

Research Article

A Mixed Problem for Quasilinear Impulsive Hyperbolic Equations with Non Stationary Boundary and Transmission Conditions

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The initial-boundary value problem for a class of linear and nonlinear equations in Hilbert space is considered. We prove the existence and uniqueness of solution of this problem. The results of this investigation are applied to solvability of initial-boundary value problems for quasilinear impulsive hyperbolic equations with non-stationary transmission and boundary conditions.

1. Abstract Model Initial Boundary Value Problem with Non Stationary Boundary and Transmission Conditions for the Impulsive Linear Hyperbolic Equations

In paper [1] there is given an abstract scheme of investigation of mixed problems for hyperbolic equations with non stationary boundary conditions. In this direction, some results were obtained in [2].

In this paper, we offer the analogous abstract model of investigation of mixed problem with non stationary boundary and transmission conditions for impulsive linear and semilinear hyperbolic equations.

1.1. Statement of the Problem and Main Theorem

Let $H^i, H_0^i, X_\nu^i, Y_\mu^j$ ($\nu = 1, 2, \dots, s; i = 1, 2, \dots, m; \mu = 1, 2, \dots, r; j = 1, 2, \dots, m$) be Hilbert Spaces. Consider the following abstract initial-boundary value problem:

$$\ddot{u}_i(t) + A_i(t)u_i(t) = f_i(t), \quad (\text{hyperbolic equations}), \quad (1.1)$$

$$B_{iv}\ddot{u}_i(t) + \sum_{k=1}^m C_{kv}^i(t)u_k(t) = g_{iv}(t), \quad (\text{non stationary boundary and transmission conditions}),$$

$$\sum_{k=1}^m D_{k\mu}^i u_k(t) = 0, \quad (\text{stationary boundary and transmission conditions}),$$

$$u_i(0) = u_i^0, \quad \dot{u}_i(0) = u_i^1, \quad (\text{initial conditions}), \quad (1.2)$$

where $t \in [0, T]$, $\ddot{u}_i = d^2u_i/dt^2$, $\dot{u}_i = du_i/dt$, $A_i(t)$ are the linear closed operators in H^i ; B_{iv} are the linear operators from H^i to X_ν^i ; $C_{kv}^i(t)$ are the linear operators from H^k to X_ν^i ; $D_{k\mu}^j$ are the linear operators from H^k to Y_μ^j ; $\nu = 1, \dots, s_i$, $i = 1, \dots, m$, $\mu = 1, \dots, r_j$, $j = 1, \dots, m$, $k = 1, \dots, m$.

We will investigate this problem under the following conditions.

- (i) Let $H_0^i \subset H^i$, and let H_0^i be densely in H^i and continuously imbedded into it, $i = 1, 2, \dots, m$.

In the Hilbert space H^i , it was defined the system of the inner products $(\cdot, \cdot)_{H^i(t)}$, which generate uniform equivalent norms, that is,

$$\begin{aligned} c_1^{-1} \|u\|_{H^i}^2 &\leq \|u\|_{H^i(t)}^2 \leq c_1 \|u\|_{H^i}^2, \quad c_1 > 0, \\ \|u\|_{H^i(t)}^2 &= (u, u)_{H^i(t)}, \quad t \in [0, T], \quad i = 1, 2, \dots, m. \end{aligned} \quad (1.3)$$

For each $u \in H^i$, the function $t \rightarrow \|u\|_{H^i(t)}^2 : [0, T] \rightarrow R_+$ is continuously differentiable, $i = 1, 2, \dots, m$.

In the Hilbert space X_ν^i , it was defined the system of the inner products $(\cdot, \cdot)_{X_\nu^i(t)}$, which generate uniform equivalent norms, that is,

$$\begin{aligned} c_2^{-1} \|v\|_{X_\nu^i}^2 &\leq \|v\|_{X_\nu^i(t)}^2 \leq c_2 \|v\|_{X_\nu^i}^2, \quad c_2 > 0, \\ \|v\|_{X_\nu^i(t)}^2 &= (v, v)_{X_\nu^i(t)}, \quad t \in [0, T], \quad \nu = 1, 2, \dots, s_i, \quad i = 1, 2, \dots, m. \end{aligned} \quad (1.4)$$

For each $v \in X_\nu^i$, the function $t \rightarrow \|v\|_{X_\nu^i(t)}^2 : [0, T] \rightarrow R_+$ is continuously differentiable.

- (ii) For each $t \in [0, T]$ and $i = 1, 2, \dots, m$, $A_i(t)$ is a linear closed operator in H^i whose domain is H_0^i ; $A_i(t)$ acts boundedly from H_0^i to H^i ; $A_i(t)$ is strongly continuously differentiable.
- (iii) The linear operators B_{iv} , that act from $H_{1/2}^i$ to X_ν^i , bounded, where $H_{1/2}^i = [H_0^i, H^i]_{1/2}$ is interpolation space between H_0^i and H^i of order $1/2$ ($\nu = 1, \dots, s_i$, $i = 1, \dots, m$) (see [3]).
- (iv) For each $t \in [0, T]$, the linear operators $C_{kv}^i(t)$, that act from H^k to X_ν^i , are bounded; $C_{kv}^i(t)$ is strongly continuously differentiable ($\nu = 1, \dots, s_i$, $i = 1, \dots, m$; $k = 1, \dots, m$).

- (v) The linear operators $D_{k\mu}^j$ from $H_{1/2}^k$ into Y_{μ}^j act boundedly ($\mu = 1, \dots, r_j, j = 1, \dots, m; k = 1, \dots, m$).

Let us introduce the following designations:

$$\begin{aligned} \widehat{H} &= H^1 \oplus \dots \oplus H^m, \\ \widehat{H}_0 &= \left\{ \bar{u} : \bar{u} = (u_1, \dots, u_m), u_i \in H_0^i, i = 1, \dots, m; \right. \\ &\quad \left. \sum_{k=1}^m D_{k\mu}^j u_k = 0, \mu = 1, \dots, r_j, j = 1, \dots, m \right\}, \\ \widehat{H}_{1/2} &= \left\{ \bar{u} : \bar{u} = (u_1, \dots, u_m), u_i \in H_{1/2}^i, i = 1, \dots, m; \right. \\ &\quad \left. \sum_{k=1}^m D_{k\mu}^j u_k = 0, \mu = 1, \dots, r_j, j = 1, \dots, m \right\}, \\ \mathcal{L}_1 &= \left\{ w : w = (w_1, \dots, w_m), w_i = (u_i, B_{i1}u_i, \dots, B_{is_i}u_i), i = 1, \dots, m, \right. \\ &\quad \left. \text{where } (u_1, \dots, u_m) \in \widehat{H}_0 \right\}, \\ \mathcal{L}^i &= H^i \oplus X_1^i \oplus \dots \oplus X_{s_i}^i, \quad \mathcal{L} = \bigoplus_{i=1}^m \mathcal{L}^i, \quad \mathcal{L}_{1/2} = [\mathcal{L}_1, \mathcal{L}]_{1/2}. \end{aligned} \tag{1.5}$$

From condition (v), it follows that the space $\widehat{H}_{1/2}$ with the norm

$$\|\bar{u}\|_{\widehat{H}_{1/2}} = \sum_{i=1}^m \|u_i\|_{H_{1/2}^i} \tag{1.6}$$

is a subspace of

$$H_{1/2} = \left\{ \bar{u} : \bar{u} = (u_1, \dots, u_m), u_i \in H_{1/2}^i, i = 1, \dots, m \right\} = H_{1/2}^1 \times \dots \times H_{1/2}^m. \tag{1.7}$$

