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On the Invariant Regions and Global Existence of Solutions for Four Components Reaction-Diffusion Systems With a Full Matrix of Diffusion Coffers and Nonhomogeneous Boundary Conditions

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Abstract

In this work we consider a reaction-diffusion systems (four equations) with a full matrix of diffusion and with nonhomogeneous boundary conditions, by using the Invariant regions and Lyapunov functional method we established the global existence of solution.

Keywords: *Reaction-Diffusion systems, Invariant regions, Matrice of diffusion, Global Existence.*

1 Introduction

We consider the following reaction-diffusion system

$$\frac{\partial u}{\partial t} - a\Delta u - b\Delta v - c\Delta w - d\Delta z = f_1(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (1.1)$$

$$\frac{\partial v}{\partial t} - c\Delta u - a\Delta v - b\Delta z = f_2(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (1.2)$$

$$\frac{\partial w}{\partial t} - b\Delta u - a\Delta w - c\Delta z = f_3(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (1.3)$$

$$\frac{\partial z}{\partial t} - d\Delta u - c\Delta v - b\Delta w - a\Delta z = f_4(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (1.4)$$

with the boundary conditions

$$\left\{ \begin{array}{ll} \lambda u + (1 - \lambda) \frac{\partial u}{\partial \eta} = \beta_1 & \text{in } R^+ \times \partial \Omega \\ \lambda v + (1 - \lambda) \frac{\partial v}{\partial \eta} = \beta_2 & \text{in } R^+ \times \partial \Omega \\ \lambda w + (1 - \lambda) \frac{\partial w}{\partial \eta} = \beta_3 & \text{in } R^+ \times \partial \Omega \\ \lambda z + (1 - \lambda) \frac{\partial z}{\partial \eta} = \beta_4 & \text{in } R^+ \times \partial \Omega \end{array} \right. \quad (1.5)$$

and the initial data

$$u(0, x) = u_0(x); v(0, x) = v_0(x); w(0, x) = w_0(x); z(0, x) = z_0(x), \quad \text{in } \Omega \quad (1.6)$$

i. For nonhomogeneous Robin boundary conditions, we use

$$0 < \lambda < 1, \text{ and } \beta_i \in R, i = 1, 2, 3, 4.$$

ii. For nonhomogeneous Neumann boundary conditions, we use

$$\lambda = \beta_i = 0, \quad i = 1, 2, 3, 4.$$

iii. For nonhomogeneous Dirichlet boundary conditions, we use

$$1 - \lambda = \beta_i = 0, \quad i = 1, 2, 3, 4.$$

Where Ω is an open bounded domain of class C^1 in R^n , with boundary $\partial \Omega$ and $\frac{\partial}{\partial \eta}$ denotes the outward normal derivative on $\partial \Omega$. a, b, c and d are positive constants satisfying the condition $(a + \frac{1}{2}(d - \mu))(a - d)$ which reflects the parabolicity of the system and implies at the same time that the matrix of diffusion

$$A = \begin{pmatrix} a & b & c & d \\ c & a & 0 & b \\ b & 0 & a & c \\ d & c & b & a \end{pmatrix} \quad (1.7)$$

is positive definite; that is the eigenvalues $\lambda_1, \lambda_2, \lambda_3$ and λ_4 ($\lambda_1 < \lambda_2 < \lambda_3 < \lambda_4$) of its transposed are positive.

The initial data $(u_0, v_0, w_0, z_0) \in R^4$ are assumed to be in the following region :

$$\sum = \left\{ \begin{array}{l} u_0 \leq -\frac{2(b-c)}{d+\mu}(v_0 - w_0) + z_0 \\ u_0 \leq -\frac{2(b-c)}{d-\mu}(v_0 - w_0) + z_0 \\ u_0 + \frac{2(b+c)}{d-\mu}(v_0 + w_0) + z_0 \geq 0 \\ \text{and} \\ u_0 + \frac{2(b+c)}{d+\mu}(v_0 + w_0) + z_0 \geq 0 \end{array} \right. \quad \text{if} \quad \left\{ \begin{array}{l} \beta_1 \leq -\frac{2(b-c)}{d+\mu}(\beta_2 - \beta_3) + \beta_4 \\ \beta_1 \leq -\frac{2(b-c)}{d-\mu}(\beta_2 - \beta_3) + \beta_4 \\ \beta_1 + \frac{2(b+c)}{d-\mu}(\beta_2 + \beta_3) + \beta_4 \geq 0 \\ \text{and} \\ \beta_1 + \frac{2(b+c)}{d+\mu}(\beta_2 + \beta_3) + \beta_4 \geq 0 \end{array} \right\}$$

where

$$\mu = \sqrt{4b^2 + 8bc + 4c^2 + d^2}$$

We suppose that the reaction terms f_1, f_2, f_3 and f_4 are continuously differentiable, polynomially bounded on Σ satisfying:

$$\left(-f_1 - \frac{2(b-c)}{d+\mu}(f_2 - f_3) + f_4 \right) \left(-\frac{2(b-c)}{d+\mu}(v - w) + z, v, w, z \right) \geq 0 \quad (1.8)$$

$$\left(-f_1 - \frac{2(b-c)}{d-\mu}(f_2 - f_3) + f_4 \right) \left(-\frac{2(b-c)}{d-\mu}(v - w) + z, v, w, z \right) \geq 0 \quad (1.9)$$

$$\left(f_1 + \frac{2(b+c)}{d-\mu}(f_2 + f_3) + f_4 \right) \left(-\frac{2(b+c)}{d-\mu}(v + w) - z, v, w, z \right) \geq 0 \quad (1.10)$$

$$\left(f_1 + \frac{2(b+c)}{d+\mu}(f_2 + f_3) + f_4 \right) \left(-\frac{2(b+c)}{d+\mu}(v + w) - z, v, w, z \right) \geq 0 \quad (1.11)$$

for all $v, w, z \geq 0$. And for positive constants $C_{11}, C_{12}, C_{13} \leq 1$.

$$(C_{11}f_1 + C_{12}f_2 + C_{13}f_3 + f_4)(u, v, w, z) \leq C_1(u + v + w + z + 1); \quad (1.12)$$

for all u, v, w, z in Σ where C_1 is a positive constant.

