liouville Theorems for a Class of Linear Second-Order Operators with Nonnegative Characteristic Form

Alessia Elisabetta Kogoj and Ermanno Lanconelli

Received 1 August 2006; Revised 28 November 2006; Accepted 29 November 2006

Recommended by Vincenzo Vespri

We report on some Liouville-type theorems for a class of linear second-order partial differential equation with nonnegative characteristic form. The theorems we show improve our previous results.

Copyright © 2007 A. E. Kogoj and E. Lanconelli. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

1. Introduction

In this paper, we survey and improve some Liouville-type theorems for a class of hypoelliptic second-order operators, appeared in the series of papers [1–4].

The operators considered in these papers can be written as follows:

$$\mathcal{L} := \sum_{i,j=1}^N \partial_{x_i} (a_{ij}(x) \partial_{x_j}) + \sum_{i=1}^N b_i(x) \partial_{x_i} - \partial_t, \quad (1.1)$$

where the coefficients a_{ij} , b_i are t -independent and smooth in \mathbb{R}^N . The matrix $A = (a_{ij})_{i,j=1,\dots,N}$ is supposed to be symmetric and nonnegative definite at any point of \mathbb{R}^N .

We will denote by $z = (x, t)$, $x \in \mathbb{R}^N$, $t \in \mathbb{R}$, the point of \mathbb{R}^{N+1} , by Y the first-order differential operator

$$Y := \sum_{i=1}^N b_i(x) \partial_{x_i} - \partial_t, \quad (1.2)$$

2 Boundary Value Problems

and by \mathcal{L}_0 the *stationary* counterpart of \mathcal{L} , that is,

$$\mathcal{L}_0 := \sum_{i,j=1}^N \partial_{x_i} (a_{ij}(x) \partial_{x_j}) + \sum_{i=1}^N b_i(x) \partial_{x_i}. \quad (1.3)$$

We always assume the operator Y to be divergence free, that is, $\sum_{i=1}^N \partial_{x_i} b_i(x) = 0$ at any point $x \in \mathbb{R}^N$. Moreover, as in [2], we assume the following hypotheses.

(H1) \mathcal{L} is homogeneous of degree two with respect to the group of dilations $(d_\lambda)_{\lambda>0}$ given by

$$\begin{aligned} d_\lambda(x, t) &= (D_\lambda(x), \lambda^2 t), \\ D_\lambda(x) &= D_\lambda(x_1, \dots, x_N) = (\lambda^{\sigma_1} x_1, \dots, \lambda^{\sigma_N} x_N), \end{aligned} \quad (1.4)$$

where $\sigma = (\sigma_1, \dots, \sigma_N)$ is an N -tuple of natural numbers satisfying $1 = \sigma_1 \leq \sigma_2 \leq \dots \leq \sigma_N$. When we say that \mathcal{L} is d_λ -homogeneous of degree two, we mean that

$$\mathcal{L}(u(d_\lambda(x, t))) = \lambda^2 (\mathcal{L}u)(d_\lambda(x, t)) \quad \forall u \in C^\infty(\mathbb{R}^{N+1}). \quad (1.5)$$

(H2) For every $(x, t), (y, \tau) \in \mathbb{R}^{N+1}$, $t > \tau$, there exists an \mathcal{L} -admissible path $\eta : [0, T] \rightarrow \mathbb{R}^{N+1}$ such that $\eta(0) = (x, t)$, $\eta(T) = (y, \tau)$.

An \mathcal{L} -admissible path is any continuous path η which is the sum of a finite number of diffusion and drift trajectories.

A *diffusion trajectory* is a curve η satisfying, at any points of its domain, the inequality

$$(\langle \eta'(s), \xi \rangle)^2 \leq \langle \hat{A}(\eta(s)) \xi, \xi \rangle \quad \forall \xi \in \mathbb{R}^N. \quad (1.6)$$

Here $\langle \cdot, \cdot \rangle$ denotes the inner product in \mathbb{R}^{N+1} and $\hat{A}(z) = \hat{A}(x, t) = \hat{A}(x)$ stands for the $(N+1) \times (N+1)$ matrix

$$\hat{A} = \begin{pmatrix} A & 0 \\ 0 & 0 \end{pmatrix}. \quad (1.7)$$

A *drift trajectory* is a positively oriented integral curve of Y .

Throughout the paper, we will denote by Q the homogeneous dimension of \mathbb{R}^{N+1} with respect to the dilations (1.4), that is,

$$Q = \sigma_1 + \dots + \sigma_N + 2 \quad (1.8)$$

and assume

$$Q \geq 5. \quad (1.9)$$

Then, the D_λ -homogeneous dimension of \mathbb{R}^N is $Q - 2 \geq 3$.

We explicitly remark that the smoothness of the coefficients of \mathcal{L} and the homogeneity assumption in (H1) imply that the a_{ij} 's and the b_i 's are polynomial functions (see [5, Lemma 2]). Moreover, the ‘‘oriented’’ connectivity condition in (H1) implies the

hypocoellipticity of \mathcal{L} and of \mathcal{L}_0 (see [1, Proposition 10.1]). For any $z = (x, t) \in \mathbb{R}^{N+1}$, we define the d_λ -homogeneous norm $|z|$ by

$$|z| = |(x, t)| := (|x|^4 + t^2)^{1/4}, \quad (1.10)$$

where

$$|x| = |(x_1, \dots, x_N)| = \left(\sum_{j=1}^N (x_j^2)^{\sigma/\sigma_j} \right)^{1/2\sigma}, \quad \sigma = \prod_{j=1}^N \sigma_j. \quad (1.11)$$

Hypotheses (H1) and (H2) imply the existence of a fundamental solution $\Gamma(z, \zeta)$ of \mathcal{L} with the following properties (see [2, page 308]):

