

**BOUNDARY PROPERTIES OF SECOND-ORDER PARTIAL DERIVATIVES OF THE POISSON INTEGRAL FOR A HALF-SPACE  $\mathbb{R}_+^{k+1}$  ( $k > 1$ )**

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ABSTRACT. The boundary properties of second-order partial derivatives of the Poisson integral are studied for a half-space  $\mathbb{R}_+^{k+1}$ .

In this paper, the theorems generalizing the author's previous results [1-5] are proved. It is the continuation of [6] and uses the same notation. Let us recall some of them.

Let  $M = \{1, 2, \dots, k\}$  ( $k \geq 2$ ) and  $B \subset M$ ,  $B' = M \setminus B$ . For every  $x \in \mathbb{R}^k$  and for an arbitrary  $B \subset M$  the symbol  $x_B$  denotes a point from  $\mathbb{R}^k$  whose coordinates with indices from the set  $B$  coincide with the respective coordinates of the point  $x$ , while the coordinates with indices from the set  $B'$  are zeros ( $x_M = x$ ,  $B \setminus i = B \setminus \{i\}$ ); if  $B = \{i_1, i_2, \dots, i_s\}$ ,  $1 \leq s \leq k$  ( $i_l < i_r$  for  $l < r$ ), then  $\bar{x}_B = (x_{i_1}, x_{i_2}, \dots, x_{i_s}) \in \mathbb{R}^s$ ;  $m(B)$  is the number of elements of the set  $B$ ;  $\tilde{L}(\mathbb{R}^k)$  is the set of functions  $f(x) = f(x_1, x_2, \dots, x_k)$  such that  $\frac{f(x)}{(1+|x|)^{\frac{k+1}{2}}} \in L(\mathbb{R}^k)$ ;  $\mathbb{R}_+^{k+1} = \{(x_1, x_2, \dots, x_{k+1}) \in \mathbb{R}^{k+1}; x_{k+1} > 0\}$  (half-space);  $\Delta_x = \Delta_{x_1 x_2 \dots x_k} = \sum_{i=1}^k \frac{\partial^2}{\partial x_i^2}$ ; the Poisson integral of the function  $f(x)$  for the half-space  $\mathbb{R}_+^{k+1}$  is

$$u(f; x, x_{k+1}) = \frac{x_{k+1} \Gamma(\frac{k+1}{2})}{\pi^{\frac{k+1}{2}}} \int_{\mathbb{R}^k} \frac{f(t) dt}{(|t-x|^2 + x_{k+1}^2)^{\frac{k+1}{2}}}.$$

As in [6], we use the following generalization of dihedral-angular limit introduced by O. P. Dzagnidze: if the point  $N \in \mathbb{R}_+^{k+1}$  tends to the point

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$\mathcal{P}(x^0, 0)$  by the condition  $x_{k+1}(\sum_{i \in B} (x_i - x_i^0)^2)^{-1/2} \geq C > 0$ ,<sup>1</sup> then we shall

write  $N(x, x_{k+1}) \xrightarrow{x_B} \mathcal{P}(x^0, 0)$ .

If  $B = M$ , then we have an angular limit and write  $N(x, x_{k+1}) \xrightarrow{\Delta} \mathcal{P}(x^0, 0)$ . Finally, the notation  $N(x, x_{k+1}) \rightarrow \mathcal{P}(x^0, 0)$  means that the point  $N$  tends to  $\mathcal{P}$  arbitrarily, remaining in the half-space  $\mathbb{R}_+^{k+1}$ .

Let  $u \in \mathbb{R}$ ,  $v \in \mathbb{R}$ . We shall consider the following derivatives of the function  $f(x)$ :

1. The limit

$$\lim_{(u, \bar{x}_B) \rightarrow (0, \bar{x}_B^0)} \frac{f(x_B + x_{B'}^0 + ue_i) + f(x_B + x_{B'}^0 - ue_i) - 2f(x_B + x_{B'}^0)}{u^2}$$

is denoted by:

- (a)  $\mathcal{D}_{x_i}^2 f(x^0)$  if  $B = \emptyset$ ;
- (b)  $\mathcal{D}_{x_i(\bar{x}_B)}^2 f(x^0)$  if  $i \in B'$ ;
- (c)  $\overline{\mathcal{D}}_{x_i(\bar{x}_B)}^2 f(x^0)$  if  $i \in B$ .

2. The limit

$$\lim_{\substack{(u,v) \rightarrow (0,0) \\ \bar{x}_B \rightarrow \bar{x}_B^0}} \left[ \frac{f(x_B + x_{B'}^0 + ue_i + ve_j) - f(x_B + x_{B'}^0 + ue_i)}{uv} - \frac{f(x_B + x_{B'}^0 + ve_j) - f(x_B + x_{B'}^0)}{uv} \right]$$

is denoted by:

- (a)  $\mathcal{D}_{x_i x_j} f(x_0)$  if  $B = \emptyset$ ;
- (b)  $\mathcal{D}_{x_i x_j(\bar{x}_B)} f(x^0)$  if  $\{i, j\} \subset B'$ ;
- (c)  $\mathcal{D}_{[x_i x_j](\bar{x}_B)} f(x^0)$  if  $\{i, j\} \subset B$ ;
- (d)  $\mathcal{D}_{[x_i] x_j(\bar{x}_B)} f(x^0)$  if  $i \in B, j \in B'$ .

3. The limit

$$\lim_{\substack{(u,v) \rightarrow (0,0) \\ \bar{x}_B \rightarrow \bar{x}_B^0}} \left[ \frac{f(x_B + x_{B'}^0 + ue_i + ve_j) - f(x_B + x_{B'}^0 + ue_i - ve_j)}{4uv} - \frac{f(x_B + x_{B'}^0 - ue_i + ve_j) - f(x_B + x_{B'}^0 - ue_i - ve_j)}{4uv} \right]$$

is denoted by:

- (a)  $\mathcal{D}_{x_i x_j}^* f(x_0)$  if  $B = \emptyset$ ;
- (b)  $\mathcal{D}_{x_i x_j(\bar{x}_B)}^* f(x^0)$  if  $\{i, j\} \subset B'$ ;
- (c)  $\mathcal{D}_{[x_i x_j](\bar{x}_B)}^* f(x^0)$  if  $\{i, j\} \subset B$ ;
- (d)  $\mathcal{D}_{[x_i] x_j(\bar{x}_B)}^* f(x^0)$  if  $i \in B, j \in B'$ .