2 Existence

2.1 Local Existence

The usual norms in spaces $L^p(\Omega)$, $L^\infty(\Omega)$ and $C(\Omega)$ are respectively denote by:

$$\begin{aligned} \|u\|_p^p &= \frac{1}{\Omega} \int_{\Omega} |u(x)|^p dx \\ \|u\|_\infty &= \max_{x \in \Omega} |u(x)|. \end{aligned}$$

For any initial data in $C(\overline{\Omega})$ or $L^p(\Omega)$, $p \in (1, +\infty)$; local existence and uniqueness of solutions to the initial value problem (1.1)-(1.5) follow from the basic existence theory for abstract semilinear differential equations (see A. Friedman[3], D.Henry[4] and A.Pazy[12]). The solutions are classical on $[0, T_{\max}[$; where T_{\max} denotes the eventual blowing-up time in $L^\infty(\Omega)$.

2.2 Invariant Regions

Proposition 1 Suppose that the functions f_1, f_2, f_3 and f_4 points into the region \sum on $\partial \sum$ then for any (u_0, v_0, w_0, z_0) in \sum , the solution $(u(t, .), v(t, .), w(t, .), z(t, .))$ of the problem (1.1)-(1.6) remains in \sum for any time.

Proof. The proof follows the same way to that in S.Kouachi[5]

- Multiplying successively (1.1) by -1 , (1.2) by $-\frac{2(b-c)}{d+\mu}$, (1.3) by $\frac{2(b-c)}{d+\mu}$ and (1.4) by 1 .

Ading the first result, the second, the third and the forth results we get (2.1).

- Multiplying successively (1.1) by -1 , (1.2) by $-\frac{2(b-c)}{d-\mu}$, (1.3) by $\frac{2(b-c)}{d-\mu}$ and last one by 1 .

Ading the first result, the second result, the third and the forth results we get (2.2).

- Multiplying successively (1.1) by 1 , (1.2) and (1.3) by $\frac{2(b+c)}{d+\mu}$, and (1.4) by 1 .

Ading the first result, the second result, the third and the forth results we get (2.3).

- Multiplying successively (1.1) by 1 , the second and the third by $\frac{2(b+c)}{d-\mu}$ and last one by 1 .

Ading the first result, the second result, the third and the forth results we get (2.4).

Finaly we obtain the system

$$\frac{\partial U}{\partial t} - \left(a - \frac{1}{2} (d + \mu) \right) \Delta U = F_1(U, V, W, Z) \quad (2.1)$$

$$\frac{\partial V}{\partial t} - \left(a - \frac{1}{2} (d - \mu) \right) \Delta V = F_2(U, V, W, Z) \quad (2.2)$$

$$\frac{\partial W}{\partial t} - \left(a + \frac{1}{2} (d - \mu) \right) \Delta W = F_3(U, V, W, Z) \quad (2.3)$$

$$\frac{\partial Z}{\partial t} - \left(a + \frac{1}{2} (d + \mu) \right) \Delta Z = F_4(U, V, W, Z) \quad (2.4)$$

with the boundary conditions

$$\begin{cases} \lambda U + (1 - \lambda) \frac{\partial U}{\partial \eta} = \rho_1 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda V + (1 - \lambda) \frac{\partial V}{\partial \eta} = \rho_2 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda W + (1 - \lambda) \frac{\partial W}{\partial \eta} = \rho_3 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda Z + (1 - \lambda) \frac{\partial Z}{\partial \eta} = \rho_4 & \text{in }]0, T^*[\times \partial \Omega \end{cases} \quad (2.5)$$

and the initial data

$$U(0, x) = U_0(x); V(0, x) = V_0(x); W(0, x) = W_0(x); Z(0, x) = Z_0(x) \quad (2.6)$$

where

$$\begin{cases} U(t, x) = -u(t, x) + \frac{2(b-c)}{d+\mu} (w(t, x) - v(t, x)) + z(t, x) \\ V(t, x) = -u(t, x) + \frac{2(b-c)}{d-\mu} (w(t, x) - v(t, x)) + z(t, x) \\ W(t, x) = u(t, x) + \frac{2(b+c)}{d-\mu} (v(t, x) + w(t, x)) + z(t, x) \\ Z(t, x) = u(t, x) + \frac{2(b+c)}{d+\mu} (v(t, x) + w(t, x)) + z(t, x) \end{cases} \quad (2.7)$$