- (i) Γ is smooth in $\{(z, \zeta) \in \mathbb{R}^{N+1} \times \mathbb{R}^{N+1} \mid z \neq \zeta\}$,
- (ii) $\Gamma(\cdot, \zeta) \in L_{loc}^1(\mathbb{R}^{N+1})$ and $\mathcal{L}\Gamma(\cdot, \zeta) = -\delta_\zeta$ for every $\zeta \in \mathbb{R}^{N+1}$,
- (iii) $\Gamma(z, \cdot) \in L_{loc}^1(\mathbb{R}^{N+1})$ and $\mathcal{L}^*\Gamma(z, \cdot) = -\delta_z$ for every $z \in \mathbb{R}^{N+1}$,
- (iv) $\limsup_{\zeta \rightarrow z} \Gamma(z, \zeta) = \infty$ for every $z \in \mathbb{R}^{N+1}$,
- (v) $\Gamma(0, \zeta) \rightarrow 0$ as $\zeta \rightarrow \infty$, $\Gamma(0, d_\lambda(\zeta)) = \lambda^{-Q+2}\Gamma(0, \zeta)$,
- (vi) $\Gamma((x, t), (\xi, \tau)) \geq 0$, > 0 if and only if $t > \tau$,
- (vii) $\Gamma((x, t), (\xi, \tau)) = \Gamma((x, 0), (\xi, \tau - t))$.

In (iii) \mathcal{L}^* denotes the formal adjoint of \mathcal{L} .

These properties of Γ allow to obtain a mean value formula at $z = 0$ for the entire solutions to $\mathcal{L}u = 0$. We then use this formula to prove a *scaling invariant Harnack inequality* for the *nonnegative* solutions $\mathcal{L}u = f$ in \mathbb{R}^{N+1} . Our first Liouville-type theorems will follow from this Harnack inequality. All these results will be showed in Section 2.

In Section 3, we show some *asymptotic* Liouville theorem for nonnegative solution to $\mathcal{L}u = 0$ in the halfspace $\mathbb{R}^N \times]-\infty, 0[$ assuming that \mathcal{L} , together with (H1) and (H2), is left invariant with respect to some Lie groups in \mathbb{R}^{N+1} .

Finally, in Section 4 some examples of operators to which our results apply are showed.

2. Polynomial Liouville theorems

Throughout this section, we will assume that \mathcal{L} in (1.1) satisfies hypotheses (H1) and (H2). Let Γ be the fundamental solution of \mathcal{L} with pole at the origin. With a standard procedure based on the Green identity for \mathcal{L} and by using the properties of Γ recalled in the introduction, one obtains a mean value formula at $z = 0$ for the solution to $\mathcal{L}u = 0$. Precisely, for every point $(0, T) \in \mathbb{R}^{N+1}$ and $r > 0$, define the \mathcal{L} -ball centered at $(0, T)$ and with radius r , as follows:

$$\Omega_r(0, T) := \left\{ \zeta \in \mathbb{R}^{N+1} : \Gamma((0, T), \zeta) > \left(\frac{1}{r}\right)^{Q-2} \right\}. \quad (2.1)$$

Then, if $\mathcal{L}u = 0$ in \mathbb{R}^{N+1} , one has

$$u(0, T) = \left(\frac{1}{r}\right)^{Q-2} \int_{\Omega_r(0, T)} K(T, \zeta) u(\zeta) d\zeta, \quad (2.2)$$

4 Boundary Value Problems

where

$$K(T, \zeta) = \frac{\langle A(\xi) \nabla_{\xi} \Gamma, \nabla_{\xi} \Gamma \rangle}{\Gamma^2}, \quad \zeta = (\xi, \tau), \quad (2.3)$$

and Γ stands for $\Gamma((0, T), (\xi, \tau))$. Moreover, $\langle \cdot, \cdot \rangle$ denotes the inner product in \mathbb{R}^N and ∇_{ξ} is the gradient operator $(\partial_{\xi_1}, \dots, \partial_{\xi_N})$.

Formula (2.2) is just one of the numerous extensions of the classical Gauss mean value theorem for harmonic functions. For a proof of it, we directly refer to [6, Theorem 1.5]. We would like to stress that in this proof one uses our assumption $\operatorname{div} Y = 0$.

The kernel $K(T, \cdot)$ is strictly positive in a dense open subset of $\Omega_r(0, T)$ for every $T, r > 0$ (see [2, Lemma 2.3]). This property of $K(T, \cdot)$, together with the d_{λ} -homogeneity of \mathcal{L} , leads to the following Harnack-type inequality for entire solutions to $\mathcal{L}u = 0$.

THEOREM 2.1. *Let $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$ be a nonnegative solution to $\mathcal{L}u = 0$ in \mathbb{R}^{N+1} . Then, there exist two positive constants $C = C(\mathcal{L})$ and $\theta = \theta(\mathcal{L})$ such that*

$$\sup_{C_{\theta r}} u \leq C u(0, r^2) \quad \forall r > 0, \quad (2.4)$$

where, for $\rho > 0$, C_{ρ} denotes the d_{λ} -symmetric ball

$$C_{\rho} := \{z \in \mathbb{R}^{N+1} \mid |z| < \rho\}. \quad (2.5)$$

The proof of this theorem is contained in [2, page 310].

By using inequality (2.4) together with some basic properties of the fundamental solution Γ , one easily gets the following a priori estimates for the positive solution to $\mathcal{L}u = f$ in \mathbb{R}^{N+1} .