<sup>1</sup>Here and in what follows  $C$  denotes absolute positive constants which, generally speaking, can be different in different relations.

## 4. The limit

$$\lim_{\substack{\rho \rightarrow 0 \\ x_B + x_{B'}^0 \rightarrow x^0}} \frac{\frac{1}{|S_\rho|} \int_{S_\rho(x_B + x_{B'}^0)} f(t) dS(t) - f(x_B + x_{B'}^0)}{\rho^2/2k},$$

where  $S_\rho(x)$  is the sphere in  $\mathbb{R}^k$  with center at  $x$ , and radius  $\rho$ , and the  $(k-1)$ -dimensional surface area  $|S_\rho(x)|$  is denoted by:

- (a)  $\bar{\Delta}f(x^0)$  if  $B = \emptyset$ ;
- (b)  $\bar{\Delta}_x f(x^0)$  if  $B = M$ ;
- (c)  $\bar{\Delta}_{x_B} f(x^0)$  if  $B \neq \emptyset$  and  $B \neq M$ .

*Remark.* The  $\lambda$ -derivatives of a function of two variables have been studied by the author in [1, 2] and hence are not considered here.

The following propositions are valid:

(1) For any  $B \subset M$ , the existence of  $\bar{D}_{x_i(\bar{x}_B)}^2 f(x^0)$  implies that there exists  $\mathcal{D}_{x_i(\bar{x}_B \setminus i)} f(x^0)$  and

$$\bar{D}_{x_i(\bar{x}_B)} f(x^0) = \mathcal{D}_{x_i(\bar{x}_B \setminus i)}^2 f(x^0) = \mathcal{D}_{x_i}^2 f(x^0).$$

If there exists  $f''_{x_i^2}(x^0)$ , then  $\mathcal{D}_{x_i}^2 f(x^0)$  exists too, and they have the same value.

(2) If in the neighborhood of the point  $x^0$  there exists a partial derivative  $f''_{x_i^2}(x)$  which is continuous at  $x^0$ , then  $\bar{D}_{x_i(x)}^2 f(x^0)$  exists too and  $\bar{D}_{x_i(x)}^2 f(x^0) = f''_{x_i^2}(x^0)$ .

Indeed, if we apply the Cauchy formula for the function  $f(x + ue_i) + f(x - ue_i) - 2f(x^0)$  and for  $u^2$  with respect to  $u$ , then we have

$$\begin{aligned} & \frac{f(x + ue_i) + f(x - ue_i) - 2f(x^0)}{u^2} = \\ & = \frac{f'_{x_i}(x + \theta(x)ue_i) - f'_{x_i}(x - \theta(x)ue_i)}{2\theta(x)u}, \quad 0 < \theta < 1. \end{aligned}$$

Now applying the Lagrange formula, we obtain

$$\begin{aligned} & \frac{f(x + ue_i) + f(x - ue_i) - 2f(x^0)}{u^2} = \\ & = \frac{2\theta u f''_{x_i^2}(x - \theta ue_i + 2\theta_1 \theta ue_i)}{2\theta u} = f''_{x_i^2}(x - \theta ue_i + 2\theta_1 \theta ue_i), \quad 0 < \theta < 1, \end{aligned}$$

which by the continuity of  $f''_{x_i^2}(x)$  implies that Proposition (2) is valid.

Note that the continuity of the partial derivative  $f''_{x_i^2}(x)$  at  $x^0$  is only a sufficient condition for the existence of the derivative  $\bar{D}_{x_i(\bar{x}_B)}^2 f(x^0)$  for any  $B \subset M$ .

(3) If in the neighborhood of the point  $x$  there exists a derivative  $f''_{x_i x_j}(x)$  which is continuous at  $x^0$ , then there exists  $\overline{\mathcal{D}}_{[x_i x_j](x)} f(x^0)$  and  $\overline{\mathcal{D}}_{[x_i x_j](x)} f(x^0) = f''_{x_i x_j} f(x^0)$ .

The continuity of  $f''_{x_i x_j}(x)$  at the point  $x^0$  is only a sufficient condition for the existence of  $\mathcal{D}_{[x_i x_j](x)} f(x^0)$ .

(4) If for the function  $f(x)$  at  $x^0$  there exists  $\mathcal{D}_{x_i x_j} f(x^0)$ , then at the same point there exists  $\mathcal{D}^*_{x_i x_j} f(x^0)$ , and their values coincide.

(5) If the function  $f(x)$  at the point  $x^0$  has continuous partial derivatives up to second order inclusive, then at the same point there exists  $\overline{\Delta} f(x^0)$ , and  $\overline{\Delta} f(x^0) = \Delta f(x^0)$  (see [7], p. 18).

In what follows it will always be assumed that  $f \in \tilde{L}(\mathbb{R}^k)$ .

The next lemma is proved analogously to the lemma from [6].