for any (t, x) in $]0, T^*[\times \Omega$, and

$$\begin{cases} F_1(U, V, W, Z) = \left(-f_1 + \frac{2(b-c)}{d+\mu} (f_3 - f_2) + f_4 \right) (u, v, w, z) \\ F_2(U, V, W, Z) = \left(-f_1 + \frac{2(b-c)}{d-\mu} (f_3 - f_2) + f_4 \right) (u, v, w, z) \\ F_3(U, V, W, Z) = \left(f_1 + \frac{2(b+c)}{d-\mu} (f_2 + f_3) + f_4 \right) (u, v, w, z) \\ F_4(U, V, W, Z) = \left(f_1 + \frac{2(b+c)}{d+\mu} (f_2 + f_3) + f_4 \right) (u, v, w, z) \end{cases} \quad (2.8)$$

for all (u, v, w, z) in Σ ,

$$\begin{cases} \lambda_1 = (a - \frac{1}{2}(d + \mu)) \\ \lambda_2 = (a - \frac{1}{2}(d - \mu)) \\ \lambda_3 = (a + \frac{1}{2}(d - \mu)) \\ \lambda_4 = (a + \frac{1}{2}(d + \mu)) \end{cases}$$

and

$$\begin{cases} \rho_1 = -\beta_1 + \frac{2(b-c)}{d+\mu} (\beta_3 - \beta_2) + \beta_4 \\ \rho_2 = -\beta_1 + \frac{2(b-c)}{d-\mu} (\beta_3 - \beta_2) + \beta_4 \\ \rho_3 = \beta_1 + \frac{2(b+c)}{d-\mu} (\beta_2 + \beta_3) + \beta_4 \\ \rho_4 = \beta_1 + \frac{2(b+c)}{d+\mu} (\beta_2 + \beta_3) + \beta_4 \end{cases}$$

First, let's notice that the condition of parabolicity of the system (1.1)-(1.4) implies the one of the (2.1)-(2.4) system; since $(a + \frac{1}{2}(d - \mu)) (a - d) \geq 0 \implies (a + \frac{1}{2}(d - \mu)) > 0$; $(a - \frac{1}{2}(d + \mu)) > 0$ and $(a - \frac{1}{2}(d - \mu)) > 0$.

Now, it suffices to prove that the region

$$\Sigma = \{U \geq 0, V \geq 0, W \geq 0, Z \geq 0\} = \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+ \times \mathbb{R}^+,$$

is invariant region for the system (2.1)-(2.4).

Since , from (1.8) – (1.9) – (1.10) – (1.11) we have $F_1(0, V, W, Z) \geq 0$ it suffices to be

$$\begin{aligned} & -f_1\left(-\frac{2(b-c)}{d+\mu}(v-w)+z, v, w, z\right)-\frac{2(b-c)}{d+\mu}\left(\left(f_2-f_3\right)\left(\left(-\frac{2(b-c)}{d+\mu}(v-w)+z, v, w, z\right)\right)\right) \\ & +f_4\left(-\frac{2(b-c)}{d+\mu}(v-w)+z, v, w, z\right) \geq 0, \text { for all } V, W, Z \geq 0 \text { and all } v, w, z \geq 0, \end{aligned}$$

then

$$U(t, x) \geq 0 \text { for all }(t, x) \text { in }]0, T^*[\times \Omega,$$

thanks to the invariant region method (see Smoller[13]), and because $F_2(U, 0, W, Z) \geq 0$ it suffices to be

$$\begin{aligned} & -f_1\left(-\frac{2(b-c)}{d-\mu}(v-w)+z, v, w, z\right)-\frac{2(b-c)}{d-\mu}\left(\left(f_2-f_3\right)\left(\left(-\frac{2(b-c)}{d-\mu}(v-w)+z, v, w, z\right)\right)\right) \\ & +f_4\left(-\frac{2(b-c)}{d-\mu}(v-w)+z, v, w, z\right) \geq 0, \text { for all } U, W, Z \geq 0 \text { and all } v, w, z \geq 0, \end{aligned}$$

then

$$V(t, x) \geq 0 \text { for all }(t, x) \text { in }]0, T^*[\times \Omega, \text { and } F_3(U, V, 0, Z) \geq 0$$

it suffices to be

$$\begin{aligned} & f_1\left(-\frac{2(b+c)}{d-\mu}(v+w)-z, v, w, z\right)+\frac{2(b+c)}{d-\mu}\left(\left(f_2+f_3\right)\left(\left(-\frac{2(b+c)}{d-\mu}(v+w)-z, v, w, z\right)\right)\right) \\ & +f_4\left(-\frac{2(b+c)}{d-\mu}(v+w)-z, v, w, z\right) \geq 0, \text { for all } U, V, Z \geq 0 \text { and all } v, w, z \geq 0, \end{aligned}$$

then

$$W(t, x) \geq 0 \text { for all }(t, x) \text { in }]0, T^*[\times \Omega, \text { and } F_4(U, V, W, 0) \geq 0$$

it suffices to be

$$\begin{aligned} & f_1\left(-\frac{2(b+c)}{d+\mu}(v+w)-z, v, w, z\right)+\frac{2(b+c)}{d+\mu}\left(\left(f_2+f_3\right)\left(\left(-\frac{2(b+c)}{d+\mu}(v+w)-z, v, w, z\right)\right)\right) \\ & +f_4\left(-\frac{2(b+c)}{d+\mu}(v+w)-z, v, w, z\right) \geq 0, \text { for all } U, V, W \geq 0 \text { and all } v, w, z \geq 0, \end{aligned}$$

then

$$Z(t, x) \geq 0 \text { for all }(t, x) \text { in }]0, T^*[\times \Omega,$$

then \sum is an invariant region for the system (1.1) – (1.4).