COROLLARY 2.2. *Let f be a smooth function in \mathbb{R}^{N+1} and let u be a nonnegative solution to*

$$\mathcal{L}u = f \quad \text{in } \mathbb{R}^{N+1}. \quad (2.6)$$

Then there exists a positive constant C independent of u and f such that

$$u(z) \leq C u \left(0, \left(\frac{|z|}{\theta} \right)^2 \right) + |z|^2 \sup_{|\zeta| \leq |z|/\theta^2} |f(\zeta)|, \quad (2.7)$$

where θ is the constant in Theorem 2.1.

This result allows to use the Liouville-type theorem of Luo [5] to obtain our main result in this section.

THEOREM 2.3. *Let $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$ be a smooth function such that*

$$\begin{aligned} \mathcal{L}u &= p \quad \text{in } \mathbb{R}^{N+1}, \\ u &\geq q \quad \text{in } \mathbb{R}^{N+1}, \end{aligned} \quad (2.8)$$

where p and q are polynomial function. Assume

$$u(0, t) = O(t^m) \quad \text{as } t \rightarrow \infty. \quad (2.9)$$

Then, u is a polynomial function.

Proof. We split the proof into two steps.

Step 1. There exists $n > 0$ such that

$$u(z) = O(|z|^n) \quad \text{as } z \rightarrow \infty. \quad (2.10)$$

Indeed, letting $v := u - q$, we have

$$\begin{aligned} \mathcal{L}v &= p - \mathcal{L}q \quad \text{in } \mathbb{R}^{N+1}, \\ v &\geq 0 \quad \text{in } \mathbb{R}^{N+1}, \end{aligned} \quad (2.11)$$

and $v(0, t) = u(0, t) - q(0, t) = O(t^{n_1})$ as $t \rightarrow \infty$, for a suitable $n_1 > 0$. Moreover, since p and $\mathcal{L}q$ are polynomial functions, $(p - \mathcal{L}q)(z) = O(|z|^{m_1})$ as $z \rightarrow \infty$ for a suitable $m_1 > 0$. Then, by the previous corollary, there exists $m_2 > 0$ such that

$$v(z) = O(|z|^{m_2}) \quad \text{as } z \rightarrow \infty. \quad (2.12)$$

From this estimate, since $v = u + q$, and q is a polynomial function, the assertion (2.10) follows.

Step 2. Since p is a polynomial function and \mathcal{L} is d_λ -homogeneous, there exists $m \in \mathbb{N}$ such that

$$\mathcal{L}^{(m)}p \equiv 0, \quad (2.13)$$

where $\mathcal{L}^{(m)} = \mathcal{L} \circ \dots \circ \mathcal{L}$ is the m th iterated of \mathcal{L} . It follows that

$$\mathcal{L}^{(m+1)}u = 0 \quad \text{in } \mathbb{R}^{N+1}. \quad (2.14)$$

Moreover, since \mathcal{L} is d_λ -homogeneous and hypoelliptic, the same properties hold for $\mathcal{L}^{(m+1)}$. On the other hand, by Step 1, $u(z) = O(z^m)$ as $z \rightarrow \infty$, so that u is a *tempered distribution*. Then, by Luo's paper [5, Theorem 1], u is a *polynomial function*. \square

Remark 2.4. It is well known that hypothesis (2.9) in the previous theorem cannot be removed. Indeed, if $\mathcal{L} = \Delta - \partial_t$ is the classical heat operator and $u(x, t) = \exp(x_1 + \dots + x_N + Nt)$, $x = (x_1, \dots, x_N) \in \mathbb{R}^N$ and $t \in \mathbb{R}$, we have

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^{N+1}, \quad u \geq 0, \quad (2.15)$$

and u is *not* a polynomial function.

In the previous theorem, the degree of the polynomial function u can be estimated in terms of the ones of p and q . For this, we need some more notation. If $\alpha = (\alpha_1, \dots, \alpha_N, \alpha_{N+1})$ is a multi-index with $(N + 1)$ nonnegative integer components, we let

$$|\alpha|_{d_\lambda} := \sigma_1 \alpha_1 + \dots + \sigma_N \alpha_N + 2\alpha_{N+1}, \quad (2.16)$$

6 Boundary Value Problems

and, if $z = (x, t) = (x_1, \dots, x_N, t) \in \mathbb{R}^{N+1}$,

$$z^\alpha := x_1^{\alpha_1} \cdots x_N^{\alpha_N} t^{\alpha_{N+1}}. \quad (2.17)$$

As a consequence, we can write every polynomial function p in \mathbb{R}^{N+1} , as follows:

$$p(z) = \sum_{|\alpha|_{d_\lambda} \leq m} c_\alpha z^\alpha \quad (2.18)$$

with $m \in \mathbb{Z}$, $m \geq 0$, and $c_\alpha \in \mathbb{R}$ for every multi-index α . If

$$\sum_{|\alpha|_{d_\lambda} = m} c_\alpha z^\alpha \neq 0 \quad \text{in } \mathbb{R}^{N+1}, \quad (2.19)$$

then we set

$$m = \deg_{d_\lambda} p. \quad (2.20)$$

If p is independent of t , that is, if p is a polynomial function in \mathbb{R}^N , we denote by

$$\deg_{D_\lambda} p \quad (2.21)$$

the degree of p with respect to the dilations $(D_\lambda)_{\lambda>0}$. Obviously, in this case, $\deg_{D_\lambda} p = \deg_{d_\lambda} p$.

PROPOSITION 2.5. *Let $u, p : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$ be polynomial functions such that*

$$\mathcal{L}u = p \quad \text{in } \mathbb{R}^{N+1}. \quad (2.22)$$

Assume $u \geq 0$. Thus, the following statements hold.

- (i) *If $p \equiv 0$, then $u = \text{constant}$.*
- (ii) *If $p \neq 0$, then*

$$\deg_{d_\lambda} u = 2 + \deg_{d_\lambda} p. \quad (2.23)$$

This proposition is a consequence of the following lemma.