**Lemma 1.** For every  $(x_1, x_1, \dots, x_k)$  the following equalities are valid:

$$\int_{-\infty}^{\infty} \frac{(k+3)(t_i - x_i)^2 - |t - x|^2 - x_{k+1}^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} dt_i = 0,$$

$$\int_{\mathbb{R}^k} \frac{(k+3)(t_i - x_i)^2 - |t - x|^2 - x_{k+1}^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} f(t - t_i e_i + x_i e_i) dt = 0,$$

$$\frac{(k+1)x_{k+1}\Gamma(\frac{k+1}{2})}{2\pi^{\frac{k+1}{2}}} \int_{\mathbb{R}^k} \frac{(k+3)(t_i - x_i)^2 - |t - x|^2 - x_{k+1}^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} t_i^2 dt = 1.$$

**Theorem 1.**

(a) If at the point  $x^0$  there exists a finite derivative  $\overline{\mathcal{D}}^2_{x_i(x)} f(x^0)$ , then

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} = \mathcal{D}^2_{x_i} f(x^0). \quad (1)$$

(b) There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that for any  $B \subset M$ ,  $m(B) < k$  all derivatives  $\overline{\mathcal{D}}^2_{x_i(\bar{x}_B)} f(0) = 0$ ,  $i = 1, k$ , but the limits

$$\lim_{x_{k+1} \rightarrow 0+} \frac{\partial^2 u(f; 0, x_{k+1})}{\partial x_i^2}$$

do not exist.

*Proof of part (a).* Let  $x^0 = 0$ ,  $C_k = \frac{(k+1)\Gamma(\frac{k+1}{2})}{\pi^{\frac{k+1}{2}}}$ . It is easy to verify that

$$\frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} = C_k x_{k+1} \int_{\mathbb{R}^k} \frac{(k+3)(t_i - x_i)^2 - |t - x|^2 - x_{k+1}^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} f(t) dt =$$

$$\begin{aligned}
 &= C_k x_{k+1} \int_{\mathbb{R}^k} \frac{(k+3)t_i^2 - |t|^2 - x_{k+1}^2}{(|t|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} f(x+t) dt = \\
 &= C_k x_{k+1} \int_{\mathbb{R}^k} \frac{(k+3)t_i^2 - |t|^2 - x_{k+1}^2}{(|t|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} f(x+t - 2t_i e_i) dt.
 \end{aligned}$$

By Lemma 1 this gives

$$\begin{aligned}
 \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} - \overline{\mathcal{D}}_{x_i(x)}^2 f(0) &= \frac{1}{2} c_k x_{k+1} \int_{\mathbb{R}^k} \frac{[(k+3)t_i^2 - |t|^2 - x_{k+1}^2] t_i^2}{(|t|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\
 &\times \left[ \frac{f(x+t) + f(x+t - 2t_i e_i) - 2f(x+t - t_i e_i)}{t_i^2} - \overline{\mathcal{D}}_{x_i(x)}^2 f(0) \right] dt,
 \end{aligned}$$

which implies that equality (1) is valid.

*Proof of part (b).* Assume  $D = [0 \leq t_1 < \infty; 0 \leq t_2 < \infty; 0 \leq t_3 < \infty]$ . Let

$$f(t) = \begin{cases} \sqrt[3]{t_1 t_2 t_3} & \text{if } (t_1, t_2, t_3) \in D, \\ 0 & \text{if } (t_1, t_2, t_3) \in CD. \end{cases}$$

We can easily find that  $\overline{\mathcal{D}}_{x_i(x_j)}^2 f(0) = 0, i, j = 1, 2, 3, i \neq j$ . However, for the given function we have

$$\begin{aligned}
 \frac{\partial^2 u(f; 0, x_4)}{\partial x_1^2} &= \frac{4x_4}{\pi^2} \int_D \frac{6t_1^2 - |t|^2 - x_4^2}{(|t|^2 + x_4^2)^4} \sqrt[3]{t_1 t_2 t_3} dt = \\
 &= \frac{4x_4}{\pi^2} \int_0^\infty \int_0^{\frac{\pi}{2}} \int_0^{\frac{\pi}{2}} \frac{6\rho^2 \sin^2 \vartheta \cos^2 \varphi - \rho^2 - x_4^2}{(\rho^2 + x_4^2)^4} \times \\
 &\times \sqrt[3]{\rho^3 \sin^2 \vartheta \cos \vartheta \sin \varphi \cos \varphi} \rho^2 \sin \vartheta d\rho d\vartheta d\varphi = \\
 &= \frac{C}{x_4} \left( 4 \int_0^{\frac{\pi}{2}} \sqrt[3]{\sin^2 \vartheta \cos \vartheta} \sin^3 \vartheta d\vartheta \int_0^{\frac{\pi}{2}} \sqrt[3]{\sin 2\varphi} \sin^2 \varphi d\varphi - \right. \\
 &\left. - \int_0^{\frac{\pi}{2}} \sqrt[3]{\sin^2 \vartheta \cos \vartheta} \sin \vartheta d\vartheta \int_0^{\frac{\pi}{2}} \sqrt[3]{\sin 2\varphi} d\varphi \right) = \\
 &= \frac{4C}{9x_4} \Gamma\left(\frac{1}{3}\right) \Gamma\left(\frac{2}{3}\right) \int_0^{\frac{\pi}{2}} \left( \sin^2 \varphi - \frac{3}{8} \right) \sqrt[3]{\sin 2\varphi} d\varphi =
 \end{aligned}$$

$$\begin{aligned}
&= \frac{C}{x_4} \left( \int_0^{\arcsin \sqrt{\frac{3}{8}}} + \int_{\arcsin \sqrt{\frac{3}{8}}}^{\frac{\pi}{2} - \arcsin \sqrt{\frac{3}{8}}} + \int_{\frac{\pi}{2} - \arcsin \sqrt{\frac{3}{8}}}^{\frac{\pi}{2}} \right) = \\
&= \frac{C}{x_4} (\mathcal{I}_1 + \mathcal{I}_2 + \mathcal{I}_3).
\end{aligned}$$

Clearly,  $\mathcal{I}_1 < 0$ ,  $\mathcal{I}_2 > 0$ ,  $\mathcal{I}_3 > 0$ . Further,

$$\mathcal{I}_3 = \int_0^{\arcsin \sqrt{\frac{3}{8}}} \left( \cos^2 \varphi - \frac{3}{8} \right) \sqrt[3]{\sin 2\varphi} d\varphi.$$