Then the system (1.1) – (1.4) with boundary condition (1.5) and initial data in \sum is equivalent to system (2.1) – (2.4) with boundary conditions (2.5) and positive initial data (2.6).

Once invariant regions are constructed, one can apply Lyapunov technique and establish global existence of unique solutions for (1.1)-(1.6) ■

2.3 Global Existence

As the determinant of the linear algebraic system (2.7) with regard to variables u, v, w and z , is different from zero, then to prove global existence of solutions of problem (1.1) – (1.6), one needs to prove it for problem (2.1) – (2.6). To this subject ; it is well-known that (see Henry[4]) it suffices to derive an uniform estimate of

$\|F_1(U, V, W, Z)\|_p$, $\|F_2(U, V, W, Z)\|_p$, $\|F_3(U, V, W, Z)\|_p$ and $\|F_4(U, V, W, Z)\|_p$ on $[0, T^*]$ for some $p > \frac{N}{2}$ ($N = \dim \Omega$).

Let's put $A_{12} = \frac{\lambda_1 + \lambda_2}{2\sqrt{\lambda_1\lambda_2}}$, $A_{13} = \frac{\lambda_1 + \lambda_3}{2\sqrt{\lambda_1\lambda_3}}$, $A_{14} = \frac{\lambda_1 + \lambda_4}{2\sqrt{\lambda_1\lambda_4}}$, $A_{23} = \frac{\lambda_2 + \lambda_3}{2\sqrt{\lambda_2\lambda_3}}$, $A_{24} = \frac{\lambda_2 + \lambda_4}{2\sqrt{\lambda_2\lambda_4}}$; θ_1, θ_2 and θ_3 are three positive constants sufficiently large such that

$$\theta_1 > A_{12}, \quad (2.9)$$

$$(\theta_1^2 - A_{12}^2)(\theta_2^2 - A_{23}^2) > (A_{13} - A_{12}A_{23})^2 \quad (2.10)$$

$$(\theta_1^2 - A_{12}^2)(\theta_2^2 - A_{23}^2)(\theta_3^2 - A_{34}^2) > (A_{13} - A_{12}A_{23})^2 + (A_{14} - A_{13}A_{24})^2 \quad (2.11)$$

The main result of the paper is as follows:

Theorem 1. Let $(U(t, .), V(t, .), W(t, .), Z(t, .))$ be any positive solution of (2.1) – (2.6) and let the functional

$$L(t) = \int_{\Omega} H_n(U(t, x), V(t, x), W(t, x), Z(t, .)) dx, \quad (2.12)$$

where

$$H_n(U, V, W, Z) = \sum_{k=0}^n \sum_{j=0}^k \sum_{i=0}^j C_n^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} U^i V^{j-i} W^{k-j} Z^{n-k}.$$

Then, the functional L is uniformly bounded on the interval $[0, T^*]$, $T^* < T_{\max}$.

Corollary 1. Suppose that the functions f_1, f_2, f_3 and f_4 are continuously differentiable on \sum , point into $\partial \sum$ and satisfy condition (1.12). Then all solutions of (1.1) – (1.6) with the initial data in \sum and uniformly bounded on Ω are in $L^\infty(0, T^*; L^p(\Omega))$ for all $p \geq 1$

Proposition 2. Under the hypothesis of corollary 1, if the reactions f_1, f_2, f_3 and f_4 are polynomially bounded, then all solutions of (1.1) – (1.6) with the initial data in \sum and uniformly bounded on Ω are global time.

2.4 Proofs

For the proof of theorem 1, we need some preparatory lemmas.

Lemma 1. Let H_n be the homogeneous polynomial defined by (2.11). Then

$$\begin{aligned} \frac{\partial H_n}{\partial U} &= n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i \theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-1)-k}, \\ \frac{\partial H_n}{\partial V} &= n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-1)-k}, \\ \frac{\partial H_n}{\partial W} &= n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-1)-k}, \\ \frac{\partial H_n}{\partial Z} &= n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} U^i V^{j-i} W^{k-j} Z^{(n-1)-k}, \end{aligned}$$

Proof of lemma 1. see Said Kouachi[6].

Lemma 2. The second partial derivatives of H_n are given by

$$\begin{aligned}
 \frac{\partial^2 H_n}{\partial U^2} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{(i+2)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial UV} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{(i+1)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial UW} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial UZ} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial V^2} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial VW} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial VZ} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial W^2} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+2)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial WZ} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+1)^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k}, \\
 \frac{\partial^2 H_n}{\partial Z^2} &= n(n-1) \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} U^i V^{j-i} W^{k-j} Z^{(n-2)-k},
 \end{aligned}$$

Proof of lemma 2. see Said Kouachi[6].

