

THE LIMIT OF MAPPINGS WITH FINITE DISTORTION

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Abstract. We show here that the limit mapping f of a weakly convergent sequence of mappings f_ν with finite distortion also has finite distortion and give several dimension free estimates for the dilatation of f . Our arguments are based on the weak continuity of the Jacobian determinants and the concept of polyconvexity.

1. Introduction

Let $f: \Omega \rightarrow \mathbf{R}^n$ be a mapping in the Sobolev space $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ where Ω is a domain in \mathbf{R}^n . Then the differential matrix $Df(x) \in \mathbf{R}^{n \times n}$ and its determinant $J(x, f) = \det Df(x)$ are well defined at almost every point $x \in \Omega$. Here $\mathbf{R}^{n \times n}$ denotes the space of all $n \times n$ -matrices, where $n > 1$, equipped with the operator norm

$$|A| = \max\{|A\xi| : \xi \in S^{n-1}\}.$$

We assume most of the time that $J(x, f) \geq 0$ a.e. and refer to such mappings f as orientation preserving. We let $\mathbf{R}_+^{n \times n}$ denote the set of matrices with positive determinant and write $\mathbf{R}_+^{n \times n} \cup \{0\}$ when the zero matrix is included.

Definition 1.1. A mapping $f \in W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ is said to be of finite distortion if

$$Df(x) \in \mathbf{R}_+^{n \times n} \cup \{0\}$$

for almost every $x \in \Omega$.

In what follows it is vital that the Sobolev exponent is at least the dimension of Ω so that we can integrate the Jacobian. In this case the mappings of finite distortion are actually continuous [18].

Definition 1.1 asserts that

$$(1.2) \quad |Df(x)|^n \leq K_O(x)J(x, f)$$

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where $1 \leq K_O(x) < \infty$ a.e. The smallest such function defined by

$$(1.3) \quad K_O(x, f) = \frac{|Df(x)|^n}{J(x, f)}$$

if $J(x, f) \neq 0$ and 1 otherwise is called the *outer dilatation* function of f .

We shall establish the following limit theorem.

Theorem 1.4. *Suppose that $f_\nu: \Omega \rightarrow \mathbf{R}^n$ is a sequence of mappings of finite distortion which converges weakly in $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ to f and suppose that*

$$(1.5) \quad K_O(x, f_\nu) \leq M(x) < \infty \quad \text{for } \nu = 1, 2, \dots$$

a.e. in Ω . Then f has finite distortion and

$$(1.6) \quad K_O(x, f) \leq M(x)$$

a.e. in Ω .

Theorem 1.4 is a refinement of Reshetnyak's theorem [15] concerning mappings f_ν of bounded distortion, that is mappings which satisfy (1.5) with $M(x) \leq K$ where K is a constant. In this case, weak convergence in $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ implies uniform convergence on compact sets and hence, by Reshetnyak's theorem, that the limit mapping f satisfies $K_O(x, f) \leq K$ instead of the pointwise bound given in (1.6).

Remark 1.7. The hypotheses of Theorem 1.4 imply a stronger conclusion than (1.6), namely the existence of a subsequence $\{f_{\nu_k}\}$ such that

$$(1.8) \quad K_O(x, f) \leq \text{b}^* \lim_{k \rightarrow \infty} K_O(x, f_{\nu_k})$$

in Ω .

The limit in (1.8) is to be understood in the sense of *biting convergence* defined in Section 2; see [1], [3] and [6]. The basic ingredient of our proof is the higher integrability of nonnegative Jacobians. For a discussion of this property for mappings with bounded distortion see [5], [7], [8], [11] and [16].