Since  $\mathcal{I}_1 + \mathcal{I}_3 > 0$ , we have  $\mathcal{I}_1 + \mathcal{I}_2 + \mathcal{I}_3 > 0$ . Finally, we obtain

$$\frac{\partial^2 u(f; 0, x_4)}{\partial x_1^2} \rightarrow +\infty \quad \text{as } x_4 \rightarrow 0+. \quad \square$$

**Corollary.** *If the function  $f$  has a continuous partial derivative  $\frac{\partial^2 f(x)}{\partial x_i^2}$  at the point  $x^0$ , then equality (1) is fulfilled.*

**Theorem 2.**

(a) *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{x_i(x_{M \setminus i})} f(x^0)$ , then*

$$\lim_{(x - x_i e_i + x_i^0 e_i, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x - x_i e_i + x_i^0 e_i, x_{k+1})}{\partial x_i^2} = \mathcal{D}_{x_i}^2 f(x^0).$$

(b) *There exists a function  $f \in L(\mathbb{R}^k)$  such that  $\mathcal{D}_{x_i(x_{M \setminus i})} f(x^0) = 0$ , but the limit*

$$\lim_{(x, x_{k+1}) \xrightarrow{\Delta} (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2}$$

*does not exist.*

*Proof of part (a).* Let  $x^0 = 0$ . By Lemma 1 we easily obtain

$$\begin{aligned}
&\frac{\partial^2 u(f; x - x_i e_i, x_{k+1})}{\partial x_i^2} - \mathcal{D}_{x_i(x_{M \setminus i})}^2 f(0) = \\
&= \frac{1}{2} c_k x_{k+1} \int_{\mathbb{R}^k} \frac{[(k+3)t_i^2 - |t|^2 - x_{k+1}^2] t_i^2}{(|t|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\
&\times \left[ \frac{f(t + x - x_i e_i) + f(t - 2t_i e_i + x - x_i e_i) - 2f(t - t_i e_i + x - x_i e_i)}{t_i^2} - \right. \\
&\quad \left. - \mathcal{D}_{x_i(x_{M \setminus i})}^2 f(0) \right] dt.
\end{aligned}$$

*Proof of part (b).* This will be given for the cases  $i = 1$  and  $k = 2$ . We have

$$\begin{aligned} \frac{\partial^2 u(f; x_1, x_2, x_3)}{\partial x_1^2} &= \frac{3x_3}{2\pi} \int_{\mathbb{R}^2} \frac{4(t_1 - x_1)^2 - (t_2 - x_2)^2 - x_3^2}{(|t - x|^2 + x_3^2)^{7/2}} f(t) dt = \\ &= \frac{3x_3}{2\pi} \int_0^\infty \int_0^{2\pi} \frac{4(\rho \cos \varphi - x_1)^2 - (\rho \sin \varphi - x_2)^2 - x_3^2}{[(\rho \cos \varphi - x_1)^2 + (\rho \sin \varphi - x_2)^2 + x_3^2]^{7/2}} f(\rho \cos \varphi, \rho \sin \varphi) \rho d\rho d\varphi. \end{aligned}$$

Let  $N(x_1, x_2, x_3) \rightarrow (0, 0, 0)$  so that  $x_2 = 0$  and  $x_3 = x_1$ . Then

$$\begin{aligned} \frac{\partial^2 u(f; x_3, 0, x_3)}{\partial x_1^2} &= \\ &= \frac{3x_3}{2\pi} \int_0^\infty \int_0^{2\pi} \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3^2)^{7/2}} f(\rho \cos \varphi, \rho \sin \varphi) \rho d\rho d\varphi. \end{aligned}$$

Using Lemma 1, for any  $x_1, x_2$ , and  $x_3$  we have

$$\int_{\mathbb{R}^2} \frac{4(t_1 - x_1)^2 - (t_2 - x_2)^2 - x_3^2}{(|t - x|^2 + x_3^2)^{7/2}} dt_1 dt_2 = 0,$$

which, in particular, yields

$$\begin{aligned} &\int_0^\infty \int_0^{2\pi} \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3^2)^{7/2}} \rho d\rho d\varphi = \\ &= 2 \int_0^\infty \int_0^\pi \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3^2)^{7/2}} f(\rho \cos \varphi, \rho \sin \varphi) \rho d\rho d\varphi = 0. \end{aligned}$$

Therefore

$$\int_0^\infty \int_0^\pi \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3^2)^{7/2}} \rho d\rho d\varphi = 0. \quad (2)$$

In the interval  $\frac{\pi}{2} \leq \varphi \leq \pi$  we have

$$\begin{aligned} &x_3 \int_0^\infty \int_{\frac{\pi}{2}}^\pi \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3^2)^{7/2}} \rho d\rho d\varphi > \\ &> x_3 \int_0^\infty \int_{\frac{\pi}{2}}^\pi \frac{5\rho^2 \cos^2 \varphi - \rho^2}{(\rho^2 + 2\rho x_3 + 4x_3^2)^{7/2}} \rho d\rho d\varphi = x_3 \int_0^\infty \int_{\frac{\pi}{2}}^\pi \frac{5\rho^2 \cos^2 \varphi - \rho^2}{(\rho + 2x_3)^7} \rho d\rho d\varphi = \end{aligned}$$

$$= \frac{3\pi}{4} x_3 \int_0^\infty \frac{\rho^3 d\rho}{(\rho + 2x_3)^7} > cx_3 \int_0^{x_3} \frac{\rho^3 rho}{(\rho + 2x_3)^7} = \frac{c}{x_3^2}.$$

Hence

$$\lim_{x_3 \rightarrow 0^+} x_3 \int_0^\infty \int_{\frac{\pi}{2}}^\pi \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3)^{7/2}} \rho d\rho d\varphi = +\infty. \tag{3}$$

Equations (2) and (3) imply

$$\lim_{x_3 \rightarrow 0^+} x_3 \int_0^\infty \int_0^{\frac{\pi}{2}} \frac{4\rho^2 \cos^2 \varphi - 8\rho x_3 \cos \varphi - \rho^2 \sin^2 \varphi + 3x_3^2}{(\rho^2 - 2\rho x_3 \cos \varphi + 2x_3)^{7/2}} \rho d\rho d\varphi = -\infty. \tag{4}$$