- (vi) Let the linear manifold \widehat{H}_0 be dense in $\widehat{H}_{1/2}$, and let linear manifold \mathcal{L}_1 be dense in \mathcal{L} .
- (vii) (Green's Identity). For arbitrary $\bar{u}, \bar{v} \in \widehat{H}_0$ and $t \in [0, T]$, the following identity is valid:

$$\begin{aligned} &\sum_{i=1}^m \left[(A_i(t)u_i, v_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} \left(\sum_{k=1}^m C_{k\nu}^i(t)u_k, B_{i\nu}v_i \right)_{X_{\nu}^i(t)} \right] \\ &= \sum_{i=1}^m \left[(u_i, A_i(t)v_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} \left(B_{i\nu}u_i, \sum_{k=1}^m C_{k\nu}^i(t)v_k \right)_{X_{\nu}^i(t)} \right]. \end{aligned} \tag{1.8}$$

(viii) For all $\bar{u} = (u_1, \dots, u_m) \in \widehat{H}_0$, the following inequality is fulfilled:

$$\begin{aligned} & c_1 \sum_{i=1}^m \left(\|u_i\|_{H^i}^2 + \sum_{\nu=1}^{s_i} \|B_{i\nu} u_i\|_{X_\nu^i}^2 \right) \\ & \leq \sum_{i=1}^m \left[(A_i(t)u_i, u_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} \left(\sum_{k=1}^m C_{k\nu}^i(t) u_k, B_{i\nu} u_i \right)_{X_\nu^i(t)} \right] \leq c_2 \sum_{i=1}^m \|u_i\|_{H_{1/2}^i}^2, \end{aligned} \quad (1.9)$$

where $c_1 \in \mathbb{R}, c_2 > 0$.

(ix) For each $t \in [0, T]$, an operator pencil

$$\begin{aligned} \mathcal{L}^t(\lambda) : \bar{u} = (u_1, \dots, u_m) & \longrightarrow \mathcal{L}^t(\lambda)\bar{u} \\ & = \left(L_{i0}^t(\lambda)\bar{u}, L_{11}^t(\lambda)\bar{u}, \dots, L_{1s_1}^t(\lambda)\bar{u}, \dots, L_{m0}^t(\lambda)\bar{u}, L_{m1}^t(\lambda)\bar{u}, \dots, L_{ms_m}^t(\lambda)\bar{u} \right), \end{aligned} \quad (1.10)$$

which acts boundedly from \widehat{H}_0 to \mathcal{L} , has a regular point $\lambda = \lambda_0 \in \mathbb{R}$, where

$$\begin{aligned} L_{i0}^t(\lambda)\bar{u} &= \lambda u_i + A_i(t)u_i, \quad i = 1, 2, \dots, m, \\ L_{i\nu}^t(\lambda)\bar{u} &= \lambda B_{i\nu} u_i + \sum_{k=1}^m C_{k\nu}^i(t) u_k, \quad \nu = 1, 2, \dots, s_i, \quad i = 1, 2, \dots, m. \end{aligned} \quad (1.11)$$

$$(x) \quad u_i^0 \in H_0^i, u_i^1 \in H_{1/2}^i, \sum_{k=1}^m D_{k\mu}^j u_k^0 = 0, \sum_{k=1}^m D_{k\mu}^j u_k^1 = 0$$

$$(i = 1, 2, \dots, m, \mu = 1, 2, \dots, r_j, j = 1, 2, \dots, m). \quad (1.12)$$

$$(xi) \quad f_i(\cdot) \in W_p^1(0, T; H^i), \quad p \geq 1, \quad i = 1, \dots, m,$$

$$g_{i\nu}(\cdot) \in W_p^1(0, T; X_\nu^i), \quad p \geq 1, \quad \nu = 1, \dots, s_i, \quad i = 1, \dots, m. \quad (1.13)$$

Definition 1.1. The function $t \rightarrow (u_1(t), \dots, u_m(t))$ is called a solution of problem (1.1)-(1.2) if the function $t \rightarrow \bar{u}(t) = (u_1(t), \dots, u_m(t))$ from $[0, T]$ to \widehat{H}_0 is continuous, and the function

$$t \longrightarrow (u_1(t), B_{11}u_1(t), \dots, B_{1s_1}u_1(t), \dots, u_m(t), B_{m1}u_m(t), \dots, B_{ms_m}u_m(t)) \quad (1.14)$$

from $[0, T]$ to \mathcal{L} is twice continuously differentiable and (1.1)-(1.2) are satisfied.

Theorem 1.2. Let conditions (i)-(xi) are satisfied, then the problem (1.1)-(1.2) has a unique solution.

Proof. We define the operator $\mathcal{A}(t)$ in the Hilbert space \mathcal{H} in the following way:

$$D(\mathcal{A}(t)) = \mathcal{H}_1,$$

$$\mathcal{A}(t)w = \left(A_1(t)u_1, \sum_{k=1}^m C_{k1}^1(t)u_k, \dots, \sum_{k=1}^m C_{ks_1}^1(t)u_k, \dots, A(t)_m u_m, \right. \\ \left. \sum_{k=1}^m C_{k1}^m(t)u_k, \dots, \sum_{k=1}^m C_{ks_m}^m(t)u_k \right), \quad t \in [0, T], w \in \mathcal{H}_1. \tag{1.15}$$

Then the problem (1.1)-(1.2) is represented as the Cauchy problem

$$\ddot{w} + \mathcal{A}(t)w = \Phi(t), \tag{1.16}$$

$$w(0) = w^0, \quad \dot{w}(0) = w^1,$$

where $w(t) = (u_1(t), B_{11}u_1(t), \dots, B_{1s_1}u_1(t), \dots, u_m(t), B_{m1}u_m(t), \dots, B_{ms_m}u_m(t))$,

$$\Phi(t) = (f_1(t), g_{11}(t), \dots, g_{1s_1}(t), \dots, f_m(t), g_{m1}(t), \dots, g_{ms_m}(t)),$$

$$w^0 = (u_1^0, B_{11}u_1^0, \dots, B_{1s_1}u_1^0, \dots, u_m^0, B_{m1}u_m^0, \dots, B_{ms_m}u_m^0), \tag{1.17}$$

$$w^1 = (u_1^1, B_{11}u_1^1, \dots, B_{1s_1}u_1^1, \dots, u_m^1, B_{m1}u_m^1, \dots, B_{ms_m}u_m^1).$$

It is obvious that if $(u_1(t), \dots, u_m(t))$ is the solution of problem (1.1)-(1.2), then $w(t)$ is the solution of the problem (1.16). On the contrary, if

$$w(t) \in C^2([0, T]; \mathcal{H}) \cap C^1([0, T]; [\mathcal{H}_1, \mathcal{H}]_{1/2}) \cap C([0, T]; \mathcal{H}_1) \tag{1.18}$$

is the solution of problem (1.16), then $w(t) = (u_1(t), B_{11}u_1(t), \dots, B_{1s_1}u_1(t), \dots, u_m(t), B_{m1}u_m(t), \dots, B_{ms_m}u_m(t))$ and $(u_1(t), \dots, u_m(t))$ is the solution of problem (1.1)-(1.2).

Let us define the system of inner product in Hilbert space \mathcal{H} in the following way:

$$(w^1, w^2)_{\mathcal{H}(t)} = \sum_{i=1}^m (w_i^1, w_i^2)_{H^i(t)} + \sum_{i=1}^m \sum_{\nu=1}^{s_i} (B_{i\nu}u_i^1, B_{i\nu}u_i^2)_{X_{\nu}^i(t)}, \quad t \in [0, T], \tag{1.19}$$

where $w^l = (w_1^l, \dots, w_m^l)$, $w_i^l = (u_i^l, B_{i1}u_i^l, \dots, B_{is_i}u_i^l)$, $i = 1, 2, \dots, m, (u_1^l, \dots, u_m^l) \in \widehat{H}_0, l = 1, 2$.

We denote space \mathcal{H} with inner product (1.19) by $\mathcal{H}(t)$. □

We will prove later the following auxiliary results.

Statement 1.3. There exists such $c_3 > 0$, that

$$c_3^{-1} \|w\|_{\mathcal{H}}^2 \leq \|w\|_{\mathcal{H}(t)}^2 \leq c_3 \|w\|_{\mathcal{H}}^2, \quad t \in [0, T], \tag{1.20}$$

and the function $t \rightarrow \|w\|_{\mathcal{H}(t)}^2 : [0, T] \rightarrow R_+$ is continuously differentiable, where $\|w\|_{\mathcal{H}(t)}^2 = (w, w)_{\mathcal{H}(t)}$.