Proof of Theorem 1. Differentiating L with respect to t yields

$$\begin{aligned}
 L'(t) &= \int_{\Omega} \left(\partial_U H_n \frac{\partial U}{\partial t} + \partial_V H_n \frac{\partial V}{\partial t} + \partial_W H_n \frac{\partial W}{\partial t} + \partial_Z H_n \frac{\partial Z}{\partial t} \right) dx \\
 &= \int_{\Omega} (\lambda_1 \partial_U H_n \Delta U + \lambda_2 \partial_V H_n \Delta V + \lambda_3 \partial_W H_n \Delta W + \lambda_4 \partial_Z H_n \Delta Z) dx \\
 &\quad + \int_{\Omega} (F_1 \partial_U H_n + F_2 \partial_V H_n + F_3 \partial_W H_n + F_4 \partial_Z H_n) dx \\
 &= I + J.
 \end{aligned}$$

Using Green's formula and applying lemma 1 we get $I = I_1 + I_2$, where

$$I_1 = \int_{\partial\Omega} \left(\lambda_1 \partial_U H_n \frac{\partial U}{\partial \eta} + \lambda_2 \partial_V H_n \frac{\partial V}{\partial \eta} + \lambda_3 \partial_W H_n \frac{\partial W}{\partial \eta} + \lambda_4 \partial_Z H_n \frac{\partial Z}{\partial \eta} \right) dx \quad (2.13)$$

$$I_2 = -n(n-1) \int_{\Omega} \sum_{k=0}^{n-2} \sum_{j=0}^k \sum_{i=0}^j C_{n-2}^k C_k^j C_j^i (TB_{ijk}) T^t dx, \quad ((2.14))$$

where

$$B_{ijk} = \begin{bmatrix} \lambda_1 \theta_1^{(i+2)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \frac{\lambda_1 + \lambda_2}{2} a_{12} & \frac{\lambda_1 + \lambda_3}{2} a_{13} & \frac{\lambda_1 + \lambda_4}{2} a_{14} \\ \frac{\lambda_1 + \lambda_2}{2} a_{12} & \lambda_2 \theta_1^{i^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \frac{\lambda_2 + \lambda_3}{2} a_{23} & \frac{\lambda_2 + \lambda_4}{2} a_{24} \\ \frac{\lambda_1 + \lambda_3}{2} a_{13} & \frac{\lambda_2 + \lambda_3}{2} a_{23} & \lambda_3 \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+2)^2} & \frac{\lambda_3 + \lambda_4}{2} a_{34} \\ \frac{\lambda_1 + \lambda_4}{2} a_{14} & \frac{\lambda_2 + \lambda_4}{2} a_{24} & \frac{\lambda_3 + \lambda_4}{2} a_{34} & \lambda_4 \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} \end{bmatrix}$$

where

$$\begin{aligned} a_{12} &= \theta_1^{(i+1)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2}; a_{13} = \theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+2)^2}; a_{14} = \theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}; \\ a_{23} &= \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+2)^2}; a_{24} = \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}; a_{34} = \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+1)^2}, \\ \text{for } i &= 0, \dots, j; j = 0, \dots, k; k = 0, \dots, n-2; \text{ and } T = (\nabla U, \nabla V, \nabla W, \nabla Z) \end{aligned}$$

We prove that there exists a positive constant C_2 independent of $t \in [0, T_{\max}]$ such that

$$I_1 \leq C_2 \text{ for all } t \in [0, T_{\max}] \quad (2.15)$$

and that

$$I_2 \leq 0 \quad (2.16)$$

for several boundary conditions.

i) If $0 < \lambda < 1$, using the boundary conditions (2.5) we get

$$I_1 = \int_{\partial\Omega} (\lambda_1 \partial_U H_n(\gamma_1 - \alpha U) + \lambda_2 \partial_V H_n(\gamma_2 - \alpha V) + \lambda_3 \partial_W H_n(\gamma_3 - \alpha W) + \lambda_4 \partial_Z H_n(\gamma_4 - \alpha Z)) dx,$$

where $\alpha = \frac{\lambda}{1-\lambda}$ and $\gamma_i = \frac{\rho_i}{1-\lambda}$, $i = 1, 2, 3, 4$.

Since

$$\begin{aligned} K(U, V, W, Z) &= \lambda_1 \partial_U H_n(\gamma_1 - \alpha U) + \lambda_2 \partial_V H_n(\gamma_2 - \alpha V) + \lambda_3 \partial_W H_n(\gamma_3 - \alpha W) \\ &\quad + \lambda_4 \partial_Z H_n(\gamma_4 - \alpha Z) = P_{n-1}(U, V, W, Z) - Q_n(U, V, W, Z) \end{aligned}$$

where P_{n-1} and Q_n are polynomials with positive coefficients and respective degrees $(n-1)$ and n and since the solution is positive, then,

$$\limsup_{(|U|+|V|+|W|) \rightarrow \infty} K(U, V, W, Z) = -\infty \quad (2.17)$$

which proves that K is uniformly bounded on \mathbb{R}_+^4 and consequently (2.15).

(ii) If $\lambda = 0$, then $I_1 = 0$ on $[0, T_{\max}]$.

(iii) The case of homogeneous Dirichlet conditions is trivial, since in this case the positivity of the solution on $[0, T_{\max}] \times \Omega$ implies $\partial_\eta U \leq 0$, $\partial_\eta V \leq 0$, $\partial_\eta W \leq 0$, and $\partial_\eta Z \leq 0$ on $[0, T_{\max}] \times \partial\Omega$. Consequently one gets again (2.15) with $C_2 = 0$.