Next, we define  $f(t_1, t_2)$  as follows:

$$f(t_1, t_2) = \begin{cases} -1 & \text{for } t_1 > 0, \ t_2 > 0, \\ 1 & \text{for } t_1 < 0, \ t_2 > 0, \\ 0 & \text{for } -\infty < t_1 < \infty, \ t_2 \leq 0, \\ 0 & \text{for } t_1 = 0, \ 0 < t_2 < \infty. \end{cases}$$

Clearly, for this function

$$\mathcal{D}_{x_1(x_2)}^2 f(0, 0) = \lim_{(t_1, x_2) \rightarrow (0, 0)} \frac{f(t_1, x_1) + f(-t_1, x_2) - 2f(0, x_2)}{t_1^2} = 0.$$

However, by (3) and (4),  $\frac{\partial^2 u(f; x_1, 0, x_3)}{\partial x_1^2} \rightarrow +\infty$ , as  $(x_1, x_2, x_3) \rightarrow (0, 0, 0)$ .  $\square$

**Lemma 2.** For any  $(x_1, x_2, \dots, x_{k+1})$  the following equalities are valid:

$$\begin{aligned} & \int_{\mathbb{R}^k} \frac{(t_i - x_i)(t_j - x_j)f(t - t_i e_i + x_i e_i)}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} dt = 0, \\ & \int_{\mathbb{R}^k} \frac{(t_i - x_i)(t_j - x_j)f(t - t_i e_i - t_j e_j + x_i e_i + x_j e_j)}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} dt = 0, \\ & \frac{(k + 1)(k + 3)x_{k+1}\Gamma(\frac{k+1}{2})}{2\pi^{\frac{k+1}{2}}} \int_{\mathbb{R}^k} \frac{(t_i - x_i)^2(t_j - x_j)^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} t_i^2 dt = 1. \end{aligned}$$

**Theorem 3.**

(a) If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{[x_i x_j](x)} f(x^0)$ ,  $i \neq j$ , then

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j} f(x^0).$$



(b) *There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that for any  $B \subset M$ ,  $m(B) < k$  all derivatives  $\mathcal{D}_{[x_i x_j](x)} f(0) = 0$ , but the limits*

$$\lim_{x_{k+1} \rightarrow 0^+} \frac{\partial^2 u(f; 0, x_{k+1})}{\partial x_i \partial x_j}$$

*do not exist.*

*Proof of part (a).* Let  $x^0 = 0$  and  $B_k = \frac{(k+1)(k+3)\Gamma(\frac{k+1}{2})}{\pi^{\frac{k+1}{2}}}$ . It is easy to verify that

$$\frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = B_k x_{k+1} \int_{\mathbb{R}^k} \frac{(t_i - x_i)(t_j - x_j) f(t) dt}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}}.$$

By Lemma 2 we obtain

$$\begin{aligned} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} - \mathcal{D}_{[x_i x_j](x)} f(0) &= B_k x_{k+1} \int_{\mathbb{R}^k} \frac{t_i^2 t_j^2}{(|t|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\ &\times \left[ \frac{f(x+t) - f(x+t-t_i e_i) + f(x+t-t_j e_j) + f(x+t-t_i e_i - t_j e_j)}{t_i t_j} - \right. \\ &\left. - \mathcal{D}_{[x_i x_j](x)} f(0) \right] dt, \end{aligned}$$

which implies that part (a) is valid.

*Proof of part (b).* Let  $k = 4$  and  $D = (\sum_{i=1}^4 t_i^2 \leq 1, t_i \geq 0, i = \overline{1, 4})$ . We define  $f$  as  $f(t) = \sqrt[5]{t_1 t_2 t_3 t_4}$  for  $t \in D$ , and extend it continuously to the set  $\mathbb{R}^4 \setminus D$  so that  $f \in L(\mathbb{R}^4)$ . It is easy verify that for any  $B \subset M$ ,  $m(B) < 4$  we have  $\mathcal{D}_{[x_i x_j](x)} f(0) = 0$ . But

$$\begin{aligned} \frac{\partial^2 u(f; 0, x_5)}{\partial x_1 \partial x_1} &= c x_5 \int_D \frac{t_1 t_2 \sqrt[5]{t_1 t_2 t_3 t_4}}{(|t|^2 + x_5^2)^{9/2}} dt + o(1) = \\ &= c x_5 \int_0^1 \frac{\rho^{29/5} d\rho}{(\rho^2 + x_5^2)^{9/2}} + o(1) \rightarrow +\infty \quad \text{as } x_5 \rightarrow 0^+. \quad \square \end{aligned}$$

**Corollary.** *If the function  $f$  at the point  $x^0$  has a continuous derivative  $f''_{x_i x_j}(x)$ , then*

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \frac{\partial^2 f(x^0)}{\partial x_i \partial x_j}.$$

The following theorem is valid by the corollaries of Theorems 1 and 3.

**Theorem 4.** *If the function  $f$  is twice continuously differentiable at the point  $x^0$ , then  $\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} d_x^2 u(f; x, x_{k+1}) = d^2 f(x^0)$ .*

**Theorem 5.**

(a) *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{[x_i]x_j(x)} f(x^0)$ , then*

$$\lim_{\substack{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0) \\ x_j}} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j} f(x^0).$$

(b) *There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that for every  $B \subset M$ ,  $m(B) < k - 1$  all derivatives  $\mathcal{D}_{[x_i]x_j(\bar{x}_B)} f(0) = 0$ , but the limits*

$$\lim_{x_{k+1} \rightarrow 0+} \frac{\partial^2 u(f; 0, x_{k+1})}{\partial x_i \partial x_j}$$

*do not exist.*

**Theorem 6.**

(a) *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{x_i x_j(x_{M \setminus \{i, j\}})} f(x^0)$ , then*

$$\lim_{\substack{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0) \\ x_i x_j}} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j} f(x^0).$$