Statement 1.4. $\mathcal{A}(t)$ is a symmetric operator in $\mathcal{H}(t)$ for each $t \in [0, T]$.

Statement 1.5. $\mathcal{A}(t)$ has a regular point for each $t \in [0, T]$ in R .

$\mathcal{A}(t)$ is symmetric and $R(\mathcal{A}(t) + \lambda I) = \mathcal{H}(t)$, for some $\lambda \in R$; therefore, for each $t \in [0, T]$, $\mathcal{A}(t)$ is a selfadjoint operator in $\mathcal{H}(t)$ (see [4, chapter x]).

Taking into account (viii) and Statement 1.3, we get

$$\begin{aligned} (\mathcal{A}(t)w, w)_{\mathcal{H}(t)} &= \sum_{i=1}^m \left[(A_i(t)u_i, u_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} \left(\sum_{k=1}^m C_{k\nu}^i(t)u_k, B_{i\nu}u_i \right)_{X_\nu^i(t)} \right] \\ &\geq c_1 \|w\|_{\mathcal{H}(t)}^2, \end{aligned} \quad (1.21)$$

that is, $\mathcal{A}(t)$ is a lower semibounded selfadjoint operator in $\mathcal{H}(t)$.

Thus, the operator $\mathcal{A}_0(t) = \mathcal{A}(t) + \lambda_0 I$ is selfadjoint and positive definite, where $\lambda_0 > c_1$. Problem (1.16) can be rewritten as

$$\begin{aligned} \ddot{w}(t) + \mathcal{A}_0(t)w(t) - \lambda_0 w(t) &= \mathcal{F}(t), \\ w(0) = w^0, \quad \dot{w}(0) &= w^1. \end{aligned} \quad (1.22)$$

It is known that if $w^0 \in \mathcal{H}_1$ and $w^1 \in \mathcal{H}_{1/2}$, then the problem (1.22) has a unique solution $w \in C^2([0, T]; \mathcal{H}) \cap C^1([0, T]; \mathcal{H}_{1/2}) \cap C([0, T]; \mathcal{H}_1)$ (see [5, 6]).

To complete the proof of the theorem, we need to show that $w^0 \in \mathcal{H}_1$ and $w^1 \in \mathcal{H}_{1/2}$.

By conditions of the theorem $u_i^0 \in H_0^i$, $\sum_{k=1}^m D_{k\mu}^j u_k^0 = 0$ ($i = 1, 2, \dots, m$; $\mu = 1, 2, \dots, r_j$, $j = 1, 2, \dots, m$) and $B_{i\nu}$ are bounded operators from $H_{1/2}^i$ to X_ν^i , $\nu = 1, 2, \dots, s_i$, $i = 1, 2, \dots, m$. Therefore,

$$w^0 = \left(u_1^0, B_{11}u_1^0, \dots, B_{1s_1}u_1^0, \dots, u_m^0, B_{m1}u_m^0, \dots, B_{ms_m}u_m^0 \right) \in \mathcal{H}_1. \quad (1.23)$$

On the other hand, $u_i^1 \in H_{1/2}^i$ and $\sum_{k=1}^m D_{k\mu}^j u_k^1 = 0$ ($i = 1, 2, \dots, m$, $\mu = 1, 2, \dots, r_j$, $j = 1, 2, \dots, m$), therefore, $B_{i\nu}u_i^1 \in X_\nu^i$ ($\nu = 1, 2, \dots, s_i$, $i = 1, 2, \dots, m$). Consequently,

$$\begin{aligned} w^1 &= \left(u_1^1, B_{11}u_1^1, \dots, B_{1s_1}u_1^1, \dots, u_m^1, B_{m1}u_m^1, \dots, B_{ms_m}u_m^1 \right) \in \mathcal{J}, \\ \mathcal{J} &= \left\{ w : w = (w_1, \dots, w_m), w_i = (u_i, B_{i1}u_i, \dots, B_{is_i}u_i), u_i \in H_{1/2}^i, \right. \\ &\quad \left. \sum_{k=1}^m D_{k\mu}^j u_k = 0, i = 1, \dots, m, \mu = 1, \dots, r_j, j = 1, \dots, m \right\}. \end{aligned} \quad (1.24)$$

From the definition of interpolation spaces (see [3, chapter 1], [7, chapter 1]), we get the following inclusion:

$$\mathcal{L}_1 \subset \mathcal{L}_{1/2} \subset \widetilde{\mathcal{L}}_{1/2} = \bigoplus_{i=1}^m \left(H_{1/2}^i \oplus X_1^i \oplus \dots \oplus X_{s_i}^i \right). \tag{1.25}$$

By virtue of definition, the powers of positive selfadjoint operator (see [8, chapter 2], [7, chapter 1]), we have that $D(\mathcal{A}_0^{1/2}(t)) = \mathcal{L}_{1/2}$ and

$$c^{-1} \|w\|_{\mathcal{L}_{1/2}} \leq \left\| \mathcal{A}_0^{1/2}(t)w \right\|_{\mathcal{L}(t)} \leq c \|w\|_{\mathcal{L}_{1/2}}, \quad c > 0. \tag{1.26}$$

Assume that $w \in D(\mathcal{A}_0) = \mathcal{L}_1$, then

$$\begin{aligned} \left\| \mathcal{A}_0^{1/2}(t)w \right\|_{\mathcal{L}(t)}^2 &= (\mathcal{A}_0(t)w, w)_{\mathcal{L}(t)} \\ &= \sum_{i=1}^m \left[(A_i(t)u_i, u_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} \left(\sum_{k=1}^m C_{k\nu}^i(t)u_k, B_{i\nu}u_i \right)_{X_\nu^i(t)} \right] \\ &\quad + \lambda_0 \sum_{i=1}^m \left[(u_i, u_i)_{H^i(t)} + \sum_{\nu=1}^{s_i} (B_{i\nu}u_i, B_{i\nu}u_i)_{X_\nu^i(t)} \right]. \end{aligned} \tag{1.27}$$

By virtue of conditions (ii), (viii), (1.26), and (1.27), we get

$$\|w\|_{\mathcal{L}_{1/2}}^2 \leq c \sum_{i=1}^m \|u_i\|_{H_{1/2}^i}^2. \tag{1.28}$$

Let $w^1 \in \mathcal{D}$. By virtue of condition (vi), \widehat{H}_0 is dense in $\widehat{H}_{1/2}$; therefore, there exists a sequence $\overline{u}^{(p)} = (u_1^{(p)}, \dots, u_m^{(p)})$, such that $\overline{u}^{(p)} \in \widehat{H}_0$ and

$$\left\| \overline{u}^{(p)} - \overline{u}^1 \right\|_{H_{1/2}^1 \oplus \dots \oplus H_{1/2}^m} \longrightarrow 0, \quad \text{at } p \longrightarrow \infty. \tag{1.29}$$

Hence it follows, that

$$\left\| \overline{u}^{(p)} - \overline{u}^{(q)} \right\|_{H_{1/2}^1 \oplus \dots \oplus H_{1/2}^m} \longrightarrow 0 \quad \text{at } p, q \longrightarrow \infty. \tag{1.30}$$

Then from (1.28) and (1.30) it follows that $\{w^{(p)}\}$ is fundamental in $\mathcal{L}_{1/2}$, that is,

$$\left\| w^{(p)} - w^{(q)} \right\|_{\mathcal{L}_{1/2}} \longrightarrow 0, \quad \text{at } p, q \longrightarrow \infty, \tag{1.31}$$

where $w^{(p)} = (u_1^{(p)}, B_{11}u_1^{(p)}, \dots, B_{1s_1}u_1^{(p)}, \dots, u_m^{(p)}, B_{m1}u_m^{(p)}, \dots, B_{ms_m}u_m^{(p)})$, $p = 1, 2, \dots$