The outer dilatation function $K_O(x, f)$ has a simple geometric interpretation. If $f: \Omega \rightarrow \mathbf{R}^n$ has a differential $Df(x) \neq 0$, then $Df(x)$ maps the unit sphere onto an ellipsoid E and

$$(1.9) \quad K_O(x, f) = \frac{\text{vol}(B_O)}{\text{vol}(E)},$$

where B_O is the smallest ball circumscribed about E . In the same way, we may define the *inner dilatation* of f at x by

$$(1.10) \quad K_I(x, f) = \frac{\text{vol}(E)}{\text{vol}(B_I)},$$

where B_I is the largest ball inscribed in E . We set $K_I(x, f) = 1$ at degenerate points where $Df(x) = 0$ and we call

$$(1.11) \quad K(x, f) = \max\{K_O(x, f), K_I(x, f)\}$$

the *maximal dilatation*,

$$(1.12) \quad K_M(x, f) = \frac{1}{2}(K_O(x, f) + K_I(x, f))$$

the *mean dilatation* and

$$(1.13) \quad H(x, f) = (K_O(x, f) K_I(x, f))^{1/n}$$

the *linear dilatation* for f at x . The linear dilatation has the following dimension free representation

$$(1.14) \quad H(x, f) = \frac{\max\{|Df(x)\xi| : \xi \in S^{n-1}\}}{\min\{|Df(x)\xi| : \xi \in S^{n-1}\}}$$

at points where $Df(x) \neq 0$.

All of these dilatation functions coincide when $n = 2$; this is not the case when $n > 2$. However, the functions K_I , K_M and K have the same lower semicontinuity property as K_O when $n > 2$.

Theorem 1.15. *Theorem 1.4 and Remark 1.7 remain valid with $K_I(x, f)$, $K_M(x, f)$ and $K(x, f)$ in place of $K_O(x, f)$.*

This is not true of the geometrically appealing linear dilatation $H(x, f)$ when $n > 2$. Indeed a striking example in [10] exhibits for each $K > 1$ a sequence of mappings $f_\nu \in W_{\text{loc}}^{1,n}(\mathbf{R}^n, \mathbf{R}^n)$ such that

1. $H(x, f_\nu) \equiv K$,
2. f_ν converges uniformly to a linear map $f: \mathbf{R}^n \rightarrow \mathbf{R}^n$,
3. $H(x, f) \equiv K' > K$ where K' is a constant.

In light of this anomaly it is desirable to see what one can say about the linear dilatation of the limit f of a sequence of mappings. The following analogue of Theorems 1.4 and 1.15 answers a question raised at the Saariselkä Conference in June 1997. See also Section 14 in [17].

Theorem 1.16. *Suppose that $f_\nu: \Omega \rightarrow \mathbf{R}^n$ is a sequence of mappings of finite distortion which converges weakly in $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ to f and suppose that*

$$(1.17) \quad H(x, f_\nu) \leq M(x) < \infty \quad \text{for } \nu = 1, 2, \dots$$

a.e. in Ω . Then f has finite distortion and

$$(1.18) \quad H(x, f) \leq \frac{1}{2}(M(x) + M(x)^{n-1})^{2/n} \leq M(x)^{2-(2/n)}$$

a.e. in Ω .

2. Biting convergence

We shall make use of some ideas of Brooks and Chacon [6], in particular, the notion of *biting convergence* or weak convergence in measure.

Suppose that h and h_ν , $\nu = 1, 2, \dots$, are Lebesgue measurable functions on $E \subset \mathbf{R}^n$ with values in a finite dimensional normed space $(V, \|\cdot\|)$. In our applications we shall assume that $V = \mathbf{R}$ or $V = \mathbf{R}^{n \times n}$. We say that h_ν converges to h in the *biting* sense in E if there exist an increasing sequence of measurable subsets E_k of E with

$$\bigcup_k E_k = E$$

such that for each k , the functions h and h_ν are in $L^1(E_k, V)$ for all ν and

$$(2.1) \quad \lim_{\nu \rightarrow \infty} \int_{E_k} \phi h_\nu dx = \int_{E_k} \phi h dx$$

whenever $\phi \in L^\infty(E_k)$. In other words, the sequence h_ν converges weakly to h outside arbitrarily small *bites* from E , that is outside $E \setminus E_k$ for $k = 1, 2, \dots$. We shall call h the *biting* limit of the sequence h_ν and write

$$(2.2) \quad h_\nu \xrightarrow{b} h \quad \text{or} \quad h = \text{b}^* \lim_{\nu \rightarrow \infty} h_\nu.$$

It is immaterial which increasing sequence of subsets E_k of E we choose to define h as long as the weak limits on these sets exist; different bites yield the same limit. We leave it to the reader to verify the following two simple properties of biting convergence.