LEMMA 2.6. *Let $u : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$ be a nonnegative polynomial function d_λ -homogeneous of degree $m > 0$. Then $\mathcal{L}u \neq 0$ in \mathbb{R}^{N+1} .*

Proof. We argue by contradiction and assume $\mathcal{L}u = 0$. Since u is nonnegative and d_λ -homogeneous of strictly positive degree, we have

$$u(0,0) = 0 = \min_{\mathbb{R}^{N+1}} u. \quad (2.24)$$

Let us now denote by \mathcal{P} the \mathcal{L} -propagation set of $(0,0)$ in \mathbb{R}^{N+1} , that is, the set

$$\begin{aligned} \mathcal{P} := \{z \in \mathbb{R}^{N+1} : \text{there exists an } \mathcal{L}\text{-admissible path } \eta : [0, T] \rightarrow \mathbb{R}^{N+1}, \\ \text{s.t. } \eta(0) = (0,0), \eta(T) = z\}. \end{aligned} \quad (2.25)$$

From hypotheses (H2), we obtain $\mathcal{P} = \mathbb{R}^N \times] - \infty, 0]$ so that, since $(0, 0)$ is a minimum point of u and the minimum spread all over \mathcal{P} (see [7]), we have

$$u(z) = u(0, 0) = 0 \quad \forall z \in \mathbb{R}^N \times] - \infty, 0]. \quad (2.26)$$

Then, being u a polynomial function, $u \equiv 0$ in \mathbb{R}^{N+1} . This contradicts the assumption $\deg_{d_\lambda} u > 0$, and completes the proof. \square

Proof of Proposition 2.5. Obviously, if $u = \text{constant}$, we have nothing to prove. If we assume $m := \deg_{d_\lambda} u > 0$ and prove that

$$m \geq 2, \quad p \neq 0, \quad \deg_{d_\lambda} p = m - 2, \quad (2.27)$$

then it would complete the proof. Let us write u as follows:

$$u = u_0 + u_1 + \cdots + u_m, \quad (2.28)$$

where u_j is a polynomial function d_λ -homogeneous of degree j , $j = 0, \dots, m$, and $u_m \neq 0$ in \mathbb{R}^{N+1} .

Then

$$p = \mathcal{L}u = \mathcal{L}u_0 + \mathcal{L}u_1 + \cdots + \mathcal{L}u_m, \quad (2.29)$$

and, since \mathcal{L} is d_λ -homogeneous of degree two,

$$(\mathcal{L}u_j)(d_\lambda(x)) = \lambda^{j-2} \mathcal{L}u_j(x) \quad (2.30)$$

so that $\mathcal{L}u_0 = \mathcal{L}u_1 \equiv 0$ and $\deg_{d_\lambda} \mathcal{L}u_j = j - 2$ if and only if $\mathcal{L}u_j \neq 0$.

On the other hand, the hypothesis $u \geq 0$ implies $u_m \geq 0$ so that, being $u_m \neq 0$ and d_λ -homogeneous of degree $m > 0$, by Lemma 2.6, we get $\mathcal{L}u_m \neq 0$. Hence $m \geq 2$. Moreover, by (2.29), $p = \mathcal{L}u \neq 0$ and

$$\deg_{d_\lambda} p = \deg_{d_\lambda} \mathcal{L}u_m = m - 2. \quad (2.31)$$

\square

This proposition allows us to make more precise the conclusion of Theorem 2.3. Indeed, we have the following.

PROPOSITION 2.7. *Let $u, p, q : \mathbb{R}^{N+1} \rightarrow \mathbb{R}$ be polynomial functions such that*

$$\begin{aligned} \mathcal{L}u &= p \quad \text{in } \mathbb{R}^{N+1}, \\ u &\geq q \quad \text{in } \mathbb{R}^{N+1}. \end{aligned} \quad (2.32)$$

Then

$$\deg_{d_\lambda} u \leq \max \{2 + \deg_{d_\lambda} p, \deg_{d_\lambda} q\}. \quad (2.33)$$

In particular, and more precisely, if $q = 0$, that is, if $u \geq 0$, then

$$\begin{aligned} \deg_{d_\lambda} u &= 2 + \deg_{d_\lambda} p \quad \text{if } p \neq 0, \\ u &= \text{constant} \quad \text{if } p \equiv 0. \end{aligned} \quad (2.34)$$

8 Boundary Value Problems

Proof. If $q \equiv 0$, the assertion is the one of Proposition 2.5. Suppose $q \not\equiv 0$. By letting $v := u - q$, we have

$$\mathcal{L}v = p - \mathcal{L}q, \quad v \geq 0. \quad (2.35)$$

By Proposition 2.5, we have

$$\deg_{d_\lambda} v \leq 2 + \deg_{d_\lambda} (p - \mathcal{L}q) \leq 2 + \max \{ \deg_{d_\lambda} p, \deg_{d_\lambda} q - 2 \} = \max \{ 2 + \deg_{d_\lambda} p, \deg_{d_\lambda} q \} \quad (2.36)$$

and (2.33) follows. \square

Proposition 2.7, together with Theorem 2.3, extends and improves the Liouville-type theorems contained in [2, 4] (precisely [2, Theorem 1.1] and [4, Theorem 1.2]).

From Theorem 2.3 and Proposition 2.7, we straightforwardly get the following polynomial Liouville theorem for the stationary operator \mathcal{L}_0 in (1.3).