Thus, there exists $\tilde{w} \in \mathcal{H}_{1/2}$ such that

$$\|w^{(p)} - \tilde{w}\|_{\mathcal{H}_{1/2}} \rightarrow 0, \quad \text{at } p \rightarrow \infty. \quad (1.32)$$

On the other hand, $\mathcal{H}_{1/2} \subset \widetilde{\mathcal{H}}_{1/2}$, therefore,

$$\|w^{(p)} - \tilde{w}\|_{\widetilde{\mathcal{H}}_{1/2}} \rightarrow 0, \quad \text{at } p \rightarrow \infty. \quad (1.33)$$

Hence,

$$\|\bar{u}^{(p)} - \bar{u}\|_{H_{1/2}^1 \oplus \dots \oplus H_{1/2}^m} \rightarrow 0, \quad \text{at } p \rightarrow \infty, \quad (1.34)$$

where $\bar{u} = (\tilde{u}_1, \dots, \tilde{u}_m)$. From this, by virtue of (1.29), $\bar{u} = \bar{u}^1$, that is,

$$\tilde{w} = \left(u_1^1, B_{11}u_1^1, \dots, B_{1s_1}u_1^1, \dots, u_m^1, B_{m1}u_m^1, \dots, B_{ms_m}u_m^1 \right) = w^1. \quad (1.35)$$

Thus, $w^1 \in \mathcal{H}_{1/2}$. The theorem is proved.

1.2. Proof of Auxiliary Results

Validity of Statement 1.3 follows from condition (i), the Statement 1.4 from condition (vii).

Proof of Statement 3. Consider in Hilbert space \mathcal{H} the equation

$$\lambda w + \mathcal{A}(t)w = \mathcal{F}, \quad t \in [0, T], \quad (1.36)$$

where $\mathcal{F} = (f_1, f_{11}, \dots, f_{1s_1}, \dots, f_m, f_{m1}, \dots, f_{ms_m}) \in \mathcal{H}$, $\lambda \in \mathbb{R}$.

Equation (1.36) is equivalent to the following system of differential-operator equations:

$$\begin{aligned} L_{i0}^t(\lambda)\bar{u} &= \lambda u_i + A_i(t)u_i = f_i, \quad t \in [0, T], \quad i = 1, 2, \dots, m, \\ L_{i\nu}^t(\lambda)\bar{u} &= \lambda B_{i\nu}u_i + \sum_{k=1}^m C_{k\nu}^i(t)u_k = g_{i\nu}, \quad t \in [0, T], \quad \nu = 1, 2, \dots, s_i, \quad i = 1, 2, \dots, m, \\ \sum_{k=1}^m D_{k\mu}^j u_k &= 0, \quad \mu = 1, 2, \dots, r_j, \quad j = 1, 2, \dots, m. \end{aligned} \quad (1.37)$$

By virtue of (ix), problem (1.37) has a solution $\bar{u} = (u_1, \dots, u_m) \in \widehat{H}_0$ for some $\lambda \in \mathbb{R}$. Thus, for each $t \in [0, T]$,

$$R(\lambda I + \mathcal{A}(t)) = \mathcal{H}(t), \quad (1.38)$$

where I is an identity operator in $\mathcal{H}(t)$, that is, \mathcal{A} has a regular point. \square

2. Abstract Model of Initial Boundary Value Problem with Non Stationary Boundary and Transmission Conditions for the Impulsive Semilinear Hyperbolic Equations

Consider the following initial boundary value problem:

$$\begin{aligned} \dot{u}_i(t) + A_i(t)u_i(t) &= f_i\left(t, \bar{u}(t), \vec{u}(t)\right), \\ B_{iv}\dot{u}_i(t) + \sum_{k=1}^m C_{kv}^i(t)u_k(t) &= g_{iv}\left(t, \bar{u}(t), \vec{u}(t)\right), \\ \sum_{k=1}^m D_{k\mu}^i u_k(t) &= 0, \\ u_i(0) &= u_i^0, \quad \dot{u}_i(0) = u_i^1, \end{aligned} \tag{2.1}$$

where $t \in [0, T]$, $v = 1, \dots, s_i$, $\mu = 1, \dots, r_i$, $i = 1, \dots, m$, $\bar{u} = (u_1, \dots, u_m)$, $\vec{u} = (\dot{u}_1, \dots, \dot{u}_m)$, $A_i(t)$, B_{iv} , $C_{kv}^i(t)$ and $D_{k\mu}^i$ satisfy all conditions of Theorem 1.2.

Assume, that the nonlinear operators f_i and g_{iv} satisfy the following conditions.

(xi') Suppose that the nonlinear operators

$$\begin{aligned} (t, \bar{u}, \vec{u}) &\longrightarrow f_i(t, \bar{u}, \vec{u}) : [0, T] \times \left(\bigoplus_{i=1}^m H_{1/2}^i\right) \times \left(\bigoplus_{i=1}^m H^i\right) \longrightarrow H^i, \\ (t, \bar{u}, \vec{u}) &\longrightarrow g_{iv}(t, \bar{u}, \vec{u}) : [0, T] \times \left(\bigoplus_{i=1}^m H_{1/2}^i\right) \times \left(\bigoplus_{i=1}^m H^i\right) \longrightarrow X_v^i \end{aligned} \tag{2.2}$$

satisfy the local Lipschitz conditions in the following sense: for arbitrary $t_1, t_2 \in [0, T]$, $(\bar{u}^1, \vec{v}^1), (\bar{u}^2, \vec{v}^2) \in \widehat{H}_{1/2} \times \widehat{H}$,

$$\begin{aligned} &\|f_i(t_1, \bar{u}^1, \vec{v}^1) - f_i(t_2, \bar{u}^2, \vec{v}^2)\|_{H^i} \\ &\leq c_i(r) \left[|t_1 - t_2| + \sum_{i=1}^m \left(\|u_i^1 - u_i^2\|_{H_{1/2}^i} + \|v_i^1 - v_i^2\|_{H^i} \right) \right], \\ &\|g_{iv}(t_1, \bar{u}^1, \vec{v}^1) - g_{iv}(t_2, \bar{u}^2, \vec{v}^2)\|_{X_v^i} \\ &\leq c_{iv}(r) \left[|t_1 - t_2| + \sum_{i=1}^m \left(\|u_i^1 - u_i^2\|_{H_{1/2}^i} + \|v_i^1 - v_i^2\|_{H^i} \right) \right], \end{aligned} \tag{2.3}$$

where $c_i(\cdot), c_{iv} \in C(R_+, R_+)$, $v = 1, \dots, s_i$, $i = 1, \dots, m$,

$$r = \sum_{i=1}^m \sum_{l=1}^2 \left(\|u_i^l\|_{H_{1/2}^i} + \|v_i^l\|_{H^i} \right). \tag{2.4}$$

Theorem 2.1. *Let conditions (i)–(x) and (xi') be satisfied, then there exists $T' \in (0, T]$, such that the problem (2.1) has a unique solution*

$$\bar{u} = (u_1, \dots, u_m) \in C([0, T'], \widehat{H}_0) \cap C^1([0, T'], \widehat{H}_{1/2}) \cap C^2([0, T'], \widehat{H}). \quad (2.5)$$