(b) *There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that for every  $B \subset M$ ,  $m(B) < k - 2$  all derivatives  $\mathcal{D}_{x_i x_j(\bar{x}_B)} f(0) = 0$ , but the limits*

$$\lim_{x_{k+1} \rightarrow 0+} \frac{\partial^2 u(f; 0, x_{k+1})}{\partial x_i \partial x_j}$$

*do not exist.*

**Theorem 7.**

(a) *If the function  $f$  is twice differentiable at the point  $x^0$ , then*

$$\lim_{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0)} d_x^2 u(f; x, x_{k+1}) = d^2 f(x^0).$$

(b) *There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that it is differentiable at the point  $x^0 = (0, 0)$  and has at this point all partial derivatives of any order; however the limits*

$$\lim_{x_{k+1} \rightarrow 0+} \frac{\partial^2 u(f; 0, x_{k+1})}{\partial x_i \partial x_j}, \quad i, j = \overline{1, k}$$

*do not exist.*

*Proof of part (a).* Let  $x^0 = 0$ . The validity of part (a) follows from the equalities

$$\begin{aligned} & \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} - \frac{\partial^2 f(0)}{\partial x_i^2} = \\ & = c_k x_{k+1} \int_{\mathbb{R}^k} \frac{[(k+3)(t_i - x_i)^2 - |t - x|^2 - x_{k+1}^2]|t|^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\ & \times \left[ \frac{f(t) + f(0) - \left(\sum_{\nu=1}^k t_\nu \frac{\partial}{\partial t_\nu}\right)f(0) - \frac{1}{2}\left(\sum_{\nu=1}^k t_\nu \frac{\partial}{\partial t_\nu}\right)^2 f(0)}{|t|^2} dt, \right. \\ & \left. \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} - \frac{\partial^2 f(0)}{\partial x_i \partial x_j} = \right. \\ & = B_k x_{k+1} \int_{\mathbb{R}^k} \frac{(t_i - x_i)(t_j - x_j)|t|^2}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\ & \times \left[ \frac{f(t) + f(0) - \left(\sum_{\nu=1}^k t_\nu \frac{\partial}{\partial t_\nu}\right)f(0) - \frac{1}{2}\left(\sum_{\nu=1}^k t_\nu \frac{\partial}{\partial t_\nu}\right)^2 f(0)}{|t|^2} dt. \right. \end{aligned}$$

*Proof of part (b).* Consider the function equal to  $\sqrt[3]{(2t_1 - t_2)^2(t_2 - \frac{1}{2}t_1)^2}$  when  $(t_1, t_2) \in D = \{(t_1, t_2) \in \mathbb{R}^2: 0 \leq t_1 < \infty; \frac{1}{2}t_1 \leq t_2 \leq 2t_1\}$  and to 0 otherwise, which is continuous in  $\mathbb{R}^2$ , differentiable at the point  $(0, 0)$ , and has all partial derivatives of any order equal to zero, but

$$\begin{aligned} \frac{\partial^2 u(f; 0, 0, x_3)}{\partial x_1 \partial x_2} &= \frac{15x_3}{2\pi} \int_0^\infty dt_1 \int_{\frac{1}{2}t_1}^{2t_1} \frac{t_1 t_2 \sqrt[3]{(2t_1 - t_2)^2(t_2 - \frac{1}{2}t_1)^2}}{(t_1^2 + t_2^2 + x_3^2)^{7/2}} dt_2 > \\ &> cx_3 \int_{x_3}^{2x_3} t_1^2 dt_1 \int_{t_1}^{\frac{3}{2}t_1} \frac{\sqrt[3]{(2t_1 - \frac{3}{2}t_1)^2(t_1 - \frac{1}{2}t_1)^2}}{(t_1^2 + 4t_1^2 + x_3^2)^{7/2}} dt_1 = \\ &= \frac{c}{x_3^6} \int_{x_3}^{2x_3} t_1^{\frac{13}{3}} dt_1 = \frac{c}{\sqrt[3]{x_3^2}} \rightarrow \infty \text{ as } x_3 \rightarrow 0+. \quad \square \end{aligned}$$

**Theorem 8.**

(a) *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{x_i x_j}^* (\bar{x}_M \setminus \{i, j\}) f(x^0)$ , then*

$$\lim_{x_{k+1} \rightarrow 0+} \frac{\partial^2 u(f; x^0, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j}^* f(x^0).$$

(b) *There exists a continuous function  $f \in L(\mathbb{R}^k)$  such that we have  $\mathcal{D}_{x_i x_j (\overline{x_M \setminus \{i,j\}})}^* f(x^0) = 0$ , but the limits*

$$\lim_{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j}$$

*do not exist.*

*Proof of part (b).* This is given for the case  $k = 2$ . Assume that  $D_1 = [0, 1; 0, 1]$ ,  $D_2 = [-1, 0; 0, 1]$ . Let

$$f(t_1, t_2) = \begin{cases} \sqrt{t_1 t_2} & \text{for } (t_1, t_2) \in D_1, \\ \sqrt{-t_1 t_2} & \text{for } (t_1, t_2) \in D_2, \\ 0 & \text{for } t_2 \leq 0 \end{cases}$$

and extend  $f(t_1, t_2)$  continuously to the set  $\mathbb{R}^2 \setminus (D_1 \cup D_2)$  so that  $f \in L(\mathbb{R}^2)$ . It is easy to verify that  $D^* f(0, 0)$ . Let  $x_1^0 = x_2^0 = 0$  and  $(x_1, x_2, x_3) \rightarrow (0, 0, 0)$  so that  $x_2 = 0$  and  $x_3 = x_1$ . Then for the constructed function we have