Now we prove (2.16). The quadratic forms (with respect to $\nabla U, \nabla V, \nabla W$ and ∇Z) associated with the matrixes B_{ijk} , $i = 0, \dots, j$; $j = 0, \dots, k$ and $k = 0, \dots, n - 2$ are positive since their main determinants $\Delta_1, \Delta_2, \Delta_3$ and Δ_4 are positive , too . To see this, we have :

$$1. \quad \Delta_1 = \lambda_1 \theta_1^{(i+2)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} > 0 \text{ for } i = 0, \dots, j ; j = 0, \dots, k ; \text{ and } k = 0, \dots, n - 2$$

2.

$$\begin{aligned} \Delta_2 &= \begin{vmatrix} \lambda_1 \theta_1^{(i+2)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \frac{\lambda_1 + \lambda_2}{2} \theta_1^{(i+1)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} \\ \frac{\lambda_1 + \lambda_2}{2} \theta_1^{(i+1)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \lambda_2 \theta_1^{i^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} \end{vmatrix} \\ &= \lambda_1 \lambda_2 \theta_1^{2(i+1)^2} \theta_2^{2(j+2)^2} \theta_3^{2(k+2)^2} (\theta_1^2 - A_{12}^2), \end{aligned}$$

for $i = 0, \dots, j ; j = 0, \dots, k$ and $k = 0, \dots, n - 2$. Using (2.9), we get $\Delta_2 > 0$.

3.

$$\begin{aligned} \Delta_3 &= \begin{vmatrix} \lambda_1 \theta_1^{(i+2)^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \frac{\lambda_1 + \lambda_2}{2} a_{12} & \frac{\lambda_1 + \lambda_3}{2} a_{13} \\ \frac{\lambda_1 + \lambda_2}{2} a_{12} & \lambda_2 \theta_1^{i^2} \theta_2^{(j+2)^2} \theta_3^{(k+2)^2} & \frac{\lambda_2 + \lambda_3}{2} a_{23} \\ \frac{\lambda_1 + \lambda_3}{2} a_{13} & \frac{\lambda_2 + \lambda_3}{2} a_{23} & \lambda_3 \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+2)^2} \end{vmatrix} \\ &= \lambda_1 \lambda_2 \lambda_3 \theta_1^{2(i+2)^2} \theta_1^{2(i+1)^2} \theta_2^{2(j+2)^2} \theta_2^{2(j+1)^2} \theta_3^{2(k+1)^2} \theta_3^{k^2} \\ &\quad \times [(\theta_1^2 - A_{12}^2) (\theta_2^2 - A_{23}^2) - (A_{13} - A_{12} A_{23})^2] \end{aligned}$$

for $i = 0, \dots, j ; j = 0, \dots, k$ and $k = 0, \dots, n - 2$. Using (2.10), we get $\Delta_3 > 0$.

4.

$$\begin{aligned} \Delta_4 &= |B_{ijk}| = \left(\lambda_1 \lambda_2 \lambda_3 \lambda_{43} \theta_1^{2(i+2)^2} \theta_1^{2(i+1)^2} \theta_2^{2(j+1)^2} \theta_2^{j^2} \theta_3^{2(k+1)^2} \theta_3^{k^2} \right) \\ &\quad \times [(\theta_1^2 - A_{12}^2) (\theta_2^2 - A_{23}^2) (\theta_3^2 - A_{34}^2) - (A_{13} - A_{12} A_{23})^2 - (A_{14} - A_{13} A_{24})^2] \end{aligned}$$

for $i = 0, \dots, j ; j = 0, \dots, k$ and $k = 0, \dots, n - 2$. Using (2.11) , we get $\Delta_4 > 0$.

Substituting the expressions of the partial derivatives given by lemma 1 in the

second integral, yields

$$\begin{aligned}
J &= \int_{\Omega} n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i \left(\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} F_1 + \theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2} F_2 + \theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+1)^2} F_3 \right. \\
&\quad \left. + \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} F_4 \right) U^i V^{j-i} W^{k-j} Z^{(n-1)-k} dx = \int_{\Omega} \left(n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i U^i V^{j-i} W^{k-j} Z^{(n-1)-k} \right) \\
&\quad \times \left(\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} F_1 + \frac{\theta_1^{i^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} F_2 + \frac{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} F_3 + F_4 \right) \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} dx. \\
&= \int_{\Omega} \left(n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i U^i V^{j-i} W^{k-j} Z^{(n-1)-k} \right) \left(\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} F_1 + \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} F_2 \right. \\
&\quad \left. + \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} F_3 + F_4 \right) \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} dx.
\end{aligned}$$

Using the expressions (2.8), we obtain

$$\begin{aligned}
J &= \int_{\Omega} \left(n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i U^i V^{j-i} W^{k-j} Z^{(n-1)-k} \right) \\
&\quad \times \left[\left(-\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} - \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + 1 \right) f_1 \right. \\
&\quad + \left(-\frac{2(b-c)}{d+\mu} \frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} - \frac{2(b-c)}{d-\mu} \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{2(b+c)}{d-\mu} \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + \frac{2(b+c)}{d+\mu} \right) f_2 \\
&\quad + \left(\frac{2(b-c)}{d+\mu} \frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} + \frac{2(b-c)}{d-\mu} \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{2(b+c)}{d-\mu} \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + \frac{2(b+c)}{d+\mu} \right) f_3 \\
&\quad \left. + \left(\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} + \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + 1 \right) f_4 \right] \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} dx
\end{aligned}$$