Additionally, if

$$E(t) = \sum_{i=1}^m \left[\|u_i(t)\|_{H_{1/2}^i} + \|\dot{u}_i(t)\|_{H^i} \right] \leq \varphi \left(\sum_{i=1}^m \left[\|u_i^0\|_{H_{1/2}^i} + \|u_i^1\|_{H^i} \right] \right), \quad t \in [0, T'), \quad (2.6)$$

where $\varphi(\cdot) \in C(\mathbb{R}_+, \mathbb{R}_+)$, then $T' = T$. Otherwise, there exists $T_0 \in (0, T)$, such that

$$\lim_{t \rightarrow T_0^-} E(t) = +\infty. \quad (2.7)$$

In the Hilbert space \mathcal{L} , the problem (2.1) is represented as the Cauchy problem

$$\begin{aligned} \ddot{w} + \mathcal{A}_0(t)w &= \mathcal{F}(t, w, \dot{w}), \\ w(0) &= w^0, \quad \dot{w}(0) = w^1, \end{aligned} \quad (2.8)$$

where $w = (u_1, B_{11}u_1, \dots, B_{1s_1}u_1, \dots, u_m, B_{m1}u_m, \dots, B_{ms_m}u_m)$,

$$\begin{aligned} w^0 &= (u_1^0, B_{11}u_1^0, \dots, B_{1s_1}u_1^0, \dots, u_m^0, B_{m1}u_m^0, \dots, B_{ms_m}u_m^0), \\ w^1 &= (u_1^1, B_{11}u_1^1, \dots, B_{1s_1}u_1^1, \dots, u_m^1, B_{m1}u_m^1, \dots, B_{ms_m}u_m^1), \\ \mathcal{F}(t, w, \dot{w}) &= \lambda_0 w + \mathcal{F}_1(t, w, \dot{w}), \\ \mathcal{F}_1(t, w, \dot{w}) &= (f_1(t, \bar{u}, \dot{\bar{u}}), g_{11}(t, \bar{u}, \dot{\bar{u}}), \dots, g_{1s_1}(t, \bar{u}, \dot{\bar{u}}), \dots, \\ & \quad f_m(t, \bar{u}, \dot{\bar{u}}), g_{m1}(t, \bar{u}, \dot{\bar{u}}), \dots, g_{ms_m}(t, \bar{u}, \dot{\bar{u}})). \end{aligned} \quad (2.9)$$

From (xi'), it follows that, for arbitrary $t_1, t_2 \in [0, T]$, $w^1, w^2 \in \mathcal{L}_{1/2}$, $z^1, z^2 \in \mathcal{L}$,

$$\left\| \mathcal{F}(t_1, w^1, z^1) - \mathcal{F}(t_2, w^2, z^2) \right\|_{\mathcal{L}} \leq c(r) \left[|t_1 - t_2| + \|w^1 - w^2\|_{\mathcal{L}_{1/2}} + \|z^1 - z^2\|_{\mathcal{L}} \right], \quad (2.10)$$

where $c(\cdot) \in C(\mathbb{R}_+, \mathbb{R}_+)$, $r = \sum_{l=1}^2 (\|w^l\|_{\mathcal{L}_{1/2}} + \|z^l\|_{\mathcal{L}})$.

Thus, the nonlinear operator \mathcal{F} satisfies the condition of local solvability of the Cauchy problem for the quasilinear hyperbolic equations in Hilbert space (see [6, 9]). Taking this into account, the problem (2.8) has a unique solution

$$w \in C^2([0, T']; \mathcal{H}) \cap C^1([0, T']; \mathcal{H}_{1/2}) \cap C([0, T']; \mathcal{H}_1). \tag{2.11}$$

3. Initial Boundary Value Problem with Non Stationary Boundary and Transmission Condition for the Impulsive Semilinear Hyperbolic Equations

Let $a_1 < a_2 < \dots < a_{m+1}$. We consider in the domain $[0, T] \times \bigcup_{i=1}^m [a_i, a_{i+1}]$ the following mixed problem

$$\begin{aligned} \ddot{u}_i(t, x) - p_i(t)u_i''(t, x) &= f_i\left(t, x, u_i(t, x), u_i'(t, x), \dot{u}_i(t, x), \varphi_i\left(\bar{u}, \ddot{u}\right)\right), \\ (t, x) &\in [0, T] \times [a_i, a_{i+1}], \quad i = 1, 2, \dots, m, \\ u_i(t, a_{i+1}) &= u_{i+1}(t, a_{i+1}), \quad i = 1, 2, \dots, m - 1, t > 0, \\ \dot{u}_1(t, a_1) - q_0(t)u_1'(t, a_1) &= g_0\left(t, \varphi_0\left(\bar{u}, \ddot{u}\right)\right), \quad t > 0, \\ \ddot{u}_i(t, a_{i+1}) + q_i(t)[u_i'(t, a_{i+1}) - u_{i+1}'(t, a_{i+1})] &= g_i\left(t, \varphi_i\left(\bar{u}, \ddot{u}\right)\right), \\ i &= 1, 2, \dots, m - 1, t > 0, \\ \ddot{u}_m(t, a_{m+1}) + q_m(t)u_m'(t, a_{m+1}) &= g_m\left(t, \varphi_m\left(\bar{u}, \ddot{u}\right)\right), \quad t > 0, \\ u_i(0, x) = u_i^0(x), \quad \dot{u}_i(0, x) = u_i^1(x), \quad x &\in [a_i, b_i], \quad i = 1, 2, \dots, m, \end{aligned} \tag{3.1}$$

where $\dot{u}_i = \partial u_i / \partial t, u_i' = \partial u_i / \partial x, \ddot{u}_i = \partial^2 u_i / \partial t^2, u_i'' = \partial^2 u_i / \partial x^2, \bar{u} = (u_1, \dots, u_m), \ddot{u} = (\ddot{u}_1, \dots, \ddot{u}_m), p_i, q_j, f_i, g_j, u_i^0, u_i^1$ are some functions, φ_i and φ_j are some functionals, which will be specified below, $i = 1, \dots, m, j = 0, 1, \dots, m$.

Recently, differential equations with impulses are great interest because of the needs of modern technology, where impulsive automatic control systems and impulsive computing systems are very important and intensively develop broadening the scope of their applications in technical problems, heterogeneous by their physical nature and functional purpose (see [10, chapter 1]).

Assume that the following conditions are held:

- (1⁰) $p_i(t) \in C^1[0, T], q_j(t) \in C^1[0, T]; p_i(t) > 0, q_j(t) > 0, t \in [0, T], i = 1, \dots, m, j = 0, 1, \dots, m,$
- (2⁰) $f_i(\cdot) \in C^1([0, T] \times [a_i, a_{i+1}] \times R^4), i = 1, 2, \dots, m,$
- (3⁰) $g_j(\cdot) \in C^1([0, T], R), j = 0, 1, \dots, m,$

(4⁰) $\varphi_i(\cdot)$ are nonlinear functionals acting from

$$\bigoplus_{k=1}^m \left(W_2^1(a_k, a_{k+1}) \times L_2(a_k, a_{k+1}) \right) \quad (3.2)$$

to R and for arbitrary $(\bar{u}^1, \bar{v}^1), (\bar{u}^2, \bar{v}^2) \in \bigoplus_{k=1}^m (W_2^1(a_k, a_{k+1}) \times L_2(a_k, a_{k+1}))$ the following inequality holds

$$\begin{aligned} & \left| \varphi_i(\bar{u}^1, \bar{v}^1) - \varphi_i(\bar{u}^2, \bar{v}^2) \right| \\ & \leq c_i(r) \sum_{k=1}^m \left[\left\| u_k^1 - u_k^2 \right\|_{W_2^1(a_k, a_{k+1})} + \left\| v_k^1 - v_k^2 \right\|_{L_2(a_k, a_{k+1})} \right], \quad (3.3) \\ & \qquad \qquad \qquad i = 1, 2, \dots, m, \end{aligned}$$

where $r = \sum_{k=1}^m [\|u_k^1\|_{W_2^1(a_k, a_{k+1})} + \|u_k^2\|_{W_2^1(a_k, a_{k+1})} + \|v_k^1\|_{L_2(a_k, a_{k+1})} + \|v_k^2\|_{L_2(a_k, a_{k+1})}]$,

$$c_i(\cdot) \in C(R_+, R_+), \quad R_+ = [0, \infty), \quad i = 1, 2, \dots, m, \quad (3.4)$$