$$\begin{aligned} \frac{\partial^2 u(f; x_1, x_2, x_3)}{\partial x_1 \partial x_2} &= \frac{15x_3}{2\pi} \left\{ \int_0^1 \int_0^1 \frac{(t_1 - x_1)t_2 \sqrt{t_1 t_2} dt_1 dt_2}{[(t_1 - x_1)^2 + t_2^2 + x_3^2]^{7/2}} + \right. \\ &\quad \left. + \int_{-1}^0 \int_0^1 \frac{(t_1 - x_1)t_2 \sqrt{-t_1 t_2} dt_1 dt_2}{[(t_1 - x_1)^2 + t_2^2 + x_3^2]^{7/2}} \right\} + o(1) = \\ &= cx_1 \left\{ \int_{-x_1}^{1-x_1} \int_0^1 \frac{t_1 t_2 \sqrt{t_2(t_1 + x_1)} dt_1 dt_2}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} - \right. \\ &\quad \left. - \int_{x_1}^{1+x_1} \int_0^1 \frac{t_1 t_2 \sqrt{(t_1 - x_1)t_2} dt_1 dt_2}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} \right\} + o(1) = \\ &= cx_1 \left\{ \int_{-x_1}^{x_1} \int_0^1 \frac{t_1 t_2 \sqrt{t_2(t_1 + x_1)} dt_1 dt_2}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} + \right. \\ &\quad \left. + \int_{x_1}^{1-x_1} \int_0^1 \frac{t_1 t_2 [\sqrt{t_2(x_1 + t_1)} - \sqrt{t_2(t_1 - x_1)}]}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} dt_1 dt_2 - \right. \\ &\quad \left. - \int_{1-x_1}^{1+x_1} \int_0^1 \frac{t_1 t_2 \sqrt{(t_1 - x_1)t_2} dt_1 dt_2}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} \right\} + o(1) = \end{aligned}$$

$$= Cx_1(\mathcal{I}_1 + \mathcal{I}_2 - \mathcal{I}_3) + o(1).$$

We can readily show that

$$\mathcal{I}_1 = \int_0^{x_1} \int_0^1 \frac{t_1 t_2 [\sqrt{t_2(t_1 + x_1)} - \sqrt{t_2(x_1 - t_1)}]}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} dt_1 dt_2 > 0, \quad \mathcal{I}_3 = O(1). \quad (5)$$

Next,

$$\begin{aligned} \mathcal{I}_2 &> \int_{x_1}^{2x_1} \int_0^{x_1} \frac{t_1 t_2 [\sqrt{t_2(x_1 + t_1)} - \sqrt{t_2 x_1}]}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} dt_1 dt_2 = \\ &= \int_0^{x_1} t_2^{3/2} \int_{x_1}^{2x_1} \frac{t_1 (\sqrt{x_1 + t_1} - \sqrt{x_1})}{(t_1^2 + t_2^2 + x_1^2)^{7/2}} dt_1 > \\ &> \int_0^{x_1} t_2^{3/2} \int_{x_1}^{2x_1} \frac{x_1 (\sqrt{2x_1} - \sqrt{x_1})}{(4x_1^2 + x_1^2 + x_1^2)^{7/2}} dt_1 > \frac{c}{x_1^2}. \end{aligned} \quad (6)$$

Therefore for  $x_2 = 0$  and  $x_3 = x_1$  (5) and (6) imply  $\frac{\partial^2 u(f; x_1, 0, x_1)}{\partial x_1 \partial x_2} > \frac{c}{x_1}$ , from which we obtain  $\frac{\partial^2 u(f; x_1, x_2, x_3)}{\partial x_1 \partial x_2} \rightarrow +\infty$ , as  $(x_1, x_2, x_3) \rightarrow (0, 0, 0)$ .  $\square$

**Theorem 9.** *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{[x_i x_j]}^*(x) f(x^0)$ , then*

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j}^* f(x^0).$$

Part (a) of Theorem 3 is the corollary of Theorem 9.

**Theorem 10.** *If at the point  $x^0$  there exists a finite derivative  $\mathcal{D}_{[x_i] x_j}^*(x) f(x^0)$ , then*

$$\lim_{(x - x_j e_j + x_j^0 e_j, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x - x_j e_j + x_j^0 e_j, x_{k+1})}{\partial x_i \partial x_j} = \mathcal{D}_{x_i x_j}^* f(x^0).$$

**Lemma 3.** *The following equalities are valid:*

$$\begin{aligned} \int_0^\infty \frac{2\rho^2 - kx_{k+1}^2}{(\rho^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \rho^{k-1} d\rho &= 0, \\ \frac{(k+1)x_{k+1} \Gamma(\frac{k+1}{2})}{k\sqrt{\pi} \Gamma(\frac{k}{2})} \int_0^\infty \frac{3\rho^2 - kx_{k+1}^2}{(\rho^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \rho^{k+1} d\rho &= 1. \end{aligned}$$

**Theorem 11.**

(a) Let  $B \subset M$ . If at the point  $x^0$  there exists a finite derivative  $\overline{\Delta}_{x_B} f(x^0)$ , then

$$\lim_{x_B + x_{B'}, x_{k+1} \rightarrow (x^0, 0)} \Delta_x u(f; x_B + x_{B'}, x_{k+1}) = \overline{\Delta}_{x_B} f(x^0).$$

(b) There exists a function  $f \in L(\mathbb{R}^k)$  such that  $\overline{\Delta} f(x^0)$  exists but the limit  $\lim_{x, x_{k+1} \rightarrow (x^0, 0)} \Delta_x u(f; x, x_{k+1})$  does not.