Lemma 2.3. *If $h_\nu \xrightarrow{b} h$ in E and if λ is finite and measurable in E , then $\lambda h_\nu \xrightarrow{b} \lambda h$ in E .*

Lemma 2.4. *If h_ν are measurable functions in E , $\nu = 1, 2, \dots$, and if*

$$\sup_\nu \|h_\nu(x)\| < \infty$$

a.e. in E , then h_ν contains a subsequence which converges in the biting sense in E .

We shall require the following lemma.

Lemma 2.5. *If A_ν converges weakly to A in $L^p_{\text{loc}}(E, \mathbf{R}^{n \times n})$ where $1 \leq p < \infty$, then there is a subsequence $\{\nu_k\}$ such that*

$$(2.6) \quad |A|^s \leq \text{b}^* \lim_{k \rightarrow \infty} |A_{\nu_k}|^s$$

for $1 \leq s \leq p$.

Proof. Choose measurable unit vectors $\xi = \xi(x)$ and $\zeta = \zeta(x)$ such that

$$|A(x)| = \langle A(x)\xi(x), \zeta(x) \rangle \quad \text{whence} \quad |A_\nu(x)| \geq \langle A_\nu(x)\xi(x), \zeta(x) \rangle$$

in E . Since t^s is convex in $0 < t < \infty$,

$$(2.7) \quad |A_\nu|^s - |A|^s \geq s|A|^{s-1}(|A_\nu| - |A|) \geq s|A|^{s-1}(\langle A_\nu\xi, \zeta \rangle - \langle A\xi, \zeta \rangle)$$

in E , the right hand side of (2.7) converges to 0 in the biting sense as $\nu \rightarrow \infty$ by Lemma 2.3 and we obtain (2.6) for some subsequence $\{\nu_k\}$ by Lemma 2.4. \square

3. Weak continuity of minors

Suppose that $\{f_\nu\}$ is a sequence of orientation preserving mappings

$$(3.1) \quad f_\nu = (f_\nu^1, \dots, f_\nu^n): \Omega \rightarrow \mathbf{R}^n, \quad \nu = 1, 2, \dots,$$

which converge weakly in $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ to a mapping $f = (f^1, \dots, f^n)$. This simply means that for each $i, j = 1, 2, \dots, n$ we have

$$(3.2) \quad \lim_{\nu \rightarrow \infty} \int_{\Omega} \phi \frac{\partial f_\nu^i}{\partial x_j} dx = \int_{\Omega} \phi \frac{\partial f^i}{\partial x_j} dx$$

for each ϕ in $L_0^{n/(n-1)}(\Omega)$, the space of test functions in $L^{n/(n-1)}$ with compact support in Ω .

A similar conclusion can be drawn for arbitrary minors of the differential matrix Df . Given l -tuples $1 \leq i_1 < \dots < i_l \leq n$ and $1 \leq j_1 < \dots < j_l \leq n$ we let

$$\frac{\partial(f^{i_1}, \dots, f^{i_l})}{\partial(x_{j_1}, \dots, x_{j_l})}$$

denote the corresponding $l \times l$ minor of Df . We then have the following counterpart for (3.2).

Lemma 3.3 (Weak continuity). *The above hypotheses imply that*

$$(3.4) \quad \lim_{\nu \rightarrow \infty} \int_{\Omega} \phi \frac{\partial(f_\nu^{i_1}, \dots, f_\nu^{i_l})}{\partial(x_{j_1}, \dots, x_{j_l})} dx = \int_{\Omega} \phi \frac{\partial(f^{i_1}, \dots, f^{i_l})}{\partial(x_{j_1}, \dots, x_{j_l})} dx$$

for each ϕ in $L_0^{n/(n-l)}(\Omega)$ and corresponding $l \times l$ minors of Df_ν and Df , $l = 1, 2, \dots, n$.