THEOREM 2.8. *Let $P, Q: \mathbb{R}^N \rightarrow \mathbb{R}$ be polynomial functions and let $U: \mathbb{R}^N \rightarrow \mathbb{R}$ be a smooth function such that*

$$\mathcal{L}_0 U = P, \quad U \geq Q, \text{ in } \mathbb{R}^N. \quad (2.37)$$

Then, U is a polynomial function and

$$\deg_{D_\lambda} U \leq \max \{ 2 + \deg_{D_\lambda} P, \deg_{D_\lambda} Q \}. \quad (2.38)$$

In particular, and more precisely, if $Q \equiv 0$, that is, if $U \geq 0$, then

$$\begin{aligned} \deg_{D_\lambda} U &= 2 + \deg_{D_\lambda} P && \text{if } P \not\equiv 0, \\ U &= \text{constant} && \text{if } P \equiv 0. \end{aligned} \quad (2.39)$$

Proof. Let us define

$$u(x, t) = U(x), \quad p(x, t) = P(x), \quad q(x, t) = Q(x). \quad (2.40)$$

Then p, q are polynomial functions in \mathbb{R}^{N+1} and u is a smooth solution to the equation

$$\mathcal{L}u = p \quad \text{in } \mathbb{R}^{N+1}, \quad (2.41)$$

such that $u \geq q$. Moreover,

$$u(0, t) = U(0) = O(1) \quad \text{as } t \rightarrow \infty. \quad (2.42)$$

Then, by Theorem 2.3, u is a polynomial function in \mathbb{R}^{N+1} . This obviously implies that U is a polynomial in \mathbb{R}^N . The second part of the theorem immediately follows from Proposition 2.5. \square

Remark 2.9. The class of our stationary operators \mathcal{L}_0 also contains “parabolic”-type operators like, for example, the following “forward-backward” heat operator

$$\mathcal{L}_0 := \partial_{x_1}^2 + x_1 \partial_{x_2} \quad \text{in } \mathbb{R}^2. \quad (2.43)$$

Nevertheless, in Theorem 2.8, we do not require any a priori behavior at infinity, like condition (2.9) in Theorem 2.3.

3. Asymptotic Liouville theorems in halfspaces

The operator \mathcal{L} in our class do not satisfy the *usual* Liouville property. Precisely, if u is a nonnegative solution to

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^{N+1}, \quad (3.1)$$

then we cannot conclude that $u \equiv \text{constant}$ without asking an extra condition on the solution u (see Theorem 2.3 and Remark 2.4).

However, if we also assume that \mathcal{L} is left translation invariant with respect to the composition law of some Lie group in \mathbb{R}^{N+1} , then we can show that *every nonnegative solution of (3.1) is constant at $t = -\infty$* .

To be precise, let us fix the new hypothesis on \mathcal{L} and give the definition of \mathcal{L} -parabolic trajectory.

Suppose \mathcal{L} satisfies (H2) of the introduction and, instead of (H1), the following condition

(H1)* There exists a homogeneous Lie group in \mathbb{R}^{N+1} ,

$$\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \quad (3.2)$$

such that \mathcal{L} is left translation invariant on \mathbb{L} and d_λ -homogeneous of degree two.

We assume the composition law \circ is Euclidean in the time variable, that is,

$$(x, t) \circ (x', t') = (c(x, t, x', t'), t + t'), \quad (3.3)$$

where $c(x, t, x', t')$ denotes a suitable function of (x, t) and (x', t') .

It is a standard matter to prove the existence of a positive constant C such that

$$|z \circ \zeta| \leq C(|z| + |\zeta|) \quad \forall z, \zeta \in \mathbb{R}^{N+1}. \quad (3.4)$$

Let $\gamma : [0, \infty[\rightarrow \mathbb{R}^N$ be a continuous function such that

$$\limsup_{s \rightarrow \infty} \frac{|\gamma(s)|^2}{s} < \infty \quad (3.5)$$

(here $|\cdot|$ denotes the D_λ -homogeneous norm (1.11)).

Then, the path

$$s \mapsto \eta(s) = (\gamma(s), T - s), \quad T \in \mathbb{R}, \quad (3.6)$$

will be called an \mathcal{L} -parabolic trajectory.

Obviously, the curve

$$s \mapsto \eta(s) = (\alpha, T - s), \quad \alpha \in \mathbb{R}^N, T \in \mathbb{R} \quad (3.7)$$

is an \mathcal{L} -parabolic trajectory. It can be proved that every integral curve of the vector fields Y in (1.2) also is an \mathcal{L} -parabolic trajectory (see [3, Lemma 3]).

Our first asymptotic Liouville theorem is the following one.

THEOREM 3.1. *Let \mathcal{L} satisfy hypotheses (H1)* and (H2), and let u be a nonnegative solution to the equation*

$$\mathcal{L}u = 0 \quad (3.8)$$

in the halfspace

$$S = \mathbb{R}^N \times]-\infty, 0[. \quad (3.9)$$

Then, for every \mathcal{L} -parabolic trajectory η ,

$$\lim_{s \rightarrow \infty} u(\eta(s)) = \inf_S u. \quad (3.10)$$

In particular

$$\lim_{t \rightarrow -\infty} u(x, t) = \inf_S u \quad \forall x \in \mathbb{R}^N. \quad (3.11)$$

The proof of this theorem relies on a *left translation* and *scaling invariant* Harnack inequality for nonnegative solutions to $\mathcal{L}u = 0$.

For every $z_0 \in \mathbb{R}^{N+1}$ and $M > 0$, let us put

$$P_{z_0}(M) := z_0 \circ P(M), \quad (3.12)$$

where

$$P(M) := \{(x, t) \in \mathbb{R}^{N+1} : |x|^2 \leq -Mt\}. \quad (3.13)$$

Then, the following theorem holds.