*Proof of part (a).* One can easily verify that

$$\begin{aligned} \Delta_x u(f; x, x_{k+1}) &= -\frac{\partial^2 u(f; x, x_{k+1})}{\partial x_{k+1}^2} = \\ &= \frac{(k+1)x_{k+1}\Gamma(\frac{k+1}{2})}{\pi^{\frac{k+1}{2}}} \int_{\mathbb{R}^k} \frac{3|t-x|^2 - kx_{k+1}^2}{(|t-x|^2 + x_{k+1}^2)^{\frac{k+5}{2}}} f(t) dt. \end{aligned}$$

Assume that  $\mathcal{D}_k = \frac{2(k+1)\Gamma(\frac{k+1}{2})}{\sqrt{\pi}\Gamma(\frac{k}{2})}$  and  $\theta = [0, \pi]^{k-2} \times [0, 2\pi]$ . Passing to the spherical coordinates, we have

$$\begin{aligned} \Delta_x u(f; x_B + x_{B'}, x_{k+1}) &= c_k x_{k+1} \int_0^\infty \frac{3\rho^2 - kx_{k+1}^2}{(\rho^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\ &\times \int_{\Theta} f(x_B + x_{B'} + t) \rho^{k-1} \sin^{k-2} \vartheta_1 \cdots \sin \vartheta_{k-2} d\rho d\vartheta_1 \cdots d\vartheta_{k-2} d\varphi = \\ &= \mathcal{D}_k x_{k+1} \int_0^\infty \frac{3\rho^2 - kx_{k+1}^2}{(\rho^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \rho^{k-1} \left[ \frac{1}{|S_\rho|} \int_{S_\rho(x_B + x_{B'})} f(t) dS(t) \right] d\rho. \end{aligned}$$

Hence by Lemma 3 we obtain

$$\begin{aligned} \Delta_x u(f; x_B + x_{B'}, x_{k+1}) - \overline{\Delta}_{x_B} f(x^0) &= \mathcal{D}_k x_{k+1} \int_0^\infty \frac{3\rho^2 - kx_{k+1}^2}{(\rho^2 + x_{k+1}^2)^{\frac{k+5}{2}}} \times \\ &\times \left[ \frac{\frac{1}{|S_\rho|} \int_{S_\rho(x_B + x_{B'})} f(t) dS(t) - f(x_B + x_{B'})}{\rho^2/2k} - \overline{\Delta}_{x_B} f(x^0) \right] \frac{\rho^2}{2k} d\rho. \end{aligned}$$

For the proof of part (b) see [2], p. 16.  $\square$

**Corollary 1.** If at the point  $x^0$  there exists a finite derivative  $\overline{\Delta} f(x^0)$ , then

$$\lim_{x_{k+1} \rightarrow 0^+} \Delta_x u(f; x^0, x_{k+1}) = \overline{\Delta} f(x^0).$$

**Corollary 2.** *If at the point  $x^0$  there exists a finite derivative  $\overline{\Delta}f(x^0)$ , then*

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \Delta_x u(f; x, x_{k+1}) = \overline{\Delta}_x f(x^0).$$

Let  $\delta > 0$  and  $S_\delta = \prod_{\nu=1}^k [x_\nu^0 - \delta; x_\nu^0 + \delta]$ .

**Theorem 12.** *Let  $f'_{t_i}(t) \in L(S_\delta)$ . If  $f'_{t_i}(t)$  has a finite derivative  $\mathcal{D}_{x_i(\overline{x}_M \setminus i)} f'_{x_i}(x^0)$  at the point  $x^0$ , then*

$$\lim_{\substack{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0) \\ x_i}} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} = f''_{x_i}(x^0).$$

*Proof.* Let  $x^0 = 0$ . The validity of the theorem follows from the equality

$$\begin{aligned} & \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} - \mathcal{D}_{x_i(\overline{x}_M \setminus i)} f'_{x_i}(0) = \\ &= c_k x_{k+1} \int_{S_\delta} \frac{(t_i - x_i)t_i}{(|t - x|^2 + x_{k+1}^2)^{\frac{k+3}{2}}} \left[ \frac{f'_{t_i}(t) - f'_{t_i}(t - t_i e_i)}{t_i} - \right. \\ & \quad \left. - \mathcal{D}_{x_i(\overline{x}_M \setminus i)} f'_{x_i}(0) \right] dt + o(1). \quad \square \end{aligned}$$

The theorems below are proved analogously.

**Theorem 13.** *Let  $f'_{x_i}(t) \in L(S_\delta)$ . If  $f'_{x_i}(t)$  has a finite derivative  $\mathcal{D}_{x_j(\overline{x}_M \setminus j)} f'_{x_i}(x^0)$  at the point  $x^0$ , then*

$$\lim_{\substack{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0) \\ x_j}} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \frac{\partial^2 f(x^0)}{\partial x_i \partial x_j}.$$

**Corollary.** *Let  $f'_{x_i}$  and  $f'_{x_j} \in L(S_\delta)$  for some  $\delta > 0$ . If at the point  $x^0$  there exist finite derivatives  $\mathcal{D}_{x_i(\overline{x}_M \setminus i)} f'_{x_j}(x^0)$  and  $\mathcal{D}_{x_j(\overline{x}_M \setminus j)} f'_{x_i}(x^0)$ , then*

$$\lim_{\substack{(x, x_{k+1}) \xrightarrow{\wedge} (x^0, 0) \\ x_i x_j}} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \frac{\partial^2 f(x^0)}{\partial x_i \partial x_j} = \frac{\partial^2 f(x^0)}{\partial x_j \partial x_i}.$$

Note that by this corollary we have obtained the condition of the coincidence of mixed derivatives of the function  $f$  at the point  $x^0$ .

**Theorem 14.** Let  $f'_{x_i} \in L(S_\delta)$  for some  $\delta > 0$ . If at the point  $x^0$  there exists a finite derivative  $\overline{D}_{x_i(x)} f'_{x_i}(x^0)$ , then

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i^2} = \frac{\partial^2 f(x^0)}{\partial x_i^2}.$$

**Theorem 15.** Let  $f'_{x_i} \in L(S_\delta)$ . If  $f'_{x_i}(t)$  has a finite derivative  $\overline{D}_{x_j(x)} f'_{x_i}(x^0)$  at the point  $x^0$ , then

$$\lim_{(x, x_{k+1}) \rightarrow (x^0, 0)} \frac{\partial^2 u(f; x, x_{k+1})}{\partial x_i \partial x_j} = \frac{\partial^2 f(x^0)}{\partial x_i \partial x_j}.$$

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