(5⁰) $\varphi_j(\cdot)$ are nonlinear functionals acting from

$$\bigoplus_{k=1}^m \left(W_2^1(a_k, a_{k+1}) \times L_2(a_k, a_{k+1}) \right) \quad (3.5)$$

to R and for arbitrary $(\bar{u}^1, \bar{v}^1), (\bar{u}^2, \bar{v}^2) \in \bigoplus_{k=1}^m (W_2^1(a_k, a_{k+1}) \times L_2(a_k, a_{k+1}))$ the following inequality holds

$$\left| \varphi_j(\bar{u}^1, \bar{v}^1) - \varphi_j(\bar{u}^2, \bar{v}^2) \right| \leq c_j(r) \sum_{k=1}^m \left[\left\| u_k^1 - u_k^2 \right\|_{W_2^1(a_k, a_{k+1})} + \left\| v_k^1 - v_k^2 \right\|_{L_2(a_k, a_{k+1})} \right], \quad (3.6)$$

where $c_j(\cdot) \in C(R_+, R_+)$, $j = 0, 1, \dots, m$, and r —is defined as in (3.3),

(6⁰) $u_i^0 \in W_2^2(a_i, a_{i+1}), u_i^1 \in W_2^1(a_i, a_{i+1}), i = 1, 2, \dots, m$, where

$$\begin{aligned} u_j^0(a_{j+1}) &= u_{j+1}^0(a_{j+1}), \\ u_j^1(a_{j+1}) &= u_{j+1}^1(a_{j+1}), \quad j = 1, 2, \dots, m-1. \end{aligned} \quad (3.7)$$

By applying Theorem 2.1, we obtain the following result.

Theorem 3.1. *Let conditions (1⁰)–(6⁰) be held, then there exists a $T' \in (0, T]$, such that the problem (3.1) has a unique solution $\bar{u} = (u_1, \dots, u_m)$, where*

$$u_i \in C^2([0, T']; L_2(a_i, a_{i+1})) \cap C^1([0, T']; W_2^1(a_i, a_{i+1})) \cap C([0, T']; W_2^2(a_i, a_{i+1})),$$

$$u_i(t, a_i), u_i(t, a_{i+1}) \in C^2([0, T'], R), \quad i = 1, 2, \dots, m. \tag{3.8}$$

Proof. Let us denote $H^i = L_2(a_i, a_{i+1})$, $H_0^i = W_2^2(a_i, a_{i+1})$, $X_\nu^i = \mathbb{C}, Y_\mu^j = \mathbb{C}, \nu = 1, 2, \dots, s_i, i = 1, 2, \dots, m, \mu = 1, 2, \dots, r_j, j = 1, 2, \dots, m$, where $s_i = 2, r_j = 1$.

In space H^i and X_ν^i are defined the following inner products:

$$(u, v)_{H^i(t)} = p_i^{-1}(t) \int_{a_i}^{a_{i+1}} u \bar{v} dx,$$

$$(h_1, h_2)_{X_1^i(t)} = q_0^{-1}(t) h_1 \bar{h}_2, \quad (h_1, h_2)_{X_2^i(t)} = q_i^{-1}(t) h_1 \bar{h}_2, \tag{3.9}$$

$$h_1, h_2 \in \mathbb{C}, \quad i = 1, 2, \dots, m.$$

From differentiability of the functions $p_i(t), i = 1, 2, \dots, m$, and $q_j(t), j = 0, 1, \dots, m$ it follows that the condition (i) is satisfied.

Let us define the following operators:

$$A_i(t)u_i = -p_i(t)u_i'', u_i \in D(A_i(t)) = W_2^2(a_i, a_{i+1}),$$

$$B_{11}u_1 = u_1(a_1), B_{j1} = 0, B_{2i}u_i = u_i(a_{i+1}), i = 1, 2, \dots, m, j = 2, \dots, m,$$

$$C_{11}^1(t)u_1 = -q_0(t)u_1'(a_1), C_{m1}^m(t)u_m = q_m(t)u_m'(a_{m+1}),$$

$$C_{k1}^i(t) = 0, \text{ for all other } i, k,$$

$$C_{i2}^i(t)u_i = q_i(t)u_i'(a_{i+1}), i = 1, 2, \dots, m,$$

$$C_{j2}^j(t)u_{j+1} = -q_j(t)u_{j+1}'(a_{j+1}), j = 1, 2, \dots, m - 1,$$

$$C_{k2}^i(t) = 0, \text{ for all other } i, k,$$

$$D_{i1}^i u_i = -u_i(a_{i+1}), D_{i+1,1}^i u_{i+1} = u_{i+1}(a_{i+1}), i = 1, 2, \dots, m - 1,$$

$$D_{k1}^i = 0, k \neq i, k \neq i + 1.$$

We also define the nonlinear operators as follows:

$$F_i(t, \bar{u}, \bar{v}) = f_i(t, x, u_i(x), u_i'(x), v_i(x), \varphi_i(\bar{u}, \bar{v})), i = 1, 2, \dots, m,$$

$$G_{11}(t, \bar{u}, \bar{v}) = g_0(t, \psi_0(\bar{u}, \bar{v})),$$

$$G_{i2}(t, \bar{u}, \bar{v}) = g_i(t, \psi_i(\bar{u}, \bar{v})), i = 1, 2, \dots, m,$$

$$G_{i1}(t, \bar{u}, \bar{v}) = 0, i = 2, 3, \dots, m.$$

It is easy to verify that linear operators $A_i(t), B_{iv}, C_{iv}^k(t)$, and $D_{i\mu}^k$ and the nonlinear operators F_i, G_{i1} , and G_{i2} , $i = 1, \dots, m$ satisfy the conditions of Theorem 2.1, and the problem (3.1) is represented as an abstract initial boundary-value problem in the following way:

$$\begin{aligned}
\ddot{u}_i(t) + A_i(t)u_i(t) &= F_i(t, \bar{u}, \dot{\bar{u}}), \\
B_{11}\ddot{u}_1(t) + C_{11}^1(t)u_1(t) &= G_0(t, \bar{u}, \dot{\bar{u}}), \\
B_{i2}\ddot{u}_i(t) + C_{i2}^i(t)u_i(t) + C_{i+2,2}^i(t)u_i(t) &= G_i(t, \bar{u}, \dot{\bar{u}}), \\
B_{m2}\ddot{u}_m(t) + C_{m2}^m(t)u_m(t) &= G_m(t, \bar{u}, \dot{\bar{u}}), \\
D_{i1}^i u_i + D_{i1}^i u_{i+1} &= 0, \quad i = 1, 2, \dots, m-1.
\end{aligned} \tag{3.10}$$

We will show that conditions of Theorem 2.1 are satisfied. Conditions (i)–(v) follow immediately from definitions of spaces H^i, X_{ν}^i , and Y_{μ}^j and operators $A_i(t), B_{iv}, C_{kv}^i(t)$, and $D_{k\mu}^j$ and traces theorems (see [3, chapter 2]), where $k = 1, 2, \dots, m$; $\nu = 1, 2, \dots, s_i$; $i = 1, 2, \dots, m$; $\mu = 1, 2, \dots, r_j$; $j = 1, 2, \dots, m$.