THEOREM 3.2 (left and scaling invariant Harnack inequality). *Let u be a nonnegative solution to*

$$\mathcal{L}u = 0 \quad \text{in } \mathbb{R}^N \times]-\infty, 0[. \quad (3.14)$$

Then, for every $z_0 \in \mathbb{R}^N \times]-\infty, 0[$ and $M > 0$, there exists a positive constant $C = C(M)$, independent of z_0 and u , such that

$$\sup_{P_{z_0}(M)} u \leq Cu(z_0). \quad (3.15)$$

Proof. It follows from Theorem 2.1 and the left translation invariance of \mathcal{L} . The details are contained in [3, Proof of Theorem 3]. \square

From this theorem we obtain the proof of Theorem 3.1.

Proof of Theorem 3.1. We may assume $\inf_S u = 0$. Let $\eta(s) = (\gamma(s), s_0 - s)$, $s_0 \leq 0$, $s \geq s_0$ be an \mathcal{L} -parabolic trajectory. Then, there exists $M_0 > 0$ such that

$$|\gamma(s)|^2 \leq M_0 s \quad \forall s \geq s^*, \quad (3.16)$$

where $s^* > 0$ is big enough. Let us put $M = 2C(M_0^2 + 1)^{1/4}$ where C is the positive constant in the triangular inequality (3.4). Let $\varepsilon > 0$ be arbitrarily fixed and choose $z_\varepsilon = (x_\varepsilon, t_\varepsilon) \in S$ such that

$$u(z_\varepsilon) < \varepsilon. \quad (3.17)$$

Now, for every $s \geq s^*$, we have

$$\begin{aligned} |z_\varepsilon^{-1} \circ \eta(s)| &\leq C(|z_\varepsilon^{-1}| + |\eta(s)|) \\ &\leq C(|z_\varepsilon^{-1}| + (M_0^2 + 1)^{1/4} \sqrt{s}) \\ &= C\sqrt{s - s_0 + t_\varepsilon} \left(\frac{|z_\varepsilon^{-1}|}{\sqrt{s - s_0 + t_\varepsilon}} + (M_0^2 + 1)^{1/4} \sqrt{\frac{s}{s - s_0 + t_\varepsilon}} \right). \end{aligned} \quad (3.18)$$

Then, there exists $T = T(\varepsilon) > 0$ such that

$$|z_\varepsilon^{-1} \circ \eta(s)| \leq M\sqrt{s - s_0 + t_\varepsilon} \quad \forall s > T. \quad (3.19)$$

This implies that

$$\eta(s) \in z_\varepsilon \circ P(M) \equiv P_{z_\varepsilon}(M) \quad \forall s > T. \quad (3.20)$$

On the other hand, by the Harnack inequality of Theorem 3.2, there exists $C^* = C^*(M) > 0$ independent of z_ε and ε such that

$$\sup_{P_{z_\varepsilon}(M)} u \leq C^* u(z_\varepsilon). \quad (3.21)$$

Therefore,

$$u(\eta(s)) \leq C^* \varepsilon \quad \forall s > T. \quad (3.22)$$

Since C^* is independent of ε , this proves the theorem. \square

Theorem 3.1 is contained in [3, Theorem 1]. The idea of our proof is taken from Glagoleva's paper [8], in which classical parabolic operators of Cordes-type are considered. For the heat equation, a stronger version of Theorem 3.1 was proved by Bear [9].

The following theorem improves Theorem 3.1.

THEOREM 3.3. *Let \mathcal{L} and u as in Theorem 3.1. For every $M > 0$ and $t < 0$, define*

$$M(u, t) = \sup \{u(x, t) : |x|^2 \leq -Mt\}. \quad (3.23)$$

Then

$$\lim_{t \rightarrow -\infty} M(u, t) = \inf_S u. \quad (3.24)$$

Proof. Let ε be arbitrarily fixed and let $z_\varepsilon = (x_\varepsilon, t_\varepsilon) \in S$ be such that

$$u(z_\varepsilon) < m + \varepsilon, \quad m := \inf_S u. \quad (3.25)$$

Let M_0 be a positive constant that will be chosen later independently of ε . Since $u - m$ is a nonnegative solution to $\mathcal{L}v = 0$ in S , the Harnack inequality of Theorem 3.2 implies

$$u(z) - m \leq C_0(u(z_\varepsilon) - m) \quad \forall z \in P_{z_\varepsilon}(M_0), \quad (3.26)$$

where $C_0 = C_0(M_0)$ is independent of ε (and u).

Let C be the constant in the triangularity inequality (3.4) and choose $T = T(u, \varepsilon) > 0$ such that

$$T > 2|z_\varepsilon - 1|^2 + 2|t_\varepsilon|. \quad (3.27)$$

Then, if $z = (x, t) \in S$ with $t < -T$ and $|x|^2 < -Mt$, we have

$$\begin{aligned} |z_\varepsilon^{-1} \circ z| &\leq C(|z_\varepsilon|^{-1} + |z|) \leq C(|z_\varepsilon|^{-1} + (\sqrt{M} + 1)\sqrt{-t}) \\ &= C\sqrt{t_\varepsilon - t} \left(\frac{|z_\varepsilon^{-1}|}{\sqrt{t_\varepsilon - t}} + (\sqrt{M} + 1)\sqrt{\frac{1}{1 - |t_\varepsilon/t|}} \right) \\ &\leq C\sqrt{t_\varepsilon - t}(1 + \sqrt{2}(\sqrt{M} + 1)) =: M_0. \end{aligned} \quad (3.28)$$

Then, by (3.25) and (3.26),

$$m \leq u(z) \leq m + C_0\varepsilon \quad (3.29)$$

for every $z = (x, t) \in S$ with $t < -T$ and $|x|^2 < -Mt$. Thus

$$m \leq M(u, t) \leq m + C_0\varepsilon \quad \forall t < -T. \quad (3.30)$$

Since C_0 does not depend on ε , this completes the proof. \square

4. Some examples

In this section, we show some explicit examples of operators to which our results apply.