Proof. The convergence of the minors in the case where ϕ is in $C_0^\infty(\Omega)$ follows from integration by parts and the compactness of the Sobolev imbedding. The result in this case can be traced back at least as far as [2], [12] and [14]. The extension to arbitrary ϕ in $L_0^{n/(n-l)}(\Omega)$ with $1 \leq l < n$ poses no problem because $C_0^\infty(\Omega)$ is dense in $L_0^{n/(n-l)}(\Omega)$. It is the case where $l = n$ and ϕ is in $L_0^\infty(\Omega)$ that requires our mappings f_ν to be orientation preserving; for this see Corollary 1.2 in [13]. \square

The case where the mappings f_ν are K -quasiregular can be handled due to the higher degree of integrability of the Jacobians [5] and [8]. For yet another approach see the biting theorem for Jacobians, Corollary 2.3 in [4] and Corollary 2.2 in [19].

Corollary 3.5 (Biting convergence). *The above hypotheses imply that*

$$(3.6) \quad \mathfrak{b}^* \lim_{\nu \rightarrow \infty} \frac{\partial(f_\nu^{i_1}, \dots, f_\nu^{i_l})}{\partial(x_{j_1}, \dots, x_{j_l})} = \frac{\partial(f^{i_1}, \dots, f^{i_l})}{\partial(x_{j_1}, \dots, x_{j_l})}$$

for corresponding $l \times l$ minors of Df_ν and Df , $l = 1, 2, \dots, n$.

4. Dilatation functions

We introduce as in Section 1 the following quantities for a matrix A in $\mathbf{R}_+^{n \times n}$:

$$(4.1) \quad \begin{aligned} \text{Outer dilatation} & \quad K_O(A) = |A|^n / \det(A), \\ \text{Inner dilatation} & \quad K_I(A) = K_O(A^{-1}), \\ \text{Mean dilatation} & \quad K_M(A) = \frac{1}{2}(K_O(A) + K_I(A)), \\ \text{Maximal dilatation} & \quad K(A) = \max\{K_O(A), K_I(A)\}, \\ \text{Linear dilatation} & \quad H(A) = (K_O(A) K_I(A))^{1/n}. \end{aligned}$$

By Cramer’s rule, we can express $K_I(A)$ in terms of the minors of order $(n - 1)$ and the determinant of A as follows:

$$(4.2) \quad K_I(A) = \frac{|A^\#|^n}{\det(A)^{n-1}}.$$

Here $A^\#$ is the matrix in $\mathbf{R}^{n \times n}$ whose entries are co-factors of A ,

$$A_{jk}^\# = (-1)^{j+k} \det(M_{jk}),$$

where M_{jk} is a submatrix of A obtained by deleting the j th row and k th column.

The above definitions and an elementary analysis of the eigenvalues of AA^T yield the following estimates

$$(4.3) \quad K_O K_I = H^n, \quad K_O \leq H^{n-1} \leq K_I^{n-1}, \quad K_I \leq H^{n-1} \leq K_O^{n-1}.$$

From this and the arithmetic-geometric mean inequality we obtain the following estimates for the linear dilatation H :

$$(4.4) \quad H^{n/2} \leq \frac{1}{2}(K_O + K_I) = K_M = \frac{1}{2}\left(K_O + \frac{H^n}{K_O}\right) \leq \frac{1}{2}(H + H^{n-1}).$$

Equality holds in the first inequality only when $K_O = K_I$ and in the second inequality only when $K_O = K_I^{n-1}$ or $K_I = K_O^{n-1}$.

5. Polyconvexity

We show here that the dilatation functions K_O , K_I , K_M and K are polyconvex on the set $\mathbf{R}_+^{n \times n}$, that is, that they can be expressed as convex functions of minors of the matrix $A \in \mathbf{R}_+^{n \times n}$.