And so we get the following inequality:

$$\begin{aligned}
J &\leq \int_{\Omega} \left(n \sum_{k=0}^{n-1} \sum_{j=0}^k \sum_{i=0}^j C_{n-1}^k C_k^j C_j^i U^i V^{j-i} W^{k-j} Z^{(n-1)-k} \right) \\
&\quad \times \left[\left(-\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} - \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + 1 \right) f_1 \right. \\
&\quad + \left(-\frac{2(b-c)}{d+\mu} \frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} - \frac{2(b-c)}{d-\mu} \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{2(b+c)}{d-\mu} \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + \frac{2(b+c)}{d+\mu} \right) f_2 \\
&\quad + \left(\frac{\theta_1^{(i+1)^2} \theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2}} + \frac{\theta_2^{(j+1)^2} \theta_3^{(k+1)^2}}{\theta_2^{i^2} \theta_3^{k^2}} + \frac{\theta_3^{(k+1)^2}}{\theta_3^{k^2}} + 1 \right) f_3 + f_4 \left. \right] \\
&\quad \times \theta_1^{i^2} \theta_2^{j^2} \theta_3^{k^2} dx,
\end{aligned}$$

using condition (1.10) , and relation (2.6) successively, we get

$$J \leq C_4 \int_{\Omega} \int_{\Omega} n \sum_{p=0}^{n-1} \sum_{q=0}^p C_{n-1}^p C_p^q U^q V^{p-q} W^{(n-1)-p} (U + V + W + 1) dx.$$

Following the same reasoning as in S. Kouachi[6], a straight forward calculation shows that

$$L'(t) \leq C_5 L(t) + C_6 L^{\frac{n-1}{n}}(t) \text{ on } [0, T^*],$$

which for $Z = L^{\frac{1}{n}}$ can be written as

$$nZ' \leq C_5 Z + C_6.$$

A simple integration gives the uniform bound of the functional L on the interval $[0, T^*]$; this ends the proof of the theorem.

Proof of corollary 1. The proof of this corolarly is an immediate consequence of the theorem and the inequality

$$\int_{\Omega} (U + V + W + Z)^P dx \leq C_8 L(t) \text{ on } [0, T^*[,$$

for some $P \geq 1$, taking into consideration expressions (2.7).

Proof of proposition 2. As it has been mentioned above; it suffices to derive a uniforme estimate of $\|F_1(U, V, W, Z)\|_p$, $\|F_2(U, V, W, Z)\|_p$, $\|F_3(U, V, W, Z)\|_p$ and $\|F_4(U, V, W, Z)\|_p$ on $[0, T^*]$ for some $p > \frac{N}{2}$. Since the functions f_1, f_2, f_3 and f_4 are polynomially bounded on Σ , then using relations (2.5), (2.7) and (2.8), we get that F_1, F_2, F_3 and F_4 are polynomially bounded, too and the proof becomes an immediate consequence of corollary 1.

3 Final Remarks

1. In the case when the system (1.1) – (1.4) rewritten as follows:

$$\frac{\partial u}{\partial t} - a\Delta u - b\Delta v - c\Delta w = f_1(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (3.1)$$

$$\frac{\partial v}{\partial t} - c\Delta u - a\Delta v - d\Delta w - b\Delta z = f_2(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (3.2)$$

$$\frac{\partial w}{\partial t} - b\Delta u - d\Delta v - a\Delta w - c\Delta z = f_3(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (3.3)$$

$$\frac{\partial z}{\partial t} - c\Delta v - b\Delta w - a\Delta z = f_4(u, v, w, z) \quad \text{in } R^+ \times \Omega \quad (3.4)$$

with the same boundary conditions (1.5) and initial data (1.6), and the diffusion matrix

$$\begin{pmatrix} a & b & c & d \\ c & a & b & 0 \\ 0 & b & a & c \\ d & c & b & a \end{pmatrix},$$

All the previous results remain valid in the region

$$\Sigma = \left\{ (u_0, v_0, w_0, z_0) \in \mathbb{R}^4 \text{ such that: } u_0 \leq -\frac{2(b-c)}{d-\mu} (v_0 - w_0) + z_0, \right. \\ \left. , u_0 \leq -\frac{2(b-c)}{d+\mu} (v_0 - w_0) + z_0, , u_0 + \frac{2(b+c)}{d-\mu} (v_0 + w_0) + z_0 \geq 0 \right. \\ \left. \text{and } u_0 + \frac{2(b+c)}{d+\mu} (v_0 + w_0) + z_0 \geq 0, \right\} \quad (3.5)$$

and system (2.1) – (2.4) becomes

$$\begin{cases} \frac{\partial U}{\partial t} - \left(a - \frac{1}{2}(d - \mu) \right) \Delta U = F_{11}(U, V, W, Z) \\ \frac{\partial V}{\partial t} - \left(a - \frac{1}{2}(d + \mu) \right) \Delta V = F_{21}(U, V, W, Z) \\ \frac{\partial W}{\partial t} - \left(a + \frac{1}{2}(d - \mu) \right) \Delta W = F_{31}(U, V, W, Z) \\ \frac{\partial Z}{\partial t} - \left(a + \frac{1}{2}(d + \mu) \right) \Delta Z = F_{41}(U, V, W, Z) \end{cases} \quad (3.6)$$

where

$$\begin{cases} U(t, x) = -u(t, x) + \frac{2(b-c)}{d+\mu} (w(t, x) - v(t, x)) + z(t, x) \\ V(t, x) = -u(t, x) + \frac{2(b-c)}{d-\mu} (w(t, x) - v(t, x)) + z(t, x) \\ W(t, x) = u(t, x) + \frac{2(b+c)}{d-\mu} (v(t, x) + w(t, x)) + z(t, x) \\ Z(t, x) = u(t, x) + \frac{2(b+c)}{d+\mu} (v(t, x) + w(t, x)) + z(t, x) \end{cases}$$