Example 4.1 (heat operators on Carnot groups). Let (\mathbb{R}^N, \circ) be a Lie group in \mathbb{R}^N . Assume that \mathbb{R}^N can be split as follows:

$$\mathbb{R}^N = \mathbb{R}^{N_1} \times \dots \times \mathbb{R}^{N_m} \tag{4.1}$$

and that the dilations

$$D_\lambda : \mathbb{R}^N \longrightarrow \mathbb{R}^N, \quad D_\lambda(x^{(N_1)}, \dots, x^{(N_m)}) = (\lambda x^{(N_1)}, \dots, \lambda^m x^{(N_m)})$$

$$x^{(N_i)} \in \mathbb{R}^{N_i}, \quad i = 1, \dots, m, \lambda > 0, \tag{4.2}$$

are automorphisms of (\mathbb{R}^N, \circ) .

We also assume

$$\text{rankLie} \{X_1, \dots, X_{N_1}\}(x) = N \quad \forall x \in \mathbb{R}^N, \tag{4.3}$$

where the X_j 's are left invariant on (\mathbb{R}^N, \circ) and

$$X_j(0) = \frac{\partial}{\partial x_j^{(N_1)}}, \quad j = 1, \dots, N_1. \tag{4.4}$$

Then $\mathbb{G} = (\mathbb{R}^N, \circ, \delta_\lambda)$ is a Carnot group whose homogeneous dimension Q_0 is the natural number

$$Q_0 := N_1 + 2N_2 + mN_m. \tag{4.5}$$

The vector fields X_1, \dots, X_{N_1} are the generators of \mathbb{G} ,

$$\Delta_{\mathbb{G}} := \sum_{j=1}^{N_1} X_j^2 \tag{4.6}$$

is the canonical sub-Laplacian on \mathbb{G} and the parabolic operator

$$\mathcal{L} = \Delta_{\mathbb{G}} - \partial_t \quad \text{in } \mathbb{R}^{N+1} \tag{4.7}$$

is called the canonical heat operator on \mathbb{G} . Obviously \mathcal{L} can be written as in (3.25). Moreover, if we define

$$\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \tag{4.8}$$

with $d_\lambda(x, t) = (D_\lambda x, \lambda^2 t)$ and the composition law \circ given by

$$(x, t) \circ (x', t') = (x \circ x', t + t'), \tag{4.9}$$

then \mathbb{L} is a homogeneous group, and the operator \mathcal{L} in (4.7) satisfies condition (H1)*. We explicitly remark that the homogeneous dimension of \mathbb{L} is $Q := Q_0 + 2$.

In [1, page 70], it is proved that \mathcal{L} also satisfies (H2).

Remark 4.2. The stationary part of the operator \mathcal{L} in (4.7) is the sub-Laplacian Δ_G . For this kind of operator, the polynomial Liouville theorem in Theorem 2.8 was first proved in [10, Theorem 1.4].

Example 4.3 (B-Kolmogorov operators). Let us split \mathbb{R}^N as follows:

$$\mathbb{R}^N = \mathbb{R}^p \times \mathbb{R}^r \tag{4.10}$$

and denote by $x = (x^{(p)}, x^{(r)})$ its points. Let B be an $N \times N$ real matrix taking the following block form:

$$B = \begin{pmatrix} 0 & 0 & 0 & \cdots & 0 \\ B_1 & 0 & 0 & \cdots & 0 \\ 0 & B_2 & \cdots & \cdots & \cdots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & B_k & 0 \end{pmatrix}, \tag{4.11}$$

where B_j is an $r_j \times r_{j-1}$ matrix with rank r_j , and $r_0 = p \geq r_1 \geq \cdots \geq r_k \geq 1$, $r_0 + r_1 + \cdots + r_k = N$. Denote

$$E(t) = \exp(-tB) \tag{4.12}$$

and introduce in \mathbb{R}^{N+1} the following composition law

$$(x, t) \circ (y, \tau) := (y + E(\tau)x, t + \tau). \tag{4.13}$$

The triplet

$$\mathbb{K} = (\mathbb{R}^{N+1}, \circ, d_\lambda) \tag{4.14}$$

is a homogeneous Lie group with respect to the dilations

$$d_\lambda(x, t) = d_\lambda(x^{(p)}, x^{(r_1)}, \dots, x^{(r_k)}, t) = (\lambda x^{(p)}, \lambda^3 x^{(r_1)}, \dots, \lambda^{2k+1} x^{(r_k)}, \lambda^2 t) \tag{4.15}$$

(see [11]). The homogeneous dimension of \mathbb{K} is

$$Q = p + 3r_1 + \cdots + (2k + 1)r_k + 2. \tag{4.16}$$

We call \mathbb{K} a *B-Kolmogorov-type group*.

Let us now consider the operator

$$\mathcal{H} = \Delta_{\mathbb{R}^p} + \langle Bx, D \rangle - \partial_t, \tag{4.17}$$

where $\Delta_{\mathbb{R}^p}$ denotes the usual Laplace operator in \mathbb{R}^p , $\langle \cdot, \cdot \rangle$ is the inner product in \mathbb{R}^N , and $D = (\partial_{x_1}, \dots, \partial_{x_N})$. In this case, we have

$$Y = \langle Bx, D \rangle - \partial_t. \tag{4.18}$$

The operator \mathcal{H} satisfies (H1)* and (H2), and it is left translation invariant on \mathbb{K} (see [1, 11]).