Lemma 5.1. *The function*

$$(5.2) \quad F(x, y) = F_{p,q}(x, y) = \frac{x^p}{y^q}$$

is convex on $\mathbf{R}_+ \times \mathbf{R}_+$ whenever $p \geq q + 1 \geq 1$.

Proof. We must show that

$$(5.3) \quad F(x, y) - F(a, b) \geq A(x - a) + B(y - b)$$

for all $x, y, a, b \in \mathbf{R}_+$ where

$$A = \frac{\partial F}{\partial x}(a, b) = \frac{pa^{p-1}}{b^q}, \quad B = \frac{\partial F}{\partial y}(a, b) = -\frac{qa^p}{b^{q+1}}.$$

Inequality (5.3) is an immediate consequence of the arithmetic-geometric mean inequality

$$(5.4) \quad u_1^{r_1} u_2^{r_2} u_3^{r_3} \leq r_1 u_1 + r_2 u_2 + r_3 u_3$$

which holds whenever r_j, u_j are nonnegative for $j = 1, 2, 3$ with $r_1 + r_2 + r_3 = 1$. See, for example, Section 2.5 in [9] In particular if we set

$$r_1 = \frac{1}{p}, \quad r_2 = \frac{q}{p}, \quad r_3 = \frac{p - q - 1}{p}, \quad u_1 = \frac{x^p}{y^q}, \quad u_2 = \frac{a^p y}{b^{q+1}}, \quad u_3 = \frac{a^p}{b^q},$$

then we obtain

$$\frac{xa^{p-1}}{b^q} = u_1^{r_1} u_2^{r_2} u_3^{r_3} \leq r_1 u_1 + r_2 u_2 + r_3 u_3 = \frac{1}{p} \frac{x^p}{y^q} + \frac{q}{p} \frac{a^p y}{b^{q+1}} + \frac{p - q - 1}{p} \frac{a^p}{b^q}$$

whence

$$(5.5) \quad \frac{x^p}{y^q} - \frac{a^p}{b^q} \geq \frac{pa^{p-1}}{b^q}(x - a) - \frac{qa^p}{b^{q+1}}(y - b)$$

which is (5.3). \square

We see from (4.1) and (4.2) that

$$(5.6) \quad \begin{aligned} K_O(A) &= F(|A|, \det(A)) && \text{with } p = n \text{ and } q = 1, \\ K_I(A) &= F(|A^\#|, \det(A)) && \text{with } p = n \text{ and } q = n - 1. \end{aligned}$$

We observe next that the function $F(x, y)$ is increasing in the variable x and that x is a convex function of the minors of A , $x = |A|$ or $x = |A^\#|$, respectively, in (5.6). This implies that both K_O and K_I are polyconvex and hence so are the mean and maximal dilatations K_M and K . On the other hand, the linear dilatation H fails to be even rank-one convex [10].

We conclude by recording from (5.5) and (5.6) what polyconvexity means for the outer and inner dilatations:

$$(5.7) \quad K_O(X) - K_O(A) \geq \frac{n|A|^{n-1}}{\det(A)} (|X| - |A|) - \frac{|A|^n}{\det(A)^2} (\det(X) - \det(A))$$

and

$$(5.8) \quad K_I(X) - K_I(A) \geq \frac{n|A^\#|^{n-1}}{\det(A)^{n-1}} (|X^\#| - |A^\#|) - \frac{(n-1)|A^\#|^n}{\det(A)^n} (\det(X) - \det(A)).$$

6. Lower semicontinuity

For simplicity of notation we will use the symbol $\mathcal{K}(f) = \mathcal{K}(x, f)$ to denote any one of the dilatations $K_O(x, f)$, $K_I(x, f)$, $K_M(x, f)$ or $K(x, f)$. Then

$$\mathcal{K}(x, f) = \mathcal{K}(Df(x))$$

whenever $J(x, f) > 0$, where $\mathcal{K}(Df)$ denotes the corresponding dilatation function of matrices defined in (4.1).