The linear manifolds \widehat{H}_0 and \mathcal{H}_1 are defined in the following way:

$$\begin{aligned}
\widehat{H}_0 &= \left\{ \bar{u}, \bar{u} = (u_1, \dots, u_m), u_i \in W_2^2(a_i, a_{i+1}), i = 1, \dots, m, \right. \\
&\quad \left. u_j(a_{j+1}) = u_{j+1}(a_{j+1}), j = 1, \dots, m-1 \right\}, \\
\mathcal{H}_1 &= \left\{ w, w = (w_1, \dots, w_m), w_1 = (u_1, u_1(a_2), u_1(a_1)), \right. \\
&\quad \left. w_i = (u_i, u_i(a_{i+1})), i = 2, \dots, m, \bar{u} \in \widehat{H}_0 \right\}.
\end{aligned} \tag{3.11}$$

We also define the spaces

$$\begin{aligned}
H_{1/2} &= \left\{ \bar{u}, \bar{u} = (u_1, \dots, u_m), u_i \in W_2^1(a_i, a_{i+1}), i = 1, \dots, m \right\}, \\
\widehat{H}_{1/2} &= \left\{ \bar{u}, \bar{u} = (u_1, \dots, u_m), u_i \in W_2^1(a_i, a_{i+1}), i = 1, \dots, m, \right. \\
&\quad \left. u_j(a_{j+1}) = u_{j+1}(a_{j+1}), j = 1, \dots, m-1 \right\}.
\end{aligned} \tag{3.12}$$

□

Statement 3.2. \mathcal{H}_1 is dense in

$$\mathcal{H} = (L_2(a_1, b_1) \oplus \mathbb{C} \oplus \mathbb{C}) \oplus \bigoplus_{i=2}^m (L_2(a_i, b_i) \oplus \mathbb{C}). \tag{3.13}$$

Proof. Assume that $(u_1, \alpha_1, \alpha_0, u_2, \alpha_2, \dots, u_m, \alpha_m) \in \mathcal{L}$. Consider the following functions:

$$u_i^0(x) = \frac{a_{i+1} - x}{a_{i+1} - a_i} \alpha_{i-1} + \frac{x - a_i}{a_{i+1} - a_i} \alpha_i, \quad x \in [a_i, a_{i+1}], \quad i = 1, \dots, m. \tag{3.14}$$

From definitions of $u_i^0(x)$, $i = 1, \dots, m$, we can see that

$$u_i^0(a_{i+1}) = u_{i+1}^0(a_{i+1}) = \alpha_i, \quad i = 1, 2, \dots, m - 1. \tag{3.15}$$

Let $\bar{u} = (u_1, \dots, u_m) \in \widehat{H}$. Consider the function

$$z = (z_1, \dots, z_m) = (u_1 - u_1^0, \dots, u_m - u_m^0). \tag{3.16}$$

It is obvious that $z \in \bigoplus_{i=1}^m L_2(a_i, a_{i+1})$. On the other hand, $\overline{\bigoplus_{i=1}^m \mathfrak{D}(a_i, a_{i+1}, a_{i+1})} = \bigoplus_{i=1}^m L_2(a_i, a_{i+1})$, where $\mathfrak{D}(a_i, a_{i+1})(i = 1, \dots, m)$ is a space of infinitely differentiable finite functions. Therefore, for an arbitrary $\varepsilon > 0$, there exist the functions $h_i \in \mathfrak{D}(a_i, a_{i+1})$, $i = 1, \dots, m$, such that

$$\sum_{i=1}^m \|z_i - h_i\| < \varepsilon. \tag{3.17}$$

By denoting $\tilde{h}_i = u_i^0 + h_i$ from (3.17), we get

$$\sum_{i=1}^m \|u_i - \tilde{h}_i\|_{L_2(a_i, a_{i+1})} < \varepsilon, \tag{3.18}$$

where $\tilde{h}_i \in C^\infty[a_i, a_{i+1}]$, $\tilde{h}_i(a_i) = \alpha_{i-1}$, $i = 1, \dots, m$.

Thus,

$$\|(u_1, u_1(a_2), u_1(a_1), u_2, u_2(a_2), \dots, u_m, u_m(a_{m+1})) - (h_1, \alpha_1, \alpha_0, h_2, \alpha_1, \dots, h_m, \alpha_m)\|_{\mathcal{L}} < \varepsilon. \tag{3.19}$$

□

The following statement is proved in the same way.

Statement 3.3. \widehat{H}_0 is dense $\widehat{H}_{1/2}$.

Now, we prove that the condition (vi) holds.

Let $\bar{u} = (u_1, \dots, u_m), \bar{v} = (v_1, \dots, v_m) \in \widehat{H}_0$, then

$$\begin{aligned}
& \sum_{i=1}^m \left[(A_i(t)u_i, v_i)_{H^i(t)} + \sum_{\nu=1}^{S_i} \left(\sum_{k=1}^m C_{k\nu}^i(t)u_k, B_{i\nu}v_i \right)_{X_{\nu}^i(t)} \right] \\
&= \sum_{i=1}^m \left[- \int_{a_i}^{a_{i+1}} u_i' v_i dx + (-u_1'(a_1), v_1(a_1)) \right. \\
&\quad \left. + \sum_{i=1}^m (u_i'(a_{i+1}) - u_{i+1}'(a_{i+1}), v_i(a_{i+1})) + (u_m'(a_{m+1}), v_m(a_m)) \right] \\
&= \sum_{i=1}^m [(u_i'(a_i), v_i(a_i)) - (u_i'(a_{i+1}), v_i(a_{i+1}))] \\
&\quad - \sum_{i=1}^m \int_{a_i}^{a_{i+1}} u_i' v_i' dx - (u_1'(a_1), v_1(a_1)) + \sum_{i=1}^{m-1} u_i'(a_{i+1}) v_i'(a_{i+1}) \\
&\quad - \sum_{i=1}^{m-1} u_{i+1}'(a_{i+1}) v_i(a_{i+1}) + u_m'(a_{m+1}) v_m(a_{m+1}) \\
&= \sum_{i=1}^m (u_i'(a_i) v_i(a_i) - u_i'(a_{i+1}) v_i'(a_{i+1})) - u_1'(a_1) v_1(a_1) + \sum_{i=1}^{m-1} u_i'(a_i) v_i(a_i) - \sum_{i=2}^m u_i'(a_i) v_i(a_i) \\
&\quad + u_m'(a_{m+1}) v_m(a_{m+1}) + \sum_{i=1}^m \int_{a_i}^{a_{i+1}} u_i' v_i' dx = \sum_{i=1}^m \int_{a_i}^{a_{i+1}} u_i' v_i' dx.
\end{aligned} \tag{3.20}$$

Similarly, we obtain the following identity:

$$\sum_{i=1}^m \left[(u_i, A_i(t)v_i)_{H^i(t)} + \sum_{\nu=1}^{S_i} \left(B_{i\nu}v_i, \sum_{k=1}^m C_{k\nu}^i(t)u_k \right)_{X_{\nu}^i(t)} \right] = \sum_{i=1}^m \int_{a_i}^{a_{i+1}} u_i' v_i' dx. \tag{3.21}$$

Thus, by virtue of (3.20)-(3.21), the condition (vi) holds.

From (3.20) or (3.21), putting $v_i = u_i$, we also obtain the identity

$$\sum_{i=1}^m \int_{a_i}^{a_{i+1}} u_i^2 dx = \sum_{i=1}^m \left[(A_i(t)u_i, u_i)_{H^i(t)} + \sum_{\nu=1}^{S_i} \left(\sum_{k=1}^m C_{k\nu}^i(t)u_k, B_{i\nu}u_i \right)_{X_{\nu}^i(t)} \right], \tag{3.22}$$

that is, condition (viii) is satisfied, $c_1 = c_2 = 1$.

Now, we verify fulfillment of condition (ix). To that end, we consider the mixed problem

$$\lambda u_i - p_i(t)u_i'' = h_i(x), \quad i = 1, 2, \dots, m, \tag{3.23}$$

$$\lambda u_1(a_1) - q_0(t)u_1'(a_1) = h_{10},$$

$$\lambda u_i(a_{i+1}) + q_i(t)[u_i'(a_{i+1}) - u_{i+1}'(a_{i+1})] = h_{i0}, \quad i = 1, 2, \dots, m - 1, \tag{3.24}$$

$$\lambda u_m(a_{m+1}) + q_m(t)u_m'(a_{m+1}) = h_{m0},$$

where $h_i \in L_2(a_i, a_{i+1}), i = 1, \dots, m; h_{j0} \in R, j = 0, 1, \dots, m, \lambda \in R$.