Remark 4.4. The matrix $E(t)$ in (4.13) takes the following triangular form:

$$E(t) = \begin{pmatrix} I_p & 0 \\ E_1(t) & I_r \end{pmatrix}, \quad (4.19)$$

where I_p and I_r are the identity matrix in \mathbb{R}^p and \mathbb{R}^r , respectively. Then, the composition law in \mathbb{K} has the following structure:

$$(x^{(p)}, x^{(r)}, t) \circ (y^{(p)}, y^{(r)}, \tau) = (x^{(p)} + y^{(p)}, x^{(r)} + y^{(r)} + E_1(\tau)x^{(p)}, t + \tau). \quad (4.20)$$

Remark 4.5. The stationary part of \mathcal{H} ,

$$\mathcal{H}_0 = \Delta_{\mathbb{R}^p} + \langle Bx, D \rangle, \quad (4.21)$$

is contained in the class of degenerate Ornstein-Uhlenbeck operators studied by Priola and Zabczyk [12], where a Liouville theorem for *bounded* solutions is proved.

Example 4.6 (sub-Kolmogorov operators). Let $\mathbb{G} = (\mathbb{R}^p \times \mathbb{R}^q, \circ, d_\lambda^{(1)})$ be a Carnot group with first layer \mathbb{R}^p and let $\mathbb{K} = (\mathbb{R}^p \times \mathbb{R}^r \times \mathbb{R}, \circ, d_\lambda^{(2)})$ be a Kolmogorov group. Let $\mathbb{L} = (\mathbb{R}^{N+1}, \circ, d_\lambda)$, $N = p + q + r$,

$$\mathbb{L} = \mathbb{G} \triangle \mathbb{K} \quad (4.22)$$

be the link of \mathbb{G} and \mathbb{K} (see [13, Section 5.2]).

Then, if Y is a derivative operator transverse to \mathbb{G} (see [13, Definition 4.5]), and X_1, \dots, X_p are the generators of \mathbb{G} , the operator

$$\mathcal{L} = \sum_{j=1}^p X_j^2 + Y, \quad \text{in } \mathbb{R}^{N+1}, \quad (4.23)$$

satisfies (H1)* and (H2).

Example 4.7 (a nontranslations invariant operator). The operator

$$\mathcal{L} = \partial_{x_1}^2 + x_1^{2m+1} \partial_{x_2} - \partial_t \quad \text{in } \mathbb{R}^3 \quad (4.24)$$

$m \in \mathbb{N}$, satisfies hypotheses (H1) and (H2). The relevant dilation group is given by

$$d_\lambda(x_1, x_2, t) = (\lambda x_1, \lambda^{2m+3} x_2, \lambda^2 t). \quad (4.25)$$

Finally, it is easy to recognize that there is no Lie group structure in \mathbb{R}^3 leaving left translation invariant the operator \mathcal{L} .

References

- [1] A. E. Kogoj and E. Lanconelli, “An invariant Harnack inequality for a class of hypoelliptic ultraparabolic equations,” *Mediterranean Journal of Mathematics*, vol. 1, no. 1, pp. 51–80, 2004.
- [2] A. E. Kogoj and E. Lanconelli, “One-side Liouville theorems for a class of hypoelliptic ultraparabolic equations,” in *Geometric Analysis of PDE and Several Complex Variables*, vol. 368 of *Contemporary Math.*, pp. 305–312, American Mathematical Society, Providence, RI, USA, 2005.

- [3] A. E. Kogoj and E. Lanconelli, “Liouville theorems in halfspaces for parabolic hypoelliptic equations,” *Ricerche di Matematica*, vol. 55, no. 2, pp. 267–282, 2006.
- [4] E. Lanconelli, “A polynomial one-side Liouville theorems for a class of real second order hypoelliptic operators,” *Rendiconti della Accademia Nazionale delle Scienze detta dei XL*, vol. 29, pp. 243–256, 2005.
- [5] X. Luo, “Liouville’s theorem for homogeneous differential operators,” *Communications in Partial Differential Equations*, vol. 22, no. 11-12, pp. 1837–1848, 1997.
- [6] E. Lanconelli and A. Pascucci, “Superparabolic functions related to second order hypoelliptic operators,” *Potential Analysis*, vol. 11, no. 3, pp. 303–323, 1999.
- [7] K. Amano, “Maximum principles for degenerate elliptic-parabolic operators,” *Indiana University Mathematics Journal*, vol. 28, no. 4, pp. 545–557, 1979.
- [8] R. Ja. Glagoleva, “Liouville theorems for the solution of a second order linear parabolic equation with discontinuous coefficients,” *Matematicheskie Zametki*, vol. 5, no. 5, pp. 599–606, 1969.
- [9] H. S. Bear, “Liouville theorems for heat functions,” *Communications in Partial Differential Equations*, vol. 11, no. 14, pp. 1605–1625, 1986.
- [10] A. Bonfiglioli and E. Lanconelli, “Liouville-type theorems for real sub-Laplacians,” *Manuscripta Mathematica*, vol. 105, no. 1, pp. 111–124, 2001.
- [11] E. Lanconelli and S. Polidoro, “On a class of hypoelliptic evolution operators,” *Rendiconti Seminario Matematico Università e Politecnico di Torino*, vol. 52, no. 1, pp. 29–63, 1994.
- [12] E. Priola and J. Zabczyk, “Liouville theorems for non-local operators,” *Journal of Functional Analysis*, vol. 216, no. 2, pp. 455–490, 2004.
- [13] A. E. Kogoj and E. Lanconelli, “Link of groups and applications to PDE’s,” to appear in Proceedings of the American Mathematical Society.

Alessia Elisabetta Kogoj: Dipartimento di Matematica, Università di Bologna,
 Piazza di Porta San Donato 5, 40126 Bologna, Italy
 Email address: kogoj@dm.unibo.it

Ermanno Lanconelli: Dipartimento di Matematica, Università di Bologna,
 Piazza di Porta San Donato 5, 40126 Bologna, Italy
 Email address: lanconel@dm.unibo.it