Theorem 6.1. *Suppose that $f_\nu: \Omega \rightarrow \mathbf{R}^n$ is a sequence of mappings of finite distortion which converge weakly in $W_{\text{loc}}^{1,n}(\Omega, \mathbf{R}^n)$ to f and suppose that*

$$(6.2) \quad \mathcal{K}(x, f_\nu) \leq M(x) < \infty \quad \text{for } \nu = 1, 2, \dots$$

a.e. in Ω . Then f has finite distortion and there exists a subsequence $\{f_{\nu_k}\}$ such that

$$(6.3) \quad \mathcal{K}(x, f) \leq \text{b}^* \lim_{k \rightarrow \infty} \mathcal{K}(x, f_{\nu_k})$$

in Ω . In particular

$$(6.4) \quad \mathcal{K}(x, f) \leq M(x)$$

a.e. in Ω .

Proof. We consider first the case where $\mathcal{K}(f)$ is the outer dilatation $K_O(f)$. Then (6.2) implies that

$$|Df_\nu(x)|^n \leq M(x)J(x, f_\nu)$$

a.e. in Ω while

$$(6.5) \quad \text{b}^*\lim_{\nu \rightarrow \infty} \det(Df_\nu) = \det(Df), \quad \text{b}^*\lim_{\nu \rightarrow \infty} M \det(Df_\nu) = M \det(Df)$$

by Corollary 3.5 and Lemma 2.3. Next by Lemma 2.5 we can choose a subsequence $\{f_{\nu_k}\}$ such that

$$(6.6) \quad |Df|^n \leq \text{b}^*\lim_{k \rightarrow \infty} |Df_{\nu_k}|^n \leq \text{b}^*\lim_{k \rightarrow \infty} M \det(Df_{\nu_k}) = M \det(Df)$$

and

$$(6.7) \quad |Df(x)|^n \leq M(x)J(x, f)$$

a.e. in Ω . Thus f has finite distortion and (6.4) holds a.e. in Ω .

Finally in order to establish (6.3) we apply (5.7) to the matrices $X = Df_\nu$ and $A = Df$ to obtain

$$(6.8) \quad K_O(f_\nu) - K_O(f) \geq M_1(|Df_\nu| - |Df|) - M_2(\det(Df_\nu) - \det(Df)),$$

where

$$(6.9) \quad M_1 = \frac{n|Df|^{n-1}}{\det(Df)}, \quad M_2 = \frac{|Df|^n}{\det(Df)^2},$$

a.e. in the set $E \subset \Omega$ where $\det(Df) \neq 0$. Next if we restrict our attention to the set E , then by Lemma 2.5, Corollary 3.5 and Lemma 2.4 we can choose a subsequence $\{f_{\nu_k}\}$ such that

$$(6.10) \quad |Df| \leq \text{b}^*\lim_{k \rightarrow \infty} |Df_{\nu_k}|, \quad \det(Df) = \text{b}^*\lim_{k \rightarrow \infty} \det(Df_{\nu_k})$$

and such that $K_O(f_{\nu_k})$ converges in the biting sense. Then we obtain

$$(6.11) \quad K_O(f) \leq \text{b}^*\lim_{k \rightarrow \infty} K_O(f_{\nu_k})$$

in E from (6.8), (6.9) and (6.10). By our convention

$$(6.12) \quad K_O(f) = 1 \leq \text{b}^*\lim_{k \rightarrow \infty} K_O(f_{\nu_k})$$

a.e. in $\Omega \setminus E$, completing the proof of Theorem 6.1 for the case where $\mathcal{K} = K_O$.

Suppose next that $\mathcal{K} = K_I$. Then (4.3) yields the rough estimate

$$(6.13) \quad K_O(x, f_\nu) \leq K_I^{n-1}(x, f_\nu) \leq M(x)^{n-1}$$

and f has finite distortion by what was proved above. Next (4.2) and (5.8) applied to the matrices $X = Df_\nu$ and $A = Df$ yield

$$(6.14) \quad K_I(f_\nu) - K_I(f) \geq M_3(|(Df_\nu)^\#| - |(Df)^\#|) - M_4(\det(Df_\nu) - \det(Df)),$$

where

$$(6.15) \quad M_3 = \frac{n|(Df)^\#|^{n-1}}{\det(Df)^{n-1}}, \quad M_4 = \frac{(n-1)|(Df)^\#|^n}{\det(Df)^n},$$

a.e. in E . Then $(Df_\nu)^\#$ converges weakly to $(Df)^\#$ in $L_{\text{loc}}^{n/(n-1)}(\Omega, \mathbf{R}^{n \times n})$, there is a subsequence $\{f_{\nu_k}\}$ such that the $K_I(f_{\nu_k})$ converges in the biting sense and

$$(6.16) \quad |(Df)^\#| \leq \text{b}^* \lim_{k \rightarrow \infty} |(Df_{\nu_k})^\#|, \quad \det(Df) = \text{b}^* \lim_{k \rightarrow \infty} \det(Df_{\nu_k})$$

again by Lemma 2.5 and Corollary 3.5. Then

$$(6.17) \quad K_I(f) \leq \text{b}^* \lim_{k \rightarrow \infty} K_I(f_{\nu_k})$$

in E as above while

$$(6.18) \quad K_I(f) = 1 \leq \text{b}^* \liminf_{k \rightarrow \infty} K_I(f_{\nu_k})$$

in $\Omega \setminus E$ since f has finite distortion. This completes the proof of Theorem 6.1 for the case where $\mathcal{K} = K_I$.

If $\mathcal{K} = K_M$, then

$$\max\{K_O(x, f_\nu), K_I(x, f_\nu)\} \leq 2K_M(x, f_\nu) \leq 2M(x)$$

and f has finite distortion. Next there exists a subsequence $\{f_{\nu_k}\}$ such that $K_O(f_{\nu_k})$, $K_I(f_{\nu_k})$ and $K_M(f_{\nu_k})$ converge in the biting sense, and we obtain

$$\begin{aligned} 2K_M(f) &= K_O(f) + K_I(f) \\ &\leq \text{b}^* \lim_{k \rightarrow \infty} K_O(f_{\nu_k}) + \text{b}^* \lim_{k \rightarrow \infty} K_I(f_{\nu_k}) = 2 \text{b}^* \lim_{k \rightarrow \infty} K_M(f_{\nu_k}) \end{aligned}$$

from (6.3) with $\mathcal{K} = K_O$ and $\mathcal{K} = K_I$.

Finally if $\mathcal{H} = K$, then

$$\max\{K_O(x, f_\nu), K_I(x, f_\nu)\} \leq K(x, f_\nu) \leq M(x)$$

and we can choose a subsequence $\{f_{\nu_k}\}$ such that

$$\begin{aligned} K_O(f) &\leq \text{b}^* \lim_{k \rightarrow \infty} K_O(f_{\nu_k}) \leq \text{b}^* \lim_{k \rightarrow \infty} K(f_{\nu_k}), \\ K_I(f) &\leq \text{b}^* \lim_{k \rightarrow \infty} K_I(f_{\nu_k}) \leq \text{b}^* \lim_{k \rightarrow \infty} K(f_{\nu_k}). \end{aligned}$$

Hence

$$(6.19) \quad K(f) \leq \text{b}^* \lim_{k \rightarrow \infty} K(f_{\nu_k})$$

completing the proof of Theorem 6.1. \square

7. Conclusions

Theorem 1.4, Remark 1.7 and Theorem 1.15 of Section 1 follow from Theorem 6.1. For the proof of Theorem 1.16, (1.17) and (4.4) imply that

$$K_M(x, f_\nu) \leq \frac{1}{2}(H(x, f_\nu) + H(x, f_\nu)^{n-1}) \leq \frac{1}{2}(M(x) + M(x)^{n-1}) \text{ for } \nu = 1, 2, \dots$$

a.e. in Ω . Hence f has finite distortion and

$$H(x, f) \leq K_M(x, f)^{2/n} \leq \left(\frac{1}{2}(M(x) + M(x)^{n-1})\right)^{2/n} \leq M(x)^{2-(2/n)}$$

a.e. in Ω by (4.4) and Theorem 1.15. \square

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