Let $h_i(x)$ be the extend of function $h_i(x)$ to R . We consider the system of the differential equations

$$\lambda \tilde{u}_i - p_i(t)\tilde{u}_{i,xx} = \tilde{h}_i(x), \quad i = 1, 2, \dots, m. \tag{3.25}$$

Hence, we have

$$\lambda \hat{\tilde{u}}_i - k^2 p_i(t)\hat{\tilde{u}}_{i,xx} = \hat{\tilde{h}}_i(x), \quad i = 1, 2, \dots, m, \tag{3.26}$$

where $\hat{g} = F[g]$ is a Fourier transformation of the function $g(x)$. From (3.26), we obtain $\hat{\tilde{u}} = \hat{\tilde{h}}_i / (\lambda + k^2 p_i(t))$, then functions $\tilde{u}_i = F^{-1}[\hat{\tilde{u}}_i] = F^{-1}[\hat{\tilde{h}}_i / (\lambda + k^2 p_i(t))]$ satisfy (3.25), and their constrictions on (a_i, a_{i+1}) satisfy the (3.23). It is clear that $\tilde{u}_i \in W_2^2(a_i, a_{i+1})$. Considering linearity of the problem (3.23), (3.24), the solution can be represented in the form

$$u_i = v_i + \tilde{u}_i, \tag{3.27}$$

where $v_i = u_i - \tilde{u}_i$ is a solution of the following problem:

$$\lambda v_i(x) - p_i(t)v_i''(x) = 0, \tag{3.28}$$

$$\lambda v_1(a_1) - q_0(t)v_1'(a_1) = \tilde{h}_{10},$$

$$\lambda v_i(a_{i+1}) + q_i(t)[v_i'(a_{i+1}) - v_{i+1}'(a_{i+1})] = \tilde{h}_{i0}, \quad i = 1, 2, \dots, m - 1, \tag{3.29}$$

$$\lambda v_m(a_{m+1}) + q_m(t)v_m'(a_{m+1}) = \tilde{h}_{m0},$$

where $\tilde{h}_{10} = h_{10} - \lambda \tilde{u}_1(a_1) + q_0(t)\tilde{u}_1'(a_1)$,

$$\tilde{h}_{i0} = h_{i0} - \lambda \tilde{u}_i(a_{i+1}) - q_i(t)[\tilde{u}_i'(a_{i+1}) - \tilde{u}_{i+1}'(a_{i+1})], \quad i = 1, 2, \dots, m - 1, \tag{3.30}$$

$$\tilde{h}_{m0}(0) = h_{m0} - \lambda \tilde{u}_m(a_{m+1}) + q_m(t)\tilde{u}_m'(a_{m+1}).$$

A general solution of a system (3.28) is found in the following form:

$$v_i(x) = c_{i1}e^{-(x-a_i)\sqrt{\lambda/p_i(t)}} + c_{i2}e^{-(b_i-x)\sqrt{\lambda/p_i(t)}}, \quad i = 1, 2, \dots, m. \quad (3.31)$$

Then, for determination of $c_{i1}, c_{i2}, i = 1, 2, \dots, m$, from (3.29), we get the following system of the algebraic equations:

$$\begin{aligned} \lambda(c_{11} + c_{12}e^{-(a_2-a_1)\sqrt{\lambda/p_1(t)}}) - q_0(t)\sqrt{\frac{\lambda}{p_1(t)}}(c_{11} - c_{12}e^{-(a_2-a_1)\sqrt{\lambda/p_1(t)}}) &= \tilde{h}_0, \\ \lambda(c_{i1}e^{-(a_{i+1}-a_i)\sqrt{\lambda/p_i(t)}} - c_{i2}) + q_i(t)\sqrt{\frac{\lambda}{p_i(t)}}(c_{i1}e^{-(a_{i+1}-a_i)\sqrt{\lambda/p_i(t)}} + c_{i2}) \\ - \sqrt{\frac{\lambda}{p_{i+1}(t)}}(c_{i+1,1} + c_{i+1,2}e^{-(a_{i+2}-a_{i+1})\sqrt{\lambda/p_{i+1}(t)}}) &= \tilde{h}_{i0}, \quad i = 1, 2, \dots, m-1, \\ c_{i1}e^{-(a_{i+1}-a_i)\sqrt{\lambda/p_i(t)}} - c_{i2} - (c_{i+1,1} - c_{i+1,2}e^{-(a_{i+2}-a_{i+1})\sqrt{\lambda/p_{i+1}(t)}}) &= 0, \quad i = 1, \dots, m-1, \\ \lambda(c_{m1}e^{-(a_{m+1}-a_m)\sqrt{\lambda/p_m(t)}} + c_{m2}) + (-c_{m1}e^{-(a_{m+1}-a_m)\sqrt{\lambda/p_m(t)}} + c_{m2}) &= \tilde{h}_{m0}. \end{aligned} \quad (3.32)$$

Let $R(\lambda)$ be a matrix of coefficients of system (3.32). From (3.32), it is clear that $R(\lambda) = R_0(\lambda) + R_1(\lambda)$, where $\det R_0(\lambda) \rightarrow +\infty$ and $\det R_1(\lambda) \rightarrow 0$ as $\lambda \rightarrow +\infty$. Thus, for sufficiently large λ , $R(\lambda)$ is invertible and $\det R(\lambda) \rightarrow +\infty$. Therefore, the system (3.32) has a unique solution.

Thus, for sufficiently positive large λ , the problem (3.23)-(3.24) has a unique solution $u = (u_1, \dots, u_m) \in H_0$.

Thus, the condition (ix) is satisfied. The fulfillment of other conditions follows from (1⁰)-(6⁰).

Now, let us consider a class of nonlinear equations, for which the large solvability theorem takes place.

Let

$$\begin{aligned} f_i(t, x, u_i, u'_i, \dot{u}_i, \varphi(\bar{u}, \dot{\bar{u}})) &= -|u_i|^{\rho_i}u_i + f_{1i}(t, x, u_i, u'_i, \dot{u}_i, \tilde{\varphi}_i(\bar{u}, \dot{\bar{u}})), \\ g_0(t, \varphi_0(\bar{u}, \dot{\bar{u}})) &= -|u_1(a_1)|^{\tau_0}u_1(a_1) + g_{01}(t, \varphi_0(\bar{u}, \dot{\bar{u}})), \\ g_i(t, \varphi_i(\bar{u}, \dot{\bar{u}})) &= -|u_i(a_{i+1})|^{\tau_i}u_i(a_{i+1}) + g_{i1}(t, \tilde{\varphi}_i(\bar{u}, \dot{\bar{u}})), \quad i = 1, 2, \dots, m, \end{aligned} \quad (3.33)$$

where $\rho_i \geq 0, \tau_j \geq 0, i = 1, 2, \dots, m; j = 0, 1, \dots, m$ and

$$(7^0) \quad f_{1i}, g_{1j}, \tilde{\varphi}_i \text{ and } \tilde{\varphi}_j, \quad i = 1, 2, \dots, m, j = 1, 2, \dots, m \text{ satisfy the conditions } (2^0) - (5^0).$$

$$(8^0) \quad |f_i(t, x, u_i, v_i, \xi_i, \eta)| \leq c(1 + |u_i|^{(\rho_i+2)/2} + |v_i| + |\xi_i| + |\eta|),$$

$$(9^0) \quad |g_{0i}(t, \eta)| \leq c(1 + |\eta|),$$

$$(10^0) \quad |\varphi_i(\bar{u}, \bar{v})| \leq c(1 + \sum_{i=1}^n |u_i|^{(\rho_i+2)/2} + |v_i|^2 + |u_i(y_i)|^{(\tau_i+2)/2}),$$

where $y_i = a_{i+1}$, $i = 0, 1, \dots, m$, $\rho = \max(\min_{i=1,2,\dots,m}(\rho_i, 2))$.

Theorem 3.4. *Let conditions (7⁰)–(10⁰) be held and initial data satisfy the condition (6⁰), then the problem (3.1) has a unique solution $\bar{u} = (u_1, \dots, u_m)$, where*

$$u_i \in C^2([0, T]; L_2(a_i, a_{i+1})) \cap C^1([0, T]; W_2^1(a_i, a_{i+1})) \cap C([0, T]; W_2^2(a_i, a_{i+1})), \quad (3.34)$$

$$u_i(t, a_i), u_i(t, a_{i+1}) \in C^2([0, T]; R), \quad i = 1, 2, \dots, m.$$

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