for all (t, x) in $]0, T^*[\times \Omega$

$$\begin{cases} F_{11}(U, V, W, Z) = \left(-f_1 + \frac{2(b-c)}{d-\mu} (f_3 - f_2) + f_4 \right) (u, v, w, z) \\ F_{12}(U, V, W, Z) = \left(-f_1 + \frac{2(b-c)}{d+\mu} (f_3 - f_2) + f_4 \right) (u, v, w, z) \\ F_{13}(U, V, W, Z) = \left(f_1 + \frac{2(b+c)}{d-\mu} (f_2 + f_3) + f_4 \right) (u, v, w, z) \\ F_{14}(U, V, W, Z) = \left(f_1 + \frac{2(b+c)}{d+\mu} (f_2 + f_3) + f_4 \right) (u, v, w, z) \end{cases} \quad (3.7)$$

for all (u, v, w, z) in \sum

With the boundary conditions

$$\begin{cases} \lambda U + (1 - \lambda) \frac{\partial U}{\partial \eta} = \rho_1 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda V + (1 - \lambda) \frac{\partial V}{\partial \eta} = \rho_2 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda W + (1 - \lambda) \frac{\partial W}{\partial \eta} = \rho_3 & \text{in }]0, T^*[\times \partial \Omega \\ \lambda Z + (1 - \lambda) \frac{\partial Z}{\partial \eta} = \rho_4 & \text{in }]0, T^*[\times \partial \Omega \end{cases} \quad (3.8)$$

where

$$\left\{ \begin{array}{l} \rho_1 = -\beta_1 + \frac{2(b-c)}{d-\mu} (\beta_3 - \beta_2) + \beta_4 \\ \rho_2 = -\beta_1 + \frac{2(b-c)}{d+\mu} (\beta_3 - \beta_2) + \beta_4 \\ \rho_3 = \beta_1 + \frac{2(b+c)}{d-\mu} (\beta_2 + \beta_3) + \beta_4 \\ \rho_4 = \beta_1 + \frac{2(b+c)}{d+\mu} (\beta_2 + \beta_3) + \beta_4 \end{array} \right. \quad (3.9)$$

and initial data (1.5).

The conditions (1.8) – (1.12) become respectively:

$$\begin{aligned} & \left(f_1 + \frac{2(b+c)}{d-\mu} (f_2 + f_3) + f_4 \right) (-\frac{2(b+c)}{d-\mu} (v+w) - z, v, w, z) \geq 0 \\ & \left(-f_1 - \frac{2(b-c)}{d+\mu} (f_2 - f_3) + f_4 \right) (-\frac{2(b-c)}{d+\mu} (v-w) + z, v, w, z) \geq 0 \\ & \left(f_1 + \frac{2(b+c)}{d-\mu} (f_2 + f_3) + f_4 \right) (-\frac{2(b+c)}{d-\mu} (v+w) - z, v, w, z) \geq 0 \\ & \left(f_1 + \frac{2(b+c)}{d+\mu} (f_2 + f_3) + f_4 \right) (-\frac{2(b+c)}{d+\mu} (v+w) - z, v, w, z) \geq 0 \end{aligned}$$

2. When the system (1.1) – (1.4) rewritten as follows:

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} - a\Delta u - b\Delta v - c\Delta w - d\Delta z = f_1(u, v, w, z) \\ \frac{\partial v}{\partial t} - c\Delta u - a\Delta v - b\Delta w = f_2(u, v, w, z) \\ \frac{\partial w}{\partial t} - b\Delta v - a\Delta w - c\Delta z = f_3(u, v, w, z) \\ \frac{\partial z}{\partial t} - d\Delta u - c\Delta v - b\Delta w - a\Delta z = f_4(u, v, w, z) \end{array} \right.$$

or

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t} - a\Delta u - b\Delta v - c\Delta w - d\Delta z = f_1(u, v, w, z) \\ \frac{\partial v}{\partial t} - a\Delta v - c\Delta w - b\Delta z = f_2(u, v, w, z) \\ \frac{\partial w}{\partial t} - b\Delta u - c\Delta v - a\Delta w = f_3(u, v, w, z) \\ \frac{\partial z}{\partial t} - d\Delta u - c\Delta v - b\Delta w - a\Delta z = f_4(u, v, w, z) \end{array} \right.,$$

all the previous results remain valid in the region

$$\begin{aligned} \sum = & \left\{ (u_0, v_0, w_0, z_0) \in \mathbb{R}^4 \text{ such that: } u_0 \leq -\frac{2(b-c)}{d-\mu} (v_0 - w_0) + z_0, \right. \\ & u_0 \leq -\frac{2(b-c)}{d+\mu} (v_0 - w_0) + z_0, u_0 + \frac{2(b+c)}{d-\mu} (v_0 + w_0) + z_0 \geq 0 \\ & \left. \text{and } u_0 + \frac{2(b+c)}{d+\mu} (v_0 + w_0) + z_0 \geq 0 \right\}, \end{aligned}$$

for the first system.

$$\begin{aligned} \sum = & \left\{ (u_0, v_0, w_0, z_0) \in \mathbb{R}^4 \text{ such that: } u_0 \leq -\frac{2(b-c)}{d-\mu} (v_0 - w_0) + z_0, \right. \\ & u_0 \leq -\frac{2(b-c)}{d+\mu} (v_0 - w_0) + z_0, u_0 + \frac{2(b+c)}{d-\mu} (v_0 + w_0) + z_0 \geq 0 \\ & \left. \text{and } u_0 + \frac{2(b+c)}{d+\mu} (v_0 + w_0) + z_0 \geq 0 \right\}, \end{aligned}$$

for the